## Assignment-4

Project title	Smart Waste Management System for		
	Metropolitan Cities		
Team ID	PNT2022TMID32675		
Team leader	Sivaram N		
Register number	813819104095		

Write a code and connections in working for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "Alert" to IBM cloud and display in the device recent events.

## Code:

```
#include
<WiFi.h>
#include
<PubSubClient.h>
void callback(char* subscribe topic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANIZATION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson IOT
Platform #define DEVICE ID "12345"//Device ID mentioned in ibm watson IOT
Platform #define TOKEN \overline{\ }12345678" //Token
String data3;
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribe topic[]
="iot-2/cmd/test/fmt/String"; char
authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback
,wifiClient); const int trigPin = 5;
const int echoPin
= 18; #define
SOUND SPEED 0.034
long duration;
float distance;
```

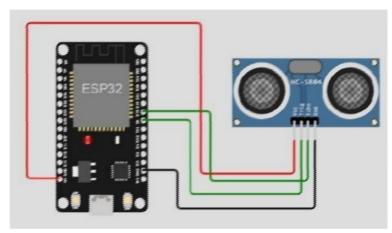
```
void setup()
Serial.begin (1152
00);
pinMode(trigPin,
OUTPUT);
pinMode (echoPin,
INPUT); wifi
connect(); mqtt
connect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin,
HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin,
HIGH); distance = duration
* SOUND SPEED/2;
Serial.print("Distance
(cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!"
);
delay(1000);
PublishData(di
stance);
delay(1000);
if (!client.loop())
{ mqtt connect();
delay(1000);
void PublishData(float dist)
{ mqtt connect();
String payload =
"{\"Distance\":"; payload
+= dist;
payload += ",\"ALERT!!\":""\"Distance less than
100 cms\""; payload += "}";
Serial.print("Sending
payload: ");
Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c str()))
{ Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
void mgtt connect() {
if (!client.connected())
{ Serial.print("Reconnecting
client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token))
Serial.print
(".");
delay(500);
initManagedD
evice();
Serial.print
ln();
void wifi connect()
Serial.println();
Serial.print("Connecting to
"); WiFi.begin("Wokwi-GUEST",
"", 6); while (WiFi.status()
! = WL CONNECTED)
delay(500)
Serial.pri
nt(".");
Serial.println("");
Serial.println("WiFi
connected");
Serial.println("IP
address: ");
Serial.println(WiFi.local
IP());
void initManagedDevice() {
if (client.subscribe(subscribe topic))
{ Serial.println((subscribe
topic));
Serial.println("subscribe to
cmd OK");
```

```
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribe topic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
//Serial.print((char)payload[i
]); data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
Diagram.json:
  "version": 1,
 "author": "Rithick
 Kumar ", "editor":
 "working", "parts":
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
   { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
 "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RXO", "$serialMonitor:TX",
    "", [] ], [
     "esp:VIN",
      "ultrasoni
     c1:VCC",
      "red",
      [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
    [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
    [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
   [ "esp:D18", "ultrasonic:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
```

}

## Circuit Diagram:



Output:
Working output: