```
import serial
import time
import csv
import numpy as np
import matplotlib.pyplot as plt
ser = serial.Serial('/COM6',9600)
ser_bytes = ser.readline(10)
print (ser_bytes)
ser.flushInput()
while True:
 try:
 ser_bytes = ser.readline()
 decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
 print(decoded_bytes)
temp = float(decoded_bytes(1:3))
turb = float(decoded_bytes(4:6))
pH = float(decoded_bytes(6:8))
 with open("test_data.csv","a") as f:
 writer = csv.writer(f,delimiter=",")
 writer.writerow([time.time(),decoded_bytes])
 except:
 print("Keyboard Interrupt")
 ser.close()
 break()
t = np.arange(0.0, 2.0, 0.01)
```

```
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
plt.xlabel('time (s)')
plt.ylabel('Celsisus (C)')
plt.title('Temperature')
plt.grid(True)
plt.savefig("Temperature.png")
plt.show()
Serial.begin(9600);
 sensors.begin();
 int sensorValue = analogRead(A1);
 voltage = sensorValue * (5.0 / 1024.0);
}
void loop(void)
{
 sensors.requestTemperatures();
 Celcius=sensors.getTempCByIndex(0);
 Fahrenheit=sensors.toFahrenheit(Celcius);
 for(int i=0;i<10;i++)
{
 buf[i]=analogRead(analogInPin);
 delay(10);
}
for(int i=0;i<9;i++)
{
```

```
 for(int j=i+1;j<10;j++)
 {
 if(buf[i]>buf[j])
 {
 temp=buf[i];
 buf[i]=buf[j];
 buf[j]=temp;
 }
n = 256
X = np.linspace(-np.pi, np.pi, 256, endpoint=True)
C,S = np.cos(X), np.sin(X)
plt.plot(X, C)
plt.plot(X,S)
plt.show()
print ("Visualization of real time sensor Data.")
print("/n")
while True:
 try:
 ser_bytes = ser.readline()
 decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
 print(decoded_bytes)
temp = float(decoded_bytes(1:3))
turb = float(decoded_bytes(4:6))
pH = float(decoded_bytes(6:8))
 with open("test_data.csv","a") as f:
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 writer.writerow([time.time(),decoded_bytes])
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 ser.close()
 break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
```