# **Assignment -4**

Assignment Date	25 October 2022
Student Name	Madhumitha.M
Student Roll Number	813819106060
Maximum Marks	2 Marks

# **Question-1:**

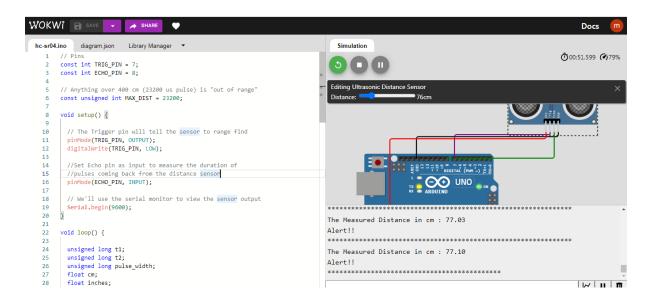
Write code and connections in wokwi for ultrasonic sensor. whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

```
//Pins
const int TRIG_PIN = 7;
constintECHO_PIN=8;
//Anythingover400cm(23200 uspulse)is"out of range"
const unsigned int MAX_DIST = 23200;
voidsetup(){
 //The Trigger pin will tell the sensor to range find
 pinMode(TRIG_PIN, OUTPUT);
 digitalWrite(TRIG_PIN,LOW);
 //Set Echo pin as input to measure the duration of
 //pulses coming back from the distance sensor
 pinMode(ECHO_PIN, INPUT);
 //We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
Void loop(){
 unsigned longt1;
 unsigned longt2;
 unsigned long pulse_width;
 float cm;
```

```
float inches;
//Hold the trigger pin high for at least10us
digitalWrite(TRIG_PIN,HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN,LOW);
//Wait for pulse on echo pin
while(digitalRead(ECHO_PIN)==0);
//Measure how long the echo pin was held high (pulsewidth)
//Note: the micros()counter will overflow after~70
\min t1 = \min(s);
while(digitalRead(ECHO_PIN)==1);
t2 = micros();
pulse_width=t2-t1;
//Calculate distance in centimeters and inches.
//The constants are found in the datasheet, and calculated from the assumed
// speed of sound in air at sea level (~340m/s).
cm = pulse\_width / 58.0;
inches=pulse_width/148.0;
//Print out results
if(pulse_width>MAX_DIST){
  Serial.println("Out of range");
 } else {
  Serial.println("*********************************):
 Serial.print("The Measured Distance in cm : ");
  Serial.println(cm);
  if(cm<100){
   // while(true){
   Serial.println("Alert!!");
   //}
  Serial.print("*****************************);
 }
//Wait atleast 1000ms before next measurement
delay(1000);
```

#### **WOKWI SIMULATION:**

### Case 1:Distance less than 100 cm



Case 2:Distance greater than 100 cms

```
WOKWI 🗈 SAVE
                                                                                                                                                                              Docs m
  hc-sr04.ino diagram.json Library Manager ▼
         // Pins
const int TRIG PIN = 7;
                                                                                                                                                                        Ō01:15.632 ⊘86%
          const int ECHO_PIN = 8;
                                                                                                Editing Ultrasonic Distance Sensor
         // Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;
           // The Trigger pin will tell the sensor to range find
pinMode(TRIG_PIN, OUTPUT);
digitalWrite(TRIG_PIN, LOW);
           //Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT);
                                                                                                                        TX ARDUINO UNO ON
            // We'll use the serial monitor to view the sensor output
    19
            Serial.begin(9600);
                                                                                              The Measured Distance in cm : 137.93
                                                                                              **********************
          void loop() {
                                                                                              The Measured Distance in cm : 137.93
            unsigned long t1;
            unsigned long t2;
unsigned long pulse_width;
                                                                                              The Measured Distance in cm : 137.93
                                                                                              *********
```

# **WOKWI LINK:**

https://wokwi.com/projects/346844033654456916

### **IBM CLOUD:**

