## **Assignment-1**

Assignment Date	03 November 2022
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Student Roll Number	130719205011
Maximum Marks	2 Marks

## **STATEMENT:**

Build a smart home in Thinkercad with 2 sensors, an Led, buzzer and submit it.

## **PROGRAM:**

```
#include<Servo.h>
const int pingPin = 2;
int servoPin = 3;
char degree = 176;
Servo servo1;
void setup() {
 Serial.begin(9600);
 servo1.attach(servoPin);
 pinMode(4,INPUT);
 pinMode(5,OUTPUT);
 pinMode(11,OUTPUT);
 pinMode(12,OUTPUT);
 pinMode(13,OUTPUT);
 pinMode(A0,INPUT);
 digitalWrite(4,LOW);
 digitalWrite(11,HIGH);
}
void loop() {
```

```
long duration, inches, cm;
pinMode(pingPin, OUTPUT);
digitalWrite(pingPin, LOW);
delayMicroseconds(2);
digitalWrite(pingPin, HIGH);
delayMicroseconds(5);
digitalWrite(pingPin, LOW);
pinMode(pingPin, INPUT);
duration = pulseIn(pingPin, HIGH);
inches = microsecondsToInches(duration);
cm = microsecondsToCentimeters(duration);
servo1.write(0);
if(cm > 100)
 servo1.write(90);
 delay(10);
}
else
 servo1.write(0);
}
int pir = digitalRead(4);
if(pir == HIGH)
```

```
digitalWrite(5,HIGH);
 delay(1000);
else if(pir == LOW)
 digitalWrite(5,LOW);
}
float tmp = analogRead(A0);
float voltage = (tmp * 5.0)/1024;
float milliVolt = voltage * 1000;
float tmpCel = (milliVolt-500)/10;
if(tmpCel > 20){
 digitalWrite(12, HIGH);
      digitalWrite(13, LOW);
 Serial.print("Temperature: ");
 Serial.print(tmpCel);
 Serial.println(degree);
 Serial.println("Fan is ON now");
 delay(2000);
}
else{
 digitalWrite(12, LOW);
      digitalWrite(13, LOW);
 Serial.print("Temperature: ");
 Serial.print(tmpCel);
 Serial.println(degree);
 Serial.println("Fan is Off now");
 delay(2000);
```

```
long microsecondsToInches(long microseconds) {
  return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
  return microseconds / 29 / 2;
}
```

## **CIRCUIT:**

