Assignment -4

Assignment Date	25 October 2022
Student Name	Akilaa.B
Student Roll Number	813819106008
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

```
// Pins
const int TRIG_PIN = 7;
const int ECHO_PIN =
8;
// Anything over 400 cm (23200 us pulse) is "out of
range" const unsigned int MAX_DIST = 23200;
void setup() {
 // The Trigger pin will tell the sensor to range find
 pinMode(TRIG_PIN, OUTPUT);
 digitalWrite(TRIG_PIN, LOW);
 //Set Echo pin as input to measure the duration of
 //pulses coming back from the distance sensor
 pinMode(ECHO_PIN, INPUT);
 // We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
}
void loop() {
 unsigned long t1;
 unsigned long t2;
 unsigned long pulse_width;
 float cm;
 float inches;
 // Hold the trigger pin high for at least 10 us
```

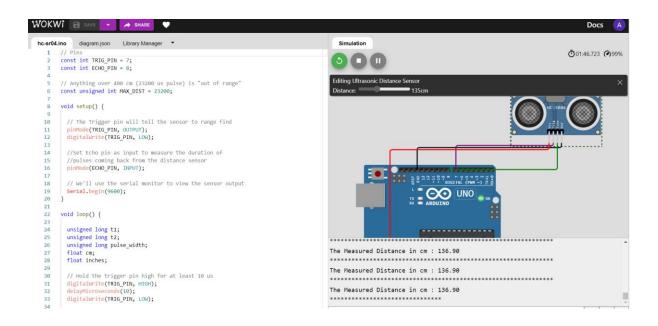
```
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead(ECHO_PIN) == 0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70
min t1 = micros();
while (digitalRead(ECHO_PIN) ==
1); t2 = micros();
pulse\_width = t2 - t1;
// Calculate distance in centimeters and inches. The constants
// are found in the datasheet, and calculated from the assumed speed
//of sound in air at sea level (~340
m/s). cm = pulse_width / 58.0;
inches = pulse_width / 148.0;
// Print out results
if (pulse_width > MAX_DIST) {
 Serial.println("Out of range");
} else {
 Serial.println("******************************);
 Serial.print("The Measured Distance in cm : ");
 Serial.println(cm);
 if(cm<100){
  // while(true){
  Serial.println("Alert!!");
  //}
 }
 Serial.print("*******************************);
// Wait at least 1000ms before next measurement
delay(1000);
```

WOKWI SIMULATION:

Case 1:Distance less than 100 cm

```
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                                                                                                                                              TX ARDUINO UNO
          void loop() {
           unsigned long t1;
unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;
                                                                                                                             red Distance in cm : 97.38
                                                                                                               Alert!!
                                                                                                               ******************
                                                                                                               The Measured Distance in cm : 97.31
            // Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds[10);
digitalWrite(TRIG_PIN, LOW);
                                                                                                               Alert!!
                                                                                                               The Measured Distance in cm : 97.38
                                                                                                                                                                                                               <u>⊬</u> II 🛍
           // Wait for pulse on echo pin
```

Case 2:Distance greater than 100 cms



WOKWI LINK:

https://wokwi.com/projects/346775395589161554

IBM CLOUD:

