Assignment -4

Assignment Date	19 September 2022
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Maximum Marks	2 Marks

Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
#define buzzerPin 4
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "nw3318"//IBM ORGANITION ID
#define DEVICE_TYPE "123"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "1234567"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
float h, t;
int d;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and
format in which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by
passing parameter like server id, portand wificredential
```

long readUltrasonicDistance(int triggerPin, int echoPin)

```
pinMode(triggerPin, OUTPUT);
 digitalWrite(triggerPin, LOW);
 delayMicroseconds(2);
 digitalWrite(triggerPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(triggerPin, LOW);
 pinMode(echoPin, INPUT);
 return pulseIn(echoPin, HIGH);
}
void setup()// configureing the ESP32
 Serial.begin(115200);
 pinMode(buzzerPin, OUTPUT);
 delay(10);
 Serial.println();
 wificonnect();
 mqttconnect();
void loop()// Recursive Function
 d=(0.01723 * readUltrasonicDistance(18, 19));
 Serial.print("distance:");
 Serial.println(d);
 if(d<100)
  tone(buzzerPin, 31);
 delay(1000);
 noTone(buzzerPin);
 delay(1000);
 tone(buzzerPin, 100, 1000);
 delay(2000);
  Serial.print("buzzer on");
  Serial.println();
  digitalWrite(buzzerPin,HIGH);
 }
 else
  Serial.print("buzzer off");
  Serial.println();
  digitalWrite(buzzerPin,LOW);
 PublishData(d);
```

```
delay(1000);
 if (!client.loop()) {
  mqttconnect();
 }
}
/*....retrieving to Cloud.....*/
void PublishData(int distance) {
 mqttconnect();//function call for connecting to ibm
   creating the String in in form JSon to update the data to ibm cloud
 String payload = "{\"distance\":";
 payload += distance;
 payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print
publish ok in Serial monitor or else it will print publish failed
  Serial.println("Publish failed");
}
void mqttconnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
  while (!!!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  }
   initManagedDevice();
   Serial.println();
 }
void wificonnect() //function defination for wificonnect
```

```
Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the
connection
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
}
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
  Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
  Serial.println("subscribe to cmd FAILED");
 }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {
  //Serial.print((char)payload[i]);
  data3 += (char)payload[i];
 Serial.println("data: "+ data3);
 if(data3=="lighton")
Serial.println(data3);
digitalWrite(LED,HIGH);
 }
 else
Serial.println(data3);
digitalWrite(LED,LOW);
 }
data3="";
}
```



