

```

import turtle
import time
a = turtle.getscreen()
a.title("TrafficLight ")
a.bgcolor("black")

write= turtle.Turtle()
write.color("White")
write.width(3)
write.hideturtle()
write.penup()
write.goto(-30, 60)
write.pendown()
write.fd(60)
write.rt(90)
write.fd(120)
write.rt(90)
write.fd(60)
write.rt(90)
write.fd(120)

red_light =turtle.Turtle()
red_light.shape("circle")
red_light.color("Black")
red_light.penup()
red_light.goto(0, 40)

yellow_light =turtle.Turtle()
yellow_light.shape("circle")
yellow_light.color("Black")
yellow_light.penup()
yellow_light.goto(0, 0)

green_light =turtle.Turtle()
green_light.shape("circle")
green_light.color("Black")
green_light.penup()
green_light.goto(0,-40)

while (1):
    green_light.color("Black")
    yellow_light.color("Black")
    red_light.color("red")
    print("Stop - Stop behind zebra cross..")
    print("Blink!!!")
    time.sleep(2)
    print("Blink!!!")

    red_light.color("Black")

```

```
yellow_light.color("yellow")
print("Move - You can go..")
print("Blink!!")
time.sleep(3)
print("Blink!!")
```

```
yellow_light.color("Black")
green_light.color("green")
print("Wait for Signal - Ready to go..")
print("Blink!!")
time.sleep(1)
print("Blink!!")
```

```
a.mainloop()
```

```
import RPi.GPIO as GPIO
import time
```

```
def on(pin,tim):
    GPIO.output(pin,1)
    time.sleep(tim)
```

```
def off(pin,tim):
    GPIO.output(pin,0)
    time.sleep(tim)
    return
```

```
GPIO.setmode(GPIO.BOARD)
```

```
GPIO.setup(10,GPIO.OUT)
GPIO.setup(12,GPIO.OUT)
GPIO.setup(13,GPIO.OUT)
```

```
for i in range(0,2):
    on(10,2)
    off(10,1)
    on(12,2)
    off(12,1)
    on(13,2)
    off(13,1)
```

```
print('Done')
GPIO.cleanup()
```