## Assignment -4

Assignment Date	25 October 2022
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Maximum Marks	2 Marks

## Question-1:

Write code and connections in wokwi for ultrasonic sensor. whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

```
//Pins
const int TRIG_PIN = 7;
constintECHO_PIN=8;
//Anythingover400cm(23200 uspulse)is"outofrange"
const unsigned int MAX_DIST = 23200;
voidsetup(){
 //TheTriggerpinwilltellthesensortorange find
 pinMode(TRIG_PIN, OUTPUT);
 digitalWrite(TRIG_PIN,LOW);
 //SetEchopinasinputtomeasuretheduration of
 //pulsescomingbackfromthedistancesensor
 pinMode(ECHO_PIN, INPUT);
 //We'llusetheserialmonitortoview thesensoroutput
 Serial.begin(9600);
}
voidloop(){
 unsignedlongt1;
 unsignedlongt2;
 unsignedlongpulse_width;
 float cm;
 floatinches;
 //Holdthetriggerpinhighforatleast10us
 digitalWrite(TRIG_PIN,HIGH);
```

```
delayMicroseconds(10);
digitalWrite(TRIG_PIN,LOW);
//Waitforpulseonechopin
while(digitalRead(ECHO_PIN)==0);
//Measurehowlongtheechopinwasheldhigh(pulsewidth)
//Note:the micros()counterwilloverflowafter~70min t1
= micros();
while(digitalRead(ECHO_PIN)==1);
t2 = micros();
pulse_width=t2-t1;
//Calculatedistanceincentimeters and inches. The constants
//arefoundinthedatasheet,andcalculatedfromtheassumedspeed
//ofsoundinairatsealevel(~340m/s). cm
= pulse_width / 58.0;
inches=pulse_width/148.0;
//Printoutresults
if(pulse_width>MAX_DIST){
 Serial.println("Out of range");
} else {
 erial.print("The Measured Distance in cm : ");
 Serial.println(cm);
 if(cm < 100){
  // while(true){
  Serial.println("Alert!!");
  //}
 }
 Serial.print("********************************);
//Waitatleast1000msbeforenextmeasurement
delay(1000);
```

## **WOKWI SIMULATION:**

## Case 1:Distance less than 100 cm

```
WOKWI 🕞 SAVE
 hc-sr04.ino
               diagram.json
                             Library Manager
                                                                                           Simulation
         // Pins
        const int TRIG_PIN = 7;
    2
        const int ECHO_PIN = 8;
    3
    4
                                                                                         Editing Ultrasonic Distance
    5
         // Anything over 400 cm (23200 us pulse) is "out of range"
                                                                                         Distance:
    6
        const unsigned int MAX_DIST = 23200;
    8
        void setup() {
    9
   10
           // The Trigger pin will tell the sensor to range find
           pinMode(TRIG_PIN, OUTPUT);
   11
   12
           digitalWrite(TRIG_PIN, LOW);
   13
           //Set Echo pin as input to measure the duration of
   14
   15
           //pulses coming back from the distance sensor
           pinMode(ECHO_PIN, INPUT);
   16
   17
           // We'll use the serial monitor to view the sensor output
    18
   19
           Serial.begin(9600);
   20
                                                                                        The Measured Distar
   21
                                                                                        Alert!!
   22
         void loop() {
   23
   24
           unsigned long t1;
                                                                                        The Measured Distar
           unsigned long t2;
   25
                                                                                        Alert!!
           unsigned long pulse_width;
   26
           float cm;
   27
           float inches;
   28
```

Case 2:Distance greater than 100 cms

```
WOKWi

→ SHARE

 hc-sr04.ino
                               Library Manager -
                                                                                                  Simulation
               diagram.json
    1
     2
            "version": 1,
            "author": "Uri Shaked",
     3
           "editor": "wokwi",
    4
     5
           "parts": [
              { "type": "wokwi-arduino-uno", "id": "uno", "top": 130.93, "left": 2.53,
    6
    7
                "type": "wokwi-hc-sr04",
    8
               "id": "ultrasonic",
    9
               "top": -4.1,
   10
               "left": 296.43,
   11
               "attrs": { "distance": "66" }
   12
   13
   14
           ],
   15
           "connections": [
            [ "uno:GND.1", "ultrasonic:GND", "black", [ "v-8", "*", "v8" ] ],
   16
             [ "uno:8", "ultrasonic:ECHO", "green", [] ],
[ "uno:7", "ultrasonic:TRIG", "purple", [ "*", "v4" ] ],
[ "uno:5V", "ultrasonic:VCC", "red", [ "v16", "h-96", "*", "v12" ] ]
   17
   18
   19
   20
                                                                                               The Measured Dista
         }
   21
                                                                                               *******
                                                                                               The Measured Dista
                                                                                               *******
                                                                                               The Measured Dista
                                                                                               *******
```

**WOKWI LINK:** 

https://wokwi.com/projects/346845722909344339

IBM CLOUD:

