

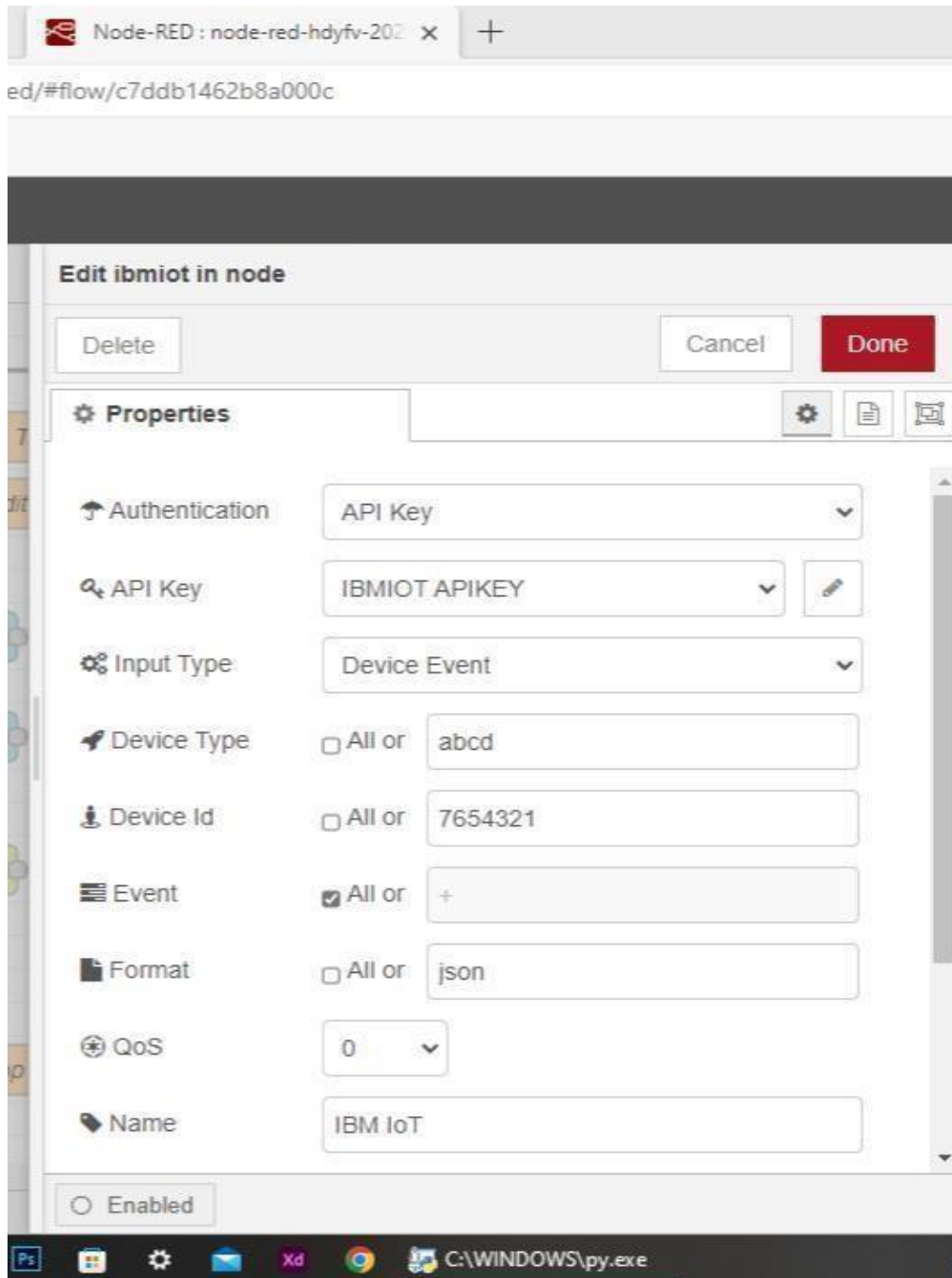
IOT ENABLED SMART FARMING APPLICATION

SPRINT DELIVERY – 3

TITLE	Smart Farmer-IOT Enabled Smart Farming Application
DOMAIN NAME	INTERNET OF THINGS
TEAM ID	PNT2022TMID21910

5.4 Configuration of Node-Red to send commands to IBM cloud

ibmiot out node I used to send data from Node-Red to IBM Watson device. So, after adding it to the flow we need to configure it with credentials of our Watson device.



Here we add two buttons in UI

1 -> for motor on

2 -> for motor off

We used a function node to analyse the data received and assign command to each number.

The Java script code for the analysis is:

```
if(msg.payload===1)
```

```
msg.payload={"command": "ON"}; else
```

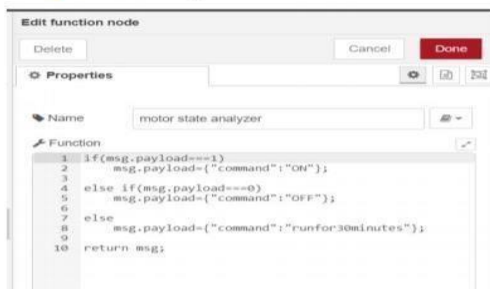
```
if(msg.payload===0)
```

```
msg.payload={"command": "OFF"};
```

Then we use another function node to parse the data and get the command and represent it visually with text node.

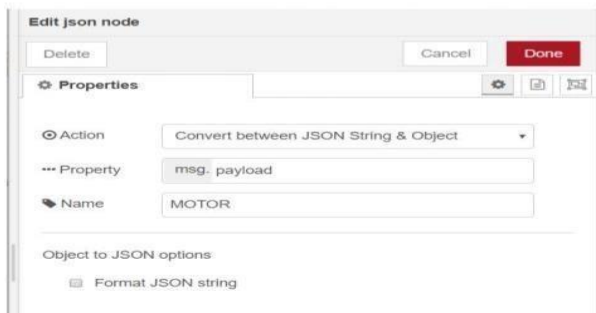
The Java script code for that function node is:

```
var state=msg.payload;  
msg.payload = state.command;  
return msg;
```

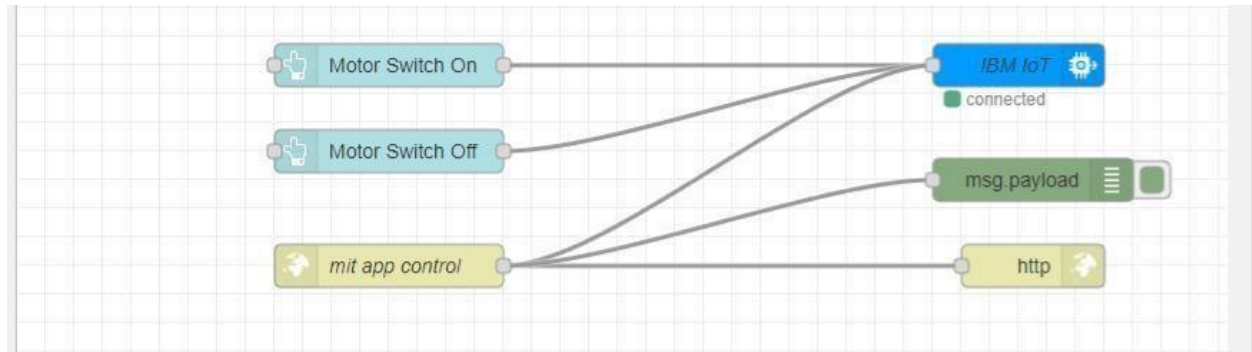


The above images show the java script codes of analyser and state function nodes.

Then we add edit json node to the conversion between JSON string & object and finally connect it to IBM IoT Out.



Edit JSON node needs to be configured like this



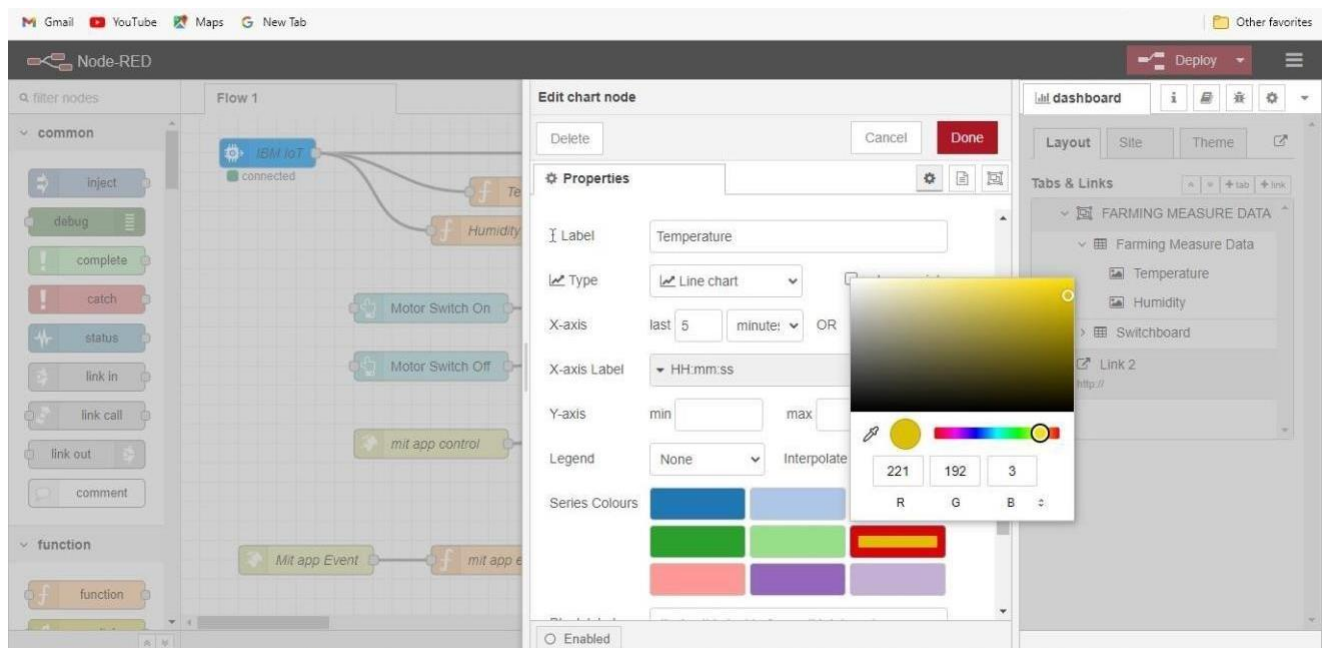
This is the program flow for sending commands to IBM cloud.

5.5 Adjusting User Interface

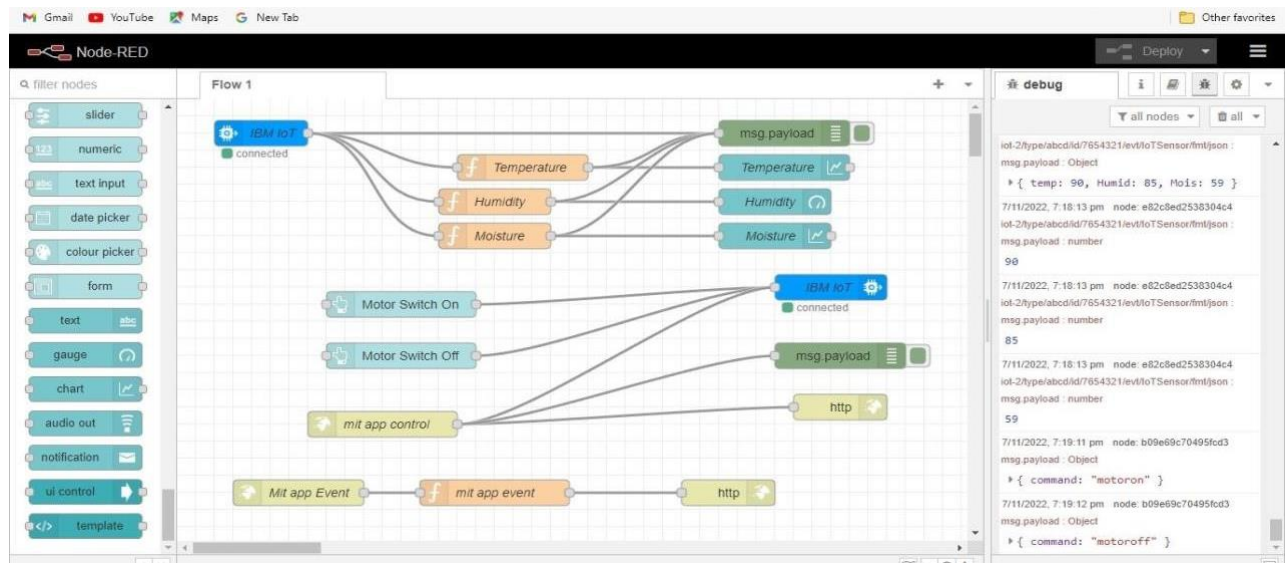
In order to display the parsed JSON data a Node-Red dashboard is created

Here we are using Gauges, text and button nodes to display in the UI and helps to monitor the parameters and control the farm equipment.

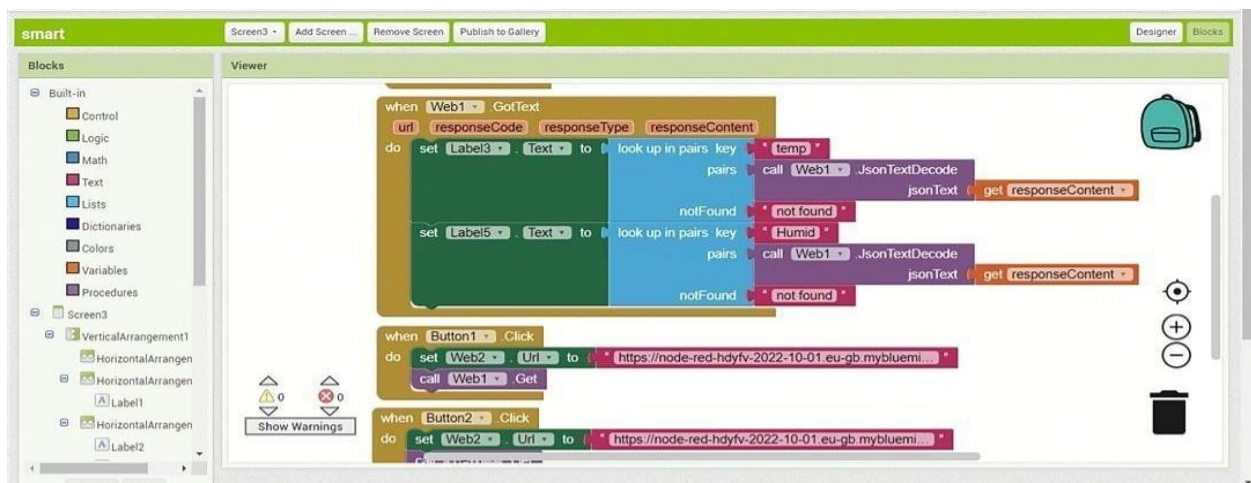
Below images are the Gauge, text and button node configurations.



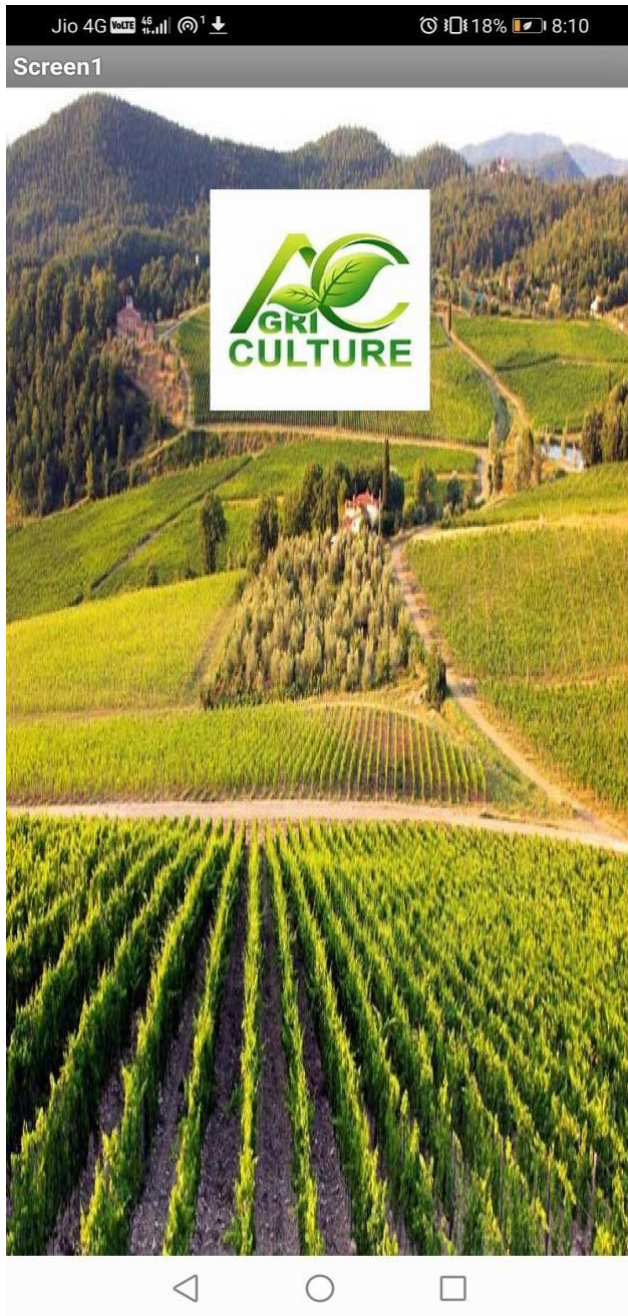
Complete Program Flow



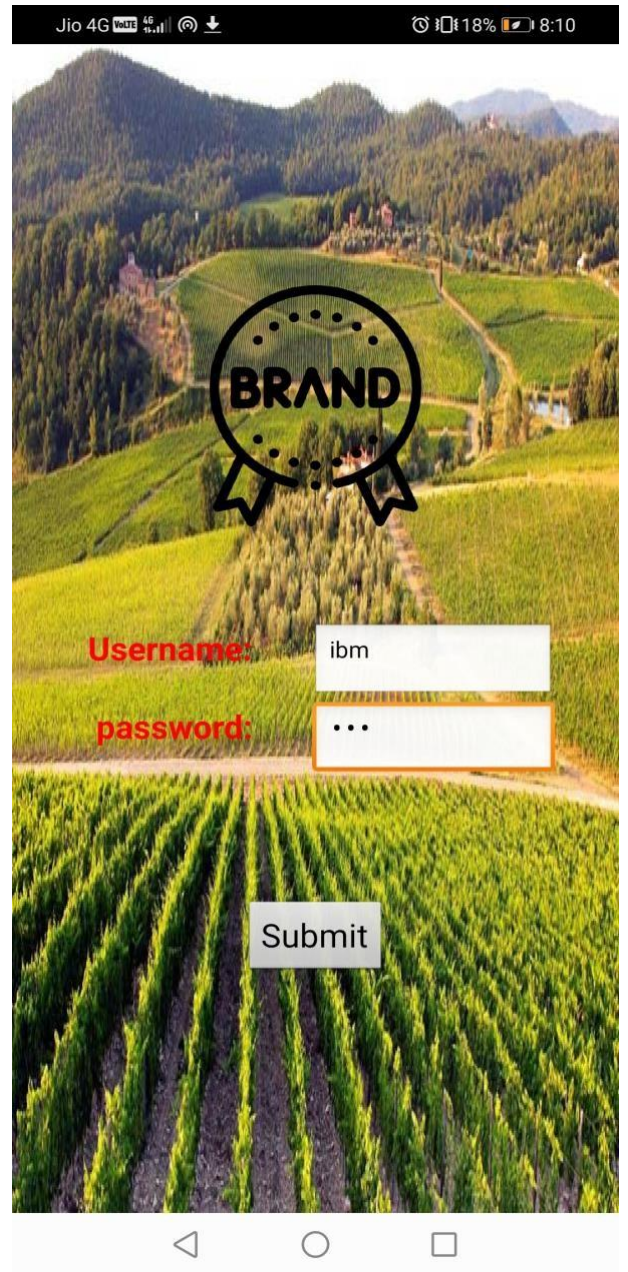
MOBILE APP WEB :



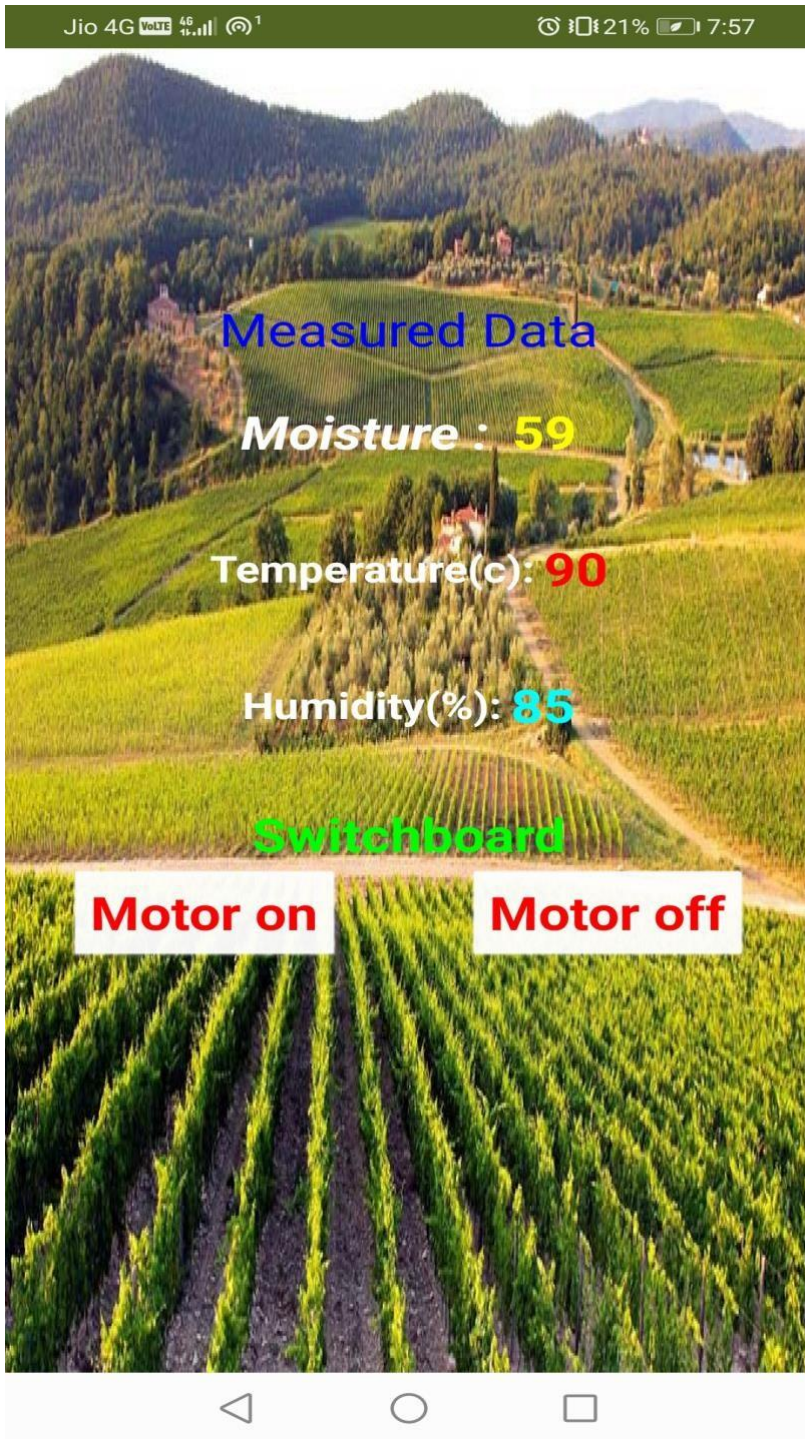
BLOCK DIAGRAM



SCREEN - 1



SCREEN - 2



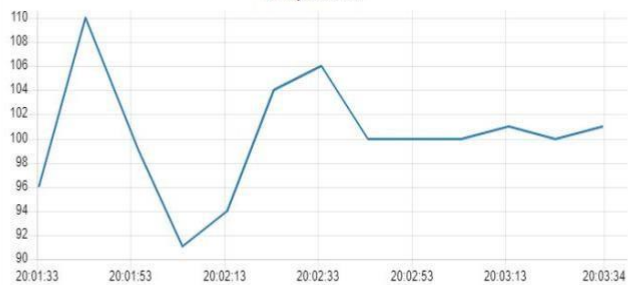
SCREEN - 3

Web APP UI Home Tab

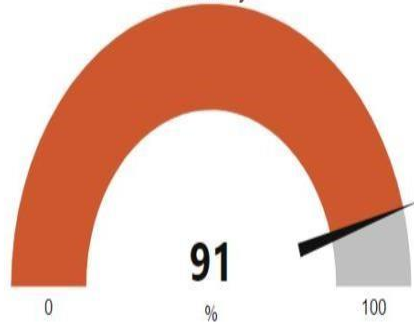
FARMING MEASURE DATA

Farming Measure Data

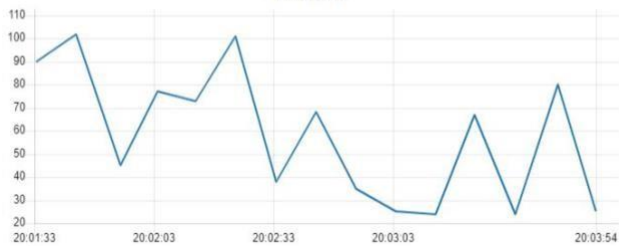
Temperature



Humidity



Moisture



Switchboard

MOTOR SWITCH ON

MOTOR SWITCH OFF