ASSIGNMENT 4

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Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

Sketch.ino

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-------credentials of IBM Accounts------
#define ORG "engn92"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP1"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "Assignment4"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
```

```
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
}
void loop()
{
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
{
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
}
```

```
delay(1000);
}
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void wificonnect()
{
```

```
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
}
Serial.println("data: "+ data3);
data3="";
}
```

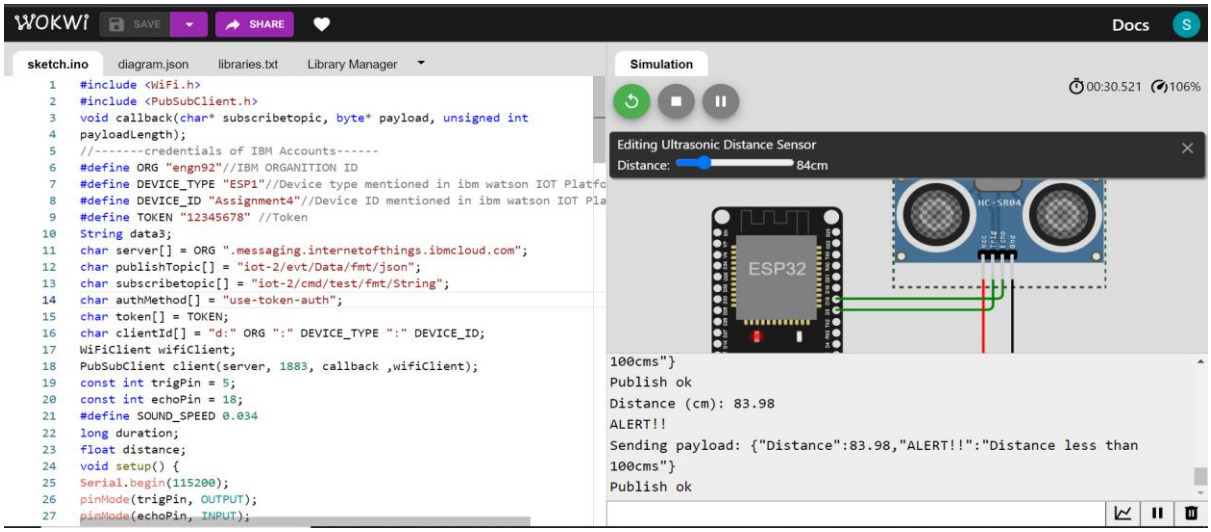
Diagram.json

```
{
  "version": 1,
  "author": "6154_ SWATHI S",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 17.33, "left": -98.67, "attrs": {} },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": -11.41, "left": 50.44, "attrs": {} }
  ],
  "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
    [ "ultrasonic1:VCC", "esp:VIN", "red", [ "v0" ] ],
    [ "ultrasonic1:GND", "esp:GND.1", "black", [ "v0" ] ],
    [ "ultrasonic1:TRIG", "esp:D5", "green", [ "v0" ] ],
    [ "ultrasonic1:ECHO", "esp:D18", "green", [ "v0" ] ]
  ]
}
```

Wokwi link:

https://wokwi.com/projects/347186552083841620

Output :


WOKWI
SAVE
SHARE
Docs
sketch.ino
diagram.json
libraries.txt
Library Manager
Simulation
00:30.521
106%
Editing Ultrasonic Distance Sensor
Distance:
84cm
ESP32
HC-SR04
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//-------credentials of IBM Accounts------
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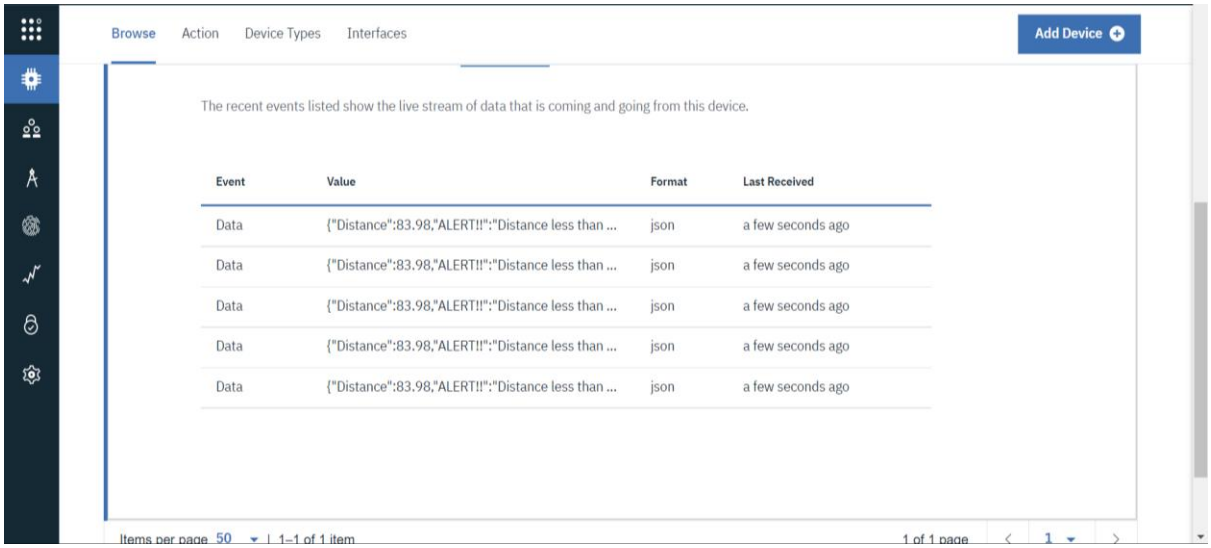
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
100cms"}
Publish ok
Distance (cm): 83.98
ALERT!!
Sending payload: {"Distance":83.98,"ALERT!!":"Distance less than 100cms"}
Publish ok


Browse
Action
Device Types
Interfaces
Add Device
The recent events listed show the live stream of data that is coming and going from this device.
Event
Value
Format
Last Received
Data
{"Distance":83.98,"ALERT!!":"Distance less than ...
json
a few seconds ago
Items per page 50
1–1 of 1 item
1 of 1 page
1