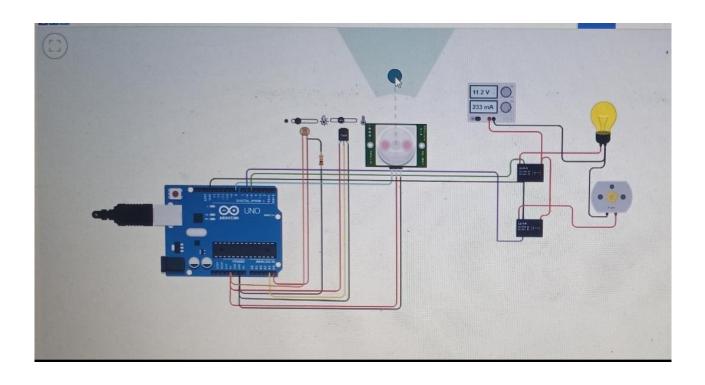
```
float x,y,z,temp;
void setup()
  pinMode(8, INPUT);
  pinMode(5, OUTPUT);
  pinMode(6, OUTPUT);
  pinMode (A5, INPUT);
  pinMode(A4, INPUT);
 Serial.begin(9600);
void loop()
  x = digitalRead(8);
   y= analogRead(A5);
   z= analogRead(A4);
   Serial.println(x);
   Serial.println(y);
   Serial.println(z);
  temp = (double)z / 1024;
  temp = temp * 5;
  temp = temp - 0.5;
   temp = temp * 100;
   if ((x>0))
     if ((y<550) \&\& (temp>30))
       digitalWrite(5, HIGH);
       digitalWrite(6, HIGH);
     else if((y < 550) &&(temp<30))
       digitalWrite(5, HIGH);
       digitalWrite(6, LOW);
     else if((y>550) && (temp>30))
       digitalWrite(5, LOW);
       digitalWrite(6, HIGH);
     else if((y>550) && (temp<30))
       digitalWrite(5, LOW);
       digitalWrite(6, LOW);
     }
   }
  else
     digitalWrite(5, LOW);
     digitalWrite(6, LOW);
 }
```



TINKERCAD: <a href="https://www.tinkercad.com/things/26S3ILYi6g5">https://www.tinkercad.com/things/26S3ILYi6g5</a>

