## Assignment -4 Wowki & IBM Cloud

<b>Assignment Date</b>	04 October 2022
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Maximum Marks	2 Marks

## **Question-1:**

Write code and connections in wowki for the ultrasonic sensor.

Whenever the distance is less than 100cms sent "alert" to IBM cloud and display in device recent events.

#### **Code:**

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
String data3;
#define ORG "sf54ab"

#define DEVICE_TYPE "MyDeviceType"

#define DEVICE_ID "12345"

#define TOKEN "ZIA1zf@zL9s)Pumv11"

#define speed 0.034 #define led 14 char server[] = ORG

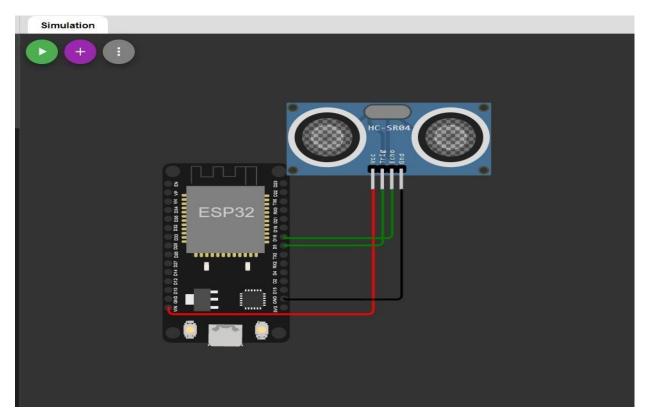
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/shreedharen/fmt/json";
```

```
char topic[] = "iot-2/cmd/led/fmt/String"; char authMethod[] =
"use-token-auth"; char token[] = TOKEN; char clientId[] = "d:"
ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5; const int echopin=18;
String command; String data=""; long
duration; float dist; void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect(); } void loop()
{ bool isNearby = dist <
100; digitalWrite(led,
isNearby); publishData();
delay(500); if (!client.loop())
{ mqttConnect();
} } void
wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
```

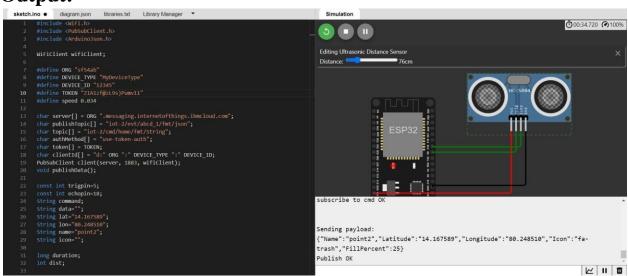
```
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
} void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to ");
Serial.println(server); while (!client.connect(clientId,
authMethod, token)) { Serial.print("."); delay(500); }
initManagedDevice();
Serial.println();
} } void
initManagedDevice() { if
(client.subscribe(topic)) {
// Serial.println(client.subscribe(topic)); Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
payload += dist; payload += "}";
```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload); if (client.publish(publishTopic,
(char*) payload.c_str())) {
Serial.println("Publish OK");
} }
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload); if(client.publish(publishTopic,
(char*) payload.c_str())) {
Serial.println("Publish OK");
}else
Serial.println("Publish FAILED");
}
```

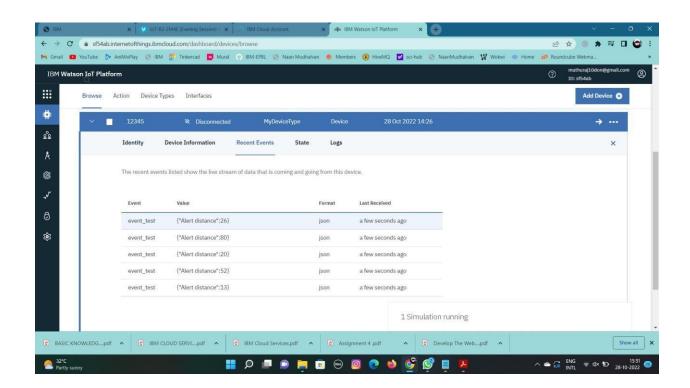
# **Connections:**



## **Output:**



**Output:(IBM Cloud)** 



Link: https://wokwi.com/projects/346587874175484499