

Assignment -4

Distance Detection Using Ultrasonic Sensor

Assignment Date	19 October 2022
Student Name	Ranton Nigil R
Student Roll Number	1901156
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK : <https://wokwi.com/projects/345964118720643668>

CODE:

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "f59trs" //IBM ORGANITION ID
#define DEVICE_TYPE "ultrasonicsensor" //Device type mentioned in
ibm watson IOT Platform
#define DEVICE_ID "distancedetection" //Device ID mentioned in ibm
watson IOT Platform
#define TOKEN "AlGMGaaF01nawa1QA3" //Token
String data3;
float dist;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; //
Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and
type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String"; //
cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client
id

//-----
```

```

WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient);
//calling the predefined client id by passing parameter like
server id,portand wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED, OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}
void loop()// Recursive Function
{

  digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}

/*.....retrieving to
Cloud.....*/

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
    creating the String in in form JSon to update the data to
    ibm cloud
  */

```

```

String object;
if (dist <100)
{
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\":";
payload += dist;
payload += "," "\"object\":";
payload += object;
payload += "\"}";

Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data
on the cloud then it will print publish ok in Serial monitor or
else it will print publish failed
} else {
    Serial.println("Publish failed");
}
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!!!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

```

```

}
void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6); //passing the wifi credentials
    to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }

    // Serial.println("data: "+ data3);
    // if(data3=="Near")
    // {
    // Serial.println(data3);
    // digitalWrite(LED,HIGH);

    // }

    // else
    // {

```

```

// Serial.println(data3);
// digitalWrite(LED,LOW);

// }
data3="";

}

```

OUTPUT :

When object is not near to the ultrasonic sensor

The screenshot displays the Wokwi IDE interface. On the left, the 'sketch.ino' file contains the following code:

```

1 #include <WiFi.h> //library for wifi
2 #include <PubSubClient.h> //library for MQTT
3
4
5 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
6
7 //-----credentials of IBM Accounts-----
8
9 #define ORG "f59trs" //IBM ORGANITION ID
10 #define DEVICE_TYPE "ultrasonicsensor" //Device type mentioned in ibm watson IOT Platform
11 #define DEVICE_ID "distancedetection" //Device ID mentioned in ibm watson IOT Platform
12 #define TOKEN "AlGMGaaF01nawa1QA3" //Token
13 String data3;
14 float dist;
15
16
17 //----- Customise the above values -----
18 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
19 char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of event perform and
20 char subscribetopic[] = "iot-2/cmd/test/fmt/String"; // cmd REPRESENT command type AND COMM
21 char authMethod[] = "use-token-auth"; // authentication method
22 char token[] = TOKEN;
23 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id
24
25
26 //-----
27 WiFiClient wificlient; // creating the instance for wificlient
28 PubSubClient client(server, 1883, callback ,wificlient); //calling the predefined client id
29
30 int LED = 4;
31 int trig = 5;
32 int echo = 18;
33 void setup()

```

The simulation window on the right shows the ESP32 and HC-SR04 sensor connected. The output log displays the following sequence of events:

```

no object found
Sending payload: {"distance":403.45,"object":"No"}
Publish ok
Distancein cm233.00
no object found
Sending payload: {"distance":233.00,"object":"No"}
Publish ok

```

Data sent to the IBM cloud device when the object is far

The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains icons for various IoT functions. The main content area displays a device named 'distancedetection' with a status of 'Connected' and a sensor type of 'ultrasonicsensor'. The 'Recent Events' tab is active, showing a table of data events. The table has columns for 'Event', 'Value', 'Format', and 'Last Received'. The data shows a series of 'Data' events with a JSON value containing distance and object status. A status box at the bottom right indicates '0 Simulations running'.

IBM Watson IoT Platform

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Browse Action Device Types Interfaces

distancedetection Connected ultrasonicsensor Device Oct 19, 2022 11:56 AM

Identity Device Information Recent Events State Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"distance":235.02,"object":"No"}	json	a few seconds ago
Data	{"distance":235.02,"object":"No"}	json	a few seconds ago
Data	{"distance":235.02,"object":"No"}	json	a few seconds ago
Data	{"distance":235.02,"object":"No"}	json	a few seconds ago
Data	{"distance":235.02,"object":"No"}	json	a few seconds ago

0 Simulations running

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When object is nearer to the ultrasonic sensor

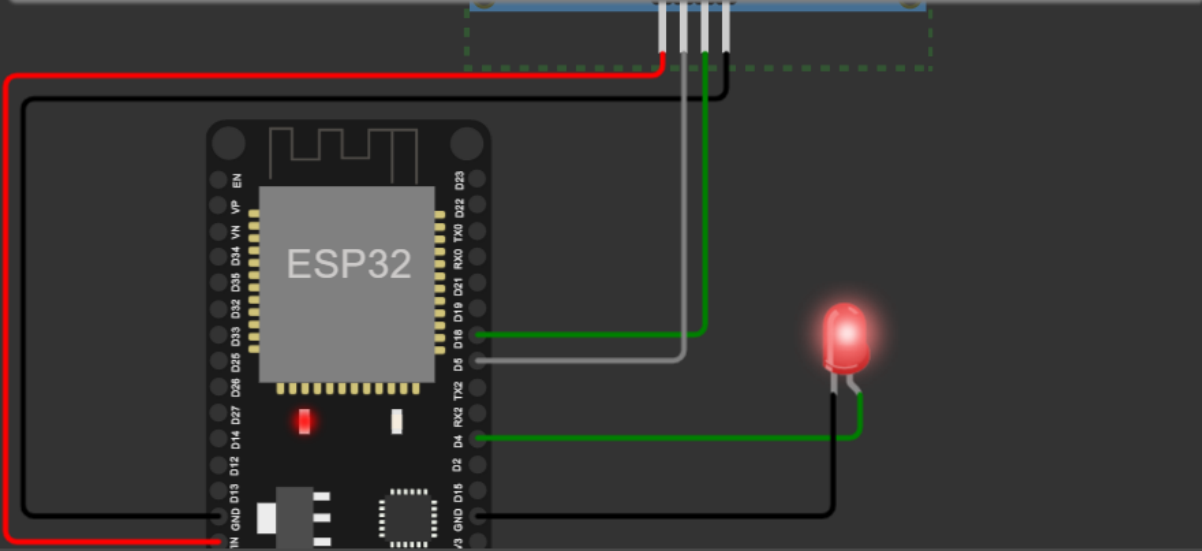
Simulation

01:03.599 94%

HC-SR04

Editing Ultrasonic Distance Sensor

Distance: 91cm



ESP32

Sending payload: {"distance":91.77,"object":"Near"}

Publish ok

Distancein cm91.77

object is near

Sending payload: {"distance":91.77,"object":"Near"}

Publish ok

Distancein cm91.77

Data sent to the IBM cloud device when the object is near

The screenshot displays the IBM Watson IoT Platform dashboard. The top navigation bar includes the platform name, a user profile, and a search bar. The main content area shows a list of devices, with 'distancedetection' selected. Below the device list, a tabbed interface shows 'Recent Events', which displays a stream of data points. The data points are JSON objects containing distance and object information. A status bar at the bottom indicates '0 Simulations running'.

Device ID	Status	Device Type	Class ID	Date Added	Descriptive Location
distancedetection	Connected	ultrasonicsensor	Device	Oct 19, 2022 11:56 AM	

Event	Value	Format	Last Received
Data	{"distance":91.77,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.75,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.77,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.79,"object":"Near"}	json	a few seconds ago
Data	{"distance":91.8,"object":"Near"}	json	a few seconds ago

0 Simulations running

<https://wokwi.com/projects/345964118720643668>

