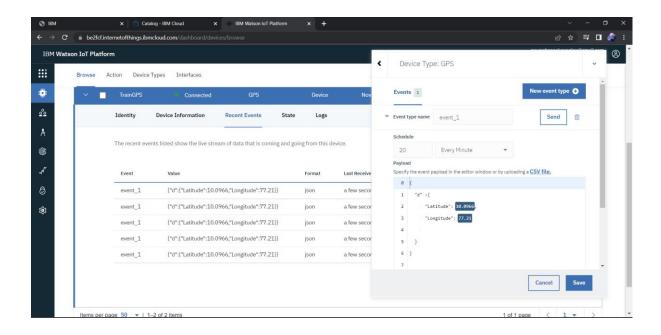
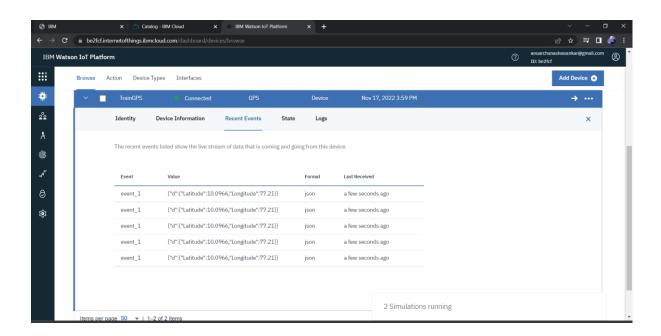
Sprint 3

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Code:

import time

```
import sys
import ibmiotf.application
import ibmiotf.device
import random
import requests
import json
#Provide your IBM Watson Device Credentials
organization = "be2fcf"
deviceType = "GPS"
                      #Credentials of Watson IoT sensor simulator
deviceId = "TrainGPS"
authMethod = "token"
authToken = "pa2tTjP1b3VRKFFP7R"
# Initialize the device client.
L=0
try:
       deviceOptions = {"org":organization , "type": deviceType , "id":deviceId , "auth-
method":authMethod , "auth-token":authToken}
       deviceCli = ibmiotf.device.Client(deviceOptions)
       #.....
except Exception as e:
       print("Caught exception connecting device: %s" % str(e))
       sys.exit()
# Connect and send a datapoint "hello" with value "world" into the cloud as an event of type
"greeting" 10 times
deviceCli.connect()
```

```
while True:
  overpass_url = "http://overpass-api.de/api/interpreter"
  overpass_query = """
  [out:json];area[name="India"];(node[place="village"](area););out;
  response = requests.get(
  overpass_url,
  params={'data': overpass_query}
  )
  coords = []
  if response.status_code == 200:
    data = response.json()
    places = data.get('elements', [])
    for place in places:
      coords.append((place['lat'], place['lon']))
    print ("Got %s village coordinates!" % len(coords))
    print (coords[0])
  else:
    print("Error")
  i = random.randint(1,100)
  L = coords[i]
  #Send random gprs data to node-red to IBM Watson
  data = {"d":{ 'Latitude' : L[0], 'Longitude' : L[1]}}
  #print data
  def myOnPublishCallback():
    print("Published gprs location = ", L, "to IBM Watson")
  success = deviceCli.publishEvent("Data", "json", data, qos=0, on_publish=myOnPublishCallback)
```

```
time.sleep(12)
if not success:
    print("Not connected to IoTF")
time.sleep(1)

deviceCli.disconnect()
```