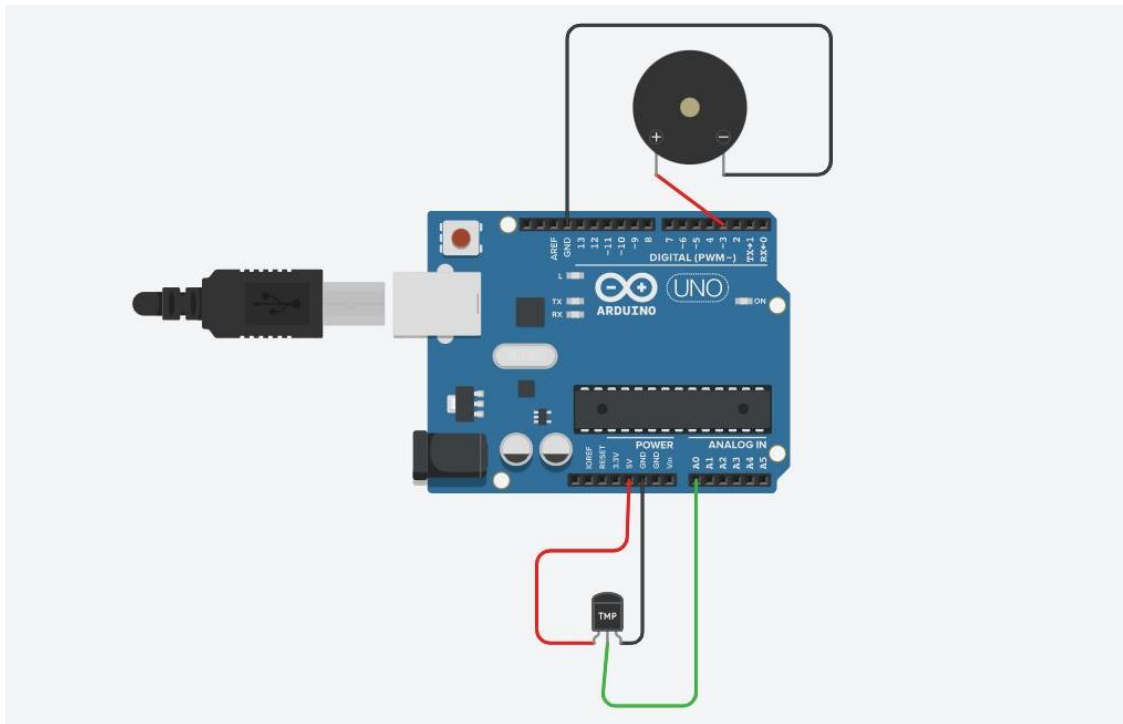


## 1) Arduino With Temperature Sensor and Buzzer :-

### ➔ Circuit Connections



### Code:

```
float sensorValue, Celsius;
```

```
void setup() {
```

```
Serial.begin(9600);  
pinMode(A0, INPUT);  
pinMode(3, OUTPUT);  
  
}  
  
void loop() {  
    sensorValue = analogRead(A0);  
    Celsius = (sensorValue*5000/1024)/10;  
    Serial.print("Celsius: ");  
    Serial.print(Celsius);  
    Serial.print("\n");  
  
    if(Celsius>60)  
    {  
        digitalWrite(3, HIGH);  
    }  
    else{
```

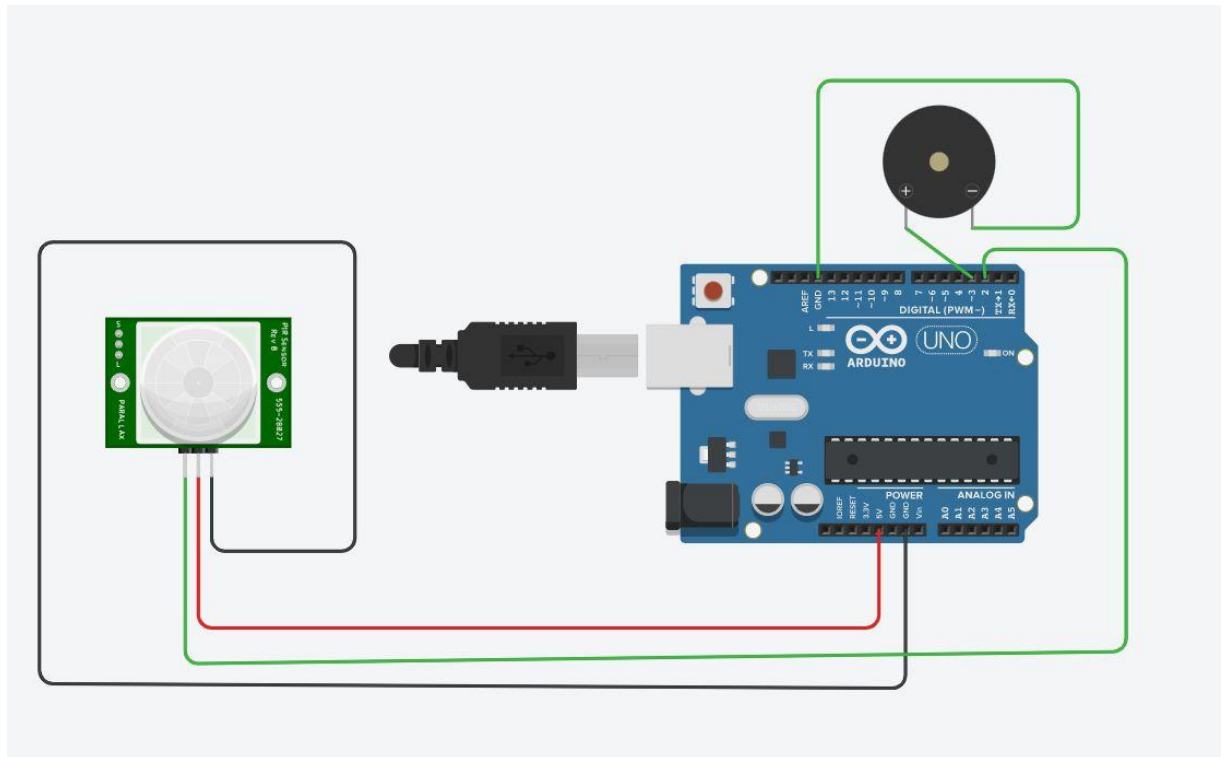
```
digitalWrite(3,LOW);  
}  
  
delay(2000);  
}
```

***Output:***



## 2) Arduino With PIR Sensor :-

### Circuit Connections:



### Code:

```
void setup() {  
  
  pinMode(2, INPUT);
```

```
pinMode(3, OUTPUT);
```

```
}
```

```
void loop() {
```

```
if (digitalRead(2) == HIGH)
```

```
{
```

```
digitalWrite(3, HIGH);
```

```
delay(100);
```

```
digitalWrite(3, LOW);
```

```
delay(100);
```

}

}