

```

#include <WiFi.h>                // library for wifi
#include <PubSubClient.h>        // library for MQTT
#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27, 20, 4);

//----- credentials of IBM Accounts -----

#define ORG "9gbe4w"            // IBM organisation id
#define DEVICE_TYPE "SWMSMC"    // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "ibmproject"  // Device ID mentioned in ibm watson iot platform
#define TOKEN "sUNA41tG6-Pq)0rk5X" // Token

//----- customise above values -----

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event
perform and format in which data to be send

char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is
test format of strings

char authMethod[] = "use-token-auth"; // authentication method

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id

//-----

WiFiClient wifiClient; // creating instance for wificlient

PubSubClient client(server, 1883, wifiClient);

#define ECHO_PIN 12

```

```
#define TRIG_PIN 13

float dist;

void setup()
{
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
    //pir pin
    pinMode(4, INPUT);

    //ledpins
    pinMode(23, OUTPUT);
    pinMode(2, OUTPUT);
    pinMode(4, OUTPUT);
    pinMode(15, OUTPUT);

    lcd.init();
    lcd.backlight();
    lcd.setCursor(1, 0);
    lcd.print("");
    wifiConnect();
    mqttConnect();
}

float readcmCM()
{
```

```
digitalWrite(TRIG_PIN, LOW);  
delayMicroseconds(2);  
digitalWrite(TRIG_PIN, HIGH);  
delayMicroseconds(10);  
digitalWrite(TRIG_PIN, LOW);  
int duration = pulseIn(ECHO_PIN, HIGH);  
return duration * 0.034 / 2;  
}
```

```
void loop()  
{  
  
    lcd.clear();  
  
    publishData();  
    delay(500);  
    if (!client.loop())  
    {  
        mqttConnect();           // function call to connect to IBM  
    }  
}
```

```
/* -----retrieving to cloud-----*/
```

```
void wifiConnect()  
{  
    Serial.print("Connecting to ");  
    Serial.print("Wifi");
```

```
WiFi.begin("Wokwi-GUEST", "", 6);  
while (WiFi.status() != WL_CONNECTED)  
{  
    delay(500);  
    Serial.print(".");  
}  
Serial.print("WiFi connected, IP address: ");  
Serial.println(WiFi.localIP());  
}  
void mqttConnect()  
{  
    if (!client.connected())  
    {  
        Serial.print("Reconnecting MQTT client to ");  
        Serial.println(server);  
        while (!client.connect(clientId, authMethod, token))  
        {  
            Serial.print(".");  
            delay(500);  
        }  
        initManagedDevice();  
        Serial.println();  
    }  
}  
void initManagedDevice()  
{  
    if (client.subscribe(topic))  
    {  
        Serial.println("IBM subscribe to cmd OK");  
    }  
}
```

```

    }
else
{
    Serial.println("subscribe to cmd FAILED");
}
}

void publishData()
{
    float cm = readcmCM();

    if(digitalRead(34))                //pir motion detection
    {
        Serial.println("Motion Detected");
        Serial.println("Lid Opened");
        digitalWrite(15, HIGH);

    }
else
{
    digitalWrite(15, LOW);
}

    if(digitalRead(34)== true)
    {
        if(cm <= 100)                //Bin level detection
        {
            digitalWrite(2, HIGH);
            Serial.println("High Alert!!!,Trash bin is about to be full");
            Serial.println("Lid Closed");

```

```
lcd.print("Full! Don't use");  
delay(2000);  
lcd.clear();  
digitalWrite(4, LOW);  
digitalWrite(23, LOW);  
}  
else if(cm > 150 && cm < 250)  
{  
    digitalWrite(4, HIGH);  
    Serial.println("Warning!!,Trash is about to cross 50% of bin level");  
    digitalWrite(2, LOW);  
    digitalWrite(23, LOW);  
}  
else if(cm > 250 && cm <=400)  
{  
    digitalWrite(23, HIGH);  
    Serial.println("Bin is available");  
    digitalWrite(2,LOW);  
    digitalWrite(4, LOW);  
}  
    delay(10000);  
    Serial.println("Lid Closed");  
}  
else  
{  
    Serial.println("No motion detected");  
}
```

```

    if(cm <= 100)
    {
        digitalWrite(21,HIGH);
        String payload = "{\"High Alert!!\":\":";
        payload += cm;
        payload += "left\"}";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);

        if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
            successfully,prints publish ok else prints publish failed
        {
            Serial.println("Publish OK");
        }
    }

    if(cm <= 250)
    {
        digitalWrite(22,HIGH);
        String payload = "{\"Warning!!\":\":";
        payload += dist;
        payload += "left\"}";
        Serial.print("\n");
        Serial.print("Sending distance: ");
        Serial.println(cm);
        if(client.publish(publishTopic, (char*) payload.c_str()))

```

```
{  
  Serial.println("Publish OK");  
}  
else  
{  
  Serial.println("Publish FAILED");  
}  
}
```

```
float inches = (cm / 2.54);           //print on lcd  
lcd.setCursor(0,0);  
  lcd.print("Inches");  
  lcd.setCursor(4,0);  
  lcd.setCursor(12,0);  
  lcd.print("cm");  
  lcd.setCursor(1,1);  
  lcd.print(inches, 1);  
  lcd.setCursor(11,1);  
  lcd.print(cm, 1);  
  lcd.setCursor(14,1);  
  delay(1000);  
  lcd.clear();  
}
```