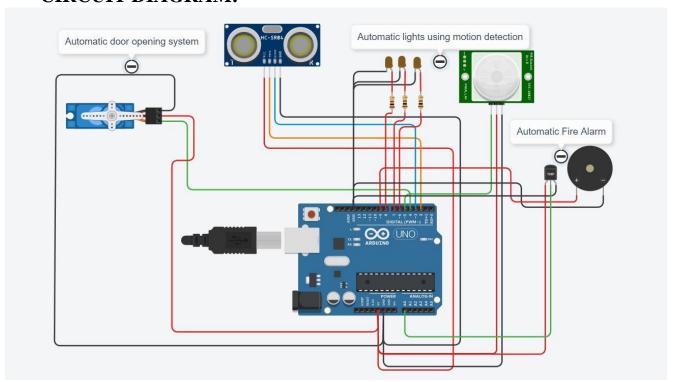
CIRCUIT DIAGRAM:



CODE:

```
#include <Servo.h>
Servo s; int trig=2;
int ec=3; int
PIR=5; int led1=6;
int led2=7; int
led3=8; int buzz=9;
void setup()
{
```

```
Serial.begin(9600);
pinMode(trig,OUTPUT);
pinMode(ec,INPUT);
pinMode(PIR,INPUT);
pinMode(led1,OUTPUT);
pinMode(led2,OUTPUT);
pinMode(led3,OUTPUT);
pinMode(buzz,OUTPUT);
 s.attach(4);
 s.write(0);
digitalWrite(led1,LOW);
digitalWrite(led2,LOW);
digitalWrite(led3,LOW);
} void autodoor() {
digitalWrite(trig,LOW);
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW); float
duration = pulseIn(ec,HIGH); float
dist = (duration*0.0343)/2;
//Serial.println(dist); if(dist<100)
   open(); } } void open() { for
(int i=0;i<=90;i++)
```

```
s.write(i);
delay(100);
  }
 delay(5000); for
(int j=90;j>=0;j--)
  {
   s.write(j);
delay(100);
  } } void
autolight()
 int p = digitalRead(5);
if(p)
  digitalWrite(led1,HIGH);
digitalWrite(led2,HIGH);
digitalWrite(led3,HIGH);
delay(5000);
digitalWrite(led1,LOW);
digitalWrite(led2,LOW);
digitalWrite(led3,LOW);
```

```
}
void firealarm() {  double a
= analogRead(A0);
 double t = (((a/1024)*5)-0.5)*100;
Serial.println(t); if(t>60)
 {
  tone(buzz,20000);
delay(10000); noTone(9);
 } } void
loop()
autodoor();
delay(1000);
autolight();
delay(1000);
firealarm();
delay(1000);
}
```

