A. Sandhiya Assignment -4

Question-1: Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

```
Solution:
#define ECHO_PIN 2
#define TRIG PIN 3
#define organization ="xkkc60"
#define deviceType=" Arduino"
#define deviceId ="4444"
#define authMethod ="use-token-auth"
#define authToken ="nMX@9nrIyogMe)!mjt"
void setup() {
 // put your setup code here, to run once:
 Serial.begin(9600);
 pinMode(TRIG_PIN,OUTPUT);
 pinMode(ECHO PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG PIN, LOW);
```

```
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
 // put your main code here, to run repeatedly:
 float distance = readDistanceCM();
 if(distance <= 100)
 {
  Serial.println("person detected ");
 }
 else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
 }
 delay(1000);
}
```

```
WOKWI ☐ SAVE → → SHARE ♥
                                                                                                                                                                                                                                                Docs 🔒
  sketch.ino diagram.json ● Library Manager ▼
    1 #define ECHO_PIN 2
    2 #define TRIG_PIN 3
    3 #define organization ="xKKc6o"
    4 #define deviceType=" Arduino"
    5 #define deviceId ="4444"
    6 #define authMethod ="use-token-auth"
7 #define authToken ="nMX@9nrIyogMe)!mjt"
   8
9 void setup() {

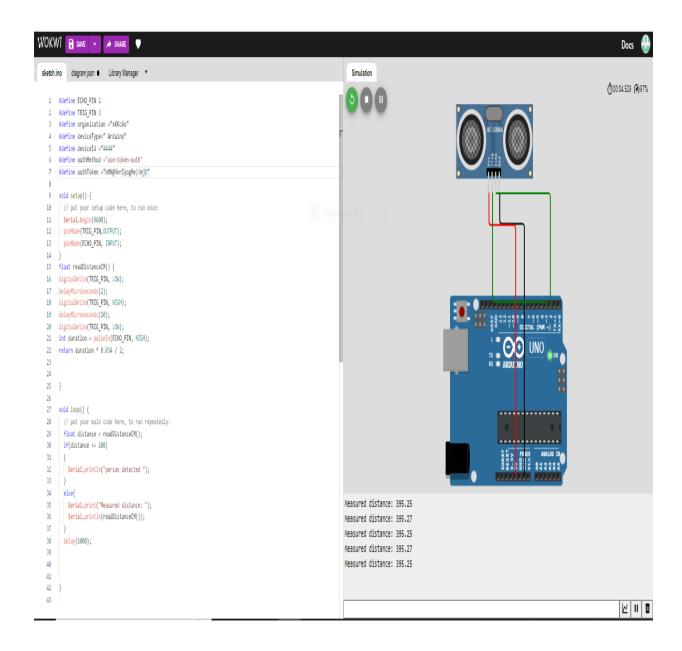
    Rectangular Snip

   15 float readDistanceCM() {
   16 digitalWrite(TRIG_PIN, LOW);
   17 delayMicroseconds(2);
                                                                                                                                                                          FERRIS IN
   18 digitalWrite(TRIG_PIN, HIGH);
   19 delayMicroseconds(10);
  20 digitalWrite(TRIG_PIN, LOW);
21 int duration = pulseIn(ECHO_PIN, HIGH);
22 return duration * 0.034 / 2;
                                                                                                                                                                                          TX OO
   25 }
   26
27 void loop() {
   28 // put your main code here, to run repeatedly:
   29  float distance = readDistanceCM();
    30 if(distance <= 100)
   32  | Serial.println("person detected ");
33  | }
   34 else{
  Serial.print("Measured distance. , Serial.println(readDistanceCM());

36 | Serial.println(readDistanceCM());

37 | }
          Serial.print("Measured distance: ");
  38 delay(1000);
39
   40
   41
                                                                                                                                                                                                                                                <u>⊬</u> II I
```

Output:



Wokwi Link: https://wokwi.com/projects/347054740456079955

Device Recent Events

