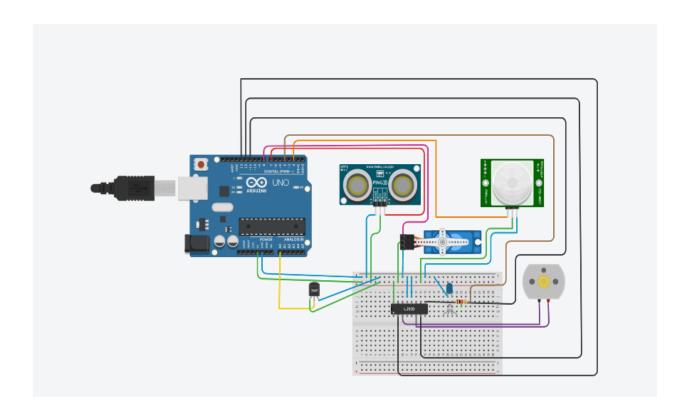
ASSIGNMENT 1

Statement:

Make a Smart Home in Tinkercad using 2+ sensors, LEDS, BUZZER, in single code and circuit.

Solution:



Code:

```
#include<Servo.h>
const int pingPin = 7;
int servoPin = 8;
Servo servo1;
void setup() {
 Serial.begin(9600);
 servo1.attach(servoPin);
 pinMode(2,INPUT);
 pinMode(4,OUTPUT);
 pinMode(11,OUTPUT);
 pinMode(12,OUTPUT);
 pinMode(13,OUTPUT);
 pinMode(A0,INPUT);
 digitalWrite(2,LOW);
 digitalWrite(11,HIGH);
}
void loop() {
 long duration, inches, cm;
 pinMode(pingPin, OUTPUT);
 digitalWrite(pingPin, LOW);
 delayMicroseconds(2);
 digitalWrite(pingPin, HIGH);
 delayMicroseconds(5);
 digitalWrite(pingPin, LOW);
 pinMode(pingPin, INPUT);
 duration = pulseIn(pingPin, HIGH);
 inches = microsecondsToInches(duration);
```

```
cm = microsecondsToCentimeters(duration);
servo1.write(0);
if(cm < 40)
{
 servo1.write(90);
 delay(2000);
}
else
{
 servo1.write(0);
}
// PIR with LED starts
int pir = digitalRead(2);
if(pir == HIGH)
 digitalWrite(4,HIGH);
 delay(1000);
else if(pir == LOW)
 digitalWrite(4,LOW);
}
//temp with fan
float value=analogRead(A0);
float temperature=value*0.48;
Serial.println("temperature");
```

```
Serial.println(temperature);
if(temperature > 20)
 digitalWrite(12,HIGH);
 digitalWrite(13,LOW);
 }
 else
 {
 digitalWrite(12,LOW);
 digitalWrite(13,LOW);
 }
}
long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
 return microseconds / 29 / 2;
}
```

OUTPUT:

