ASSIGNMENT - 4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
Team ID	PNT2022TMID32584
Project Name	Personal Assistance for seniors who are self reliant
Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

```
### wind callbooks (not () bear to a mile a mile and interpretation of the control of the contro
```

```
esp32-blink.ino • diagram json •
                                   libraries.bd .
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo, IMPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalwrite(trig, LOW);
         digitalWrite(trig, HISH);
         delayMicroseconds(10);
         digitalWrite(trig, (OW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein on");
         Serial.println(dist);
         PublishData(dist);
         dellay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to 1hm
```

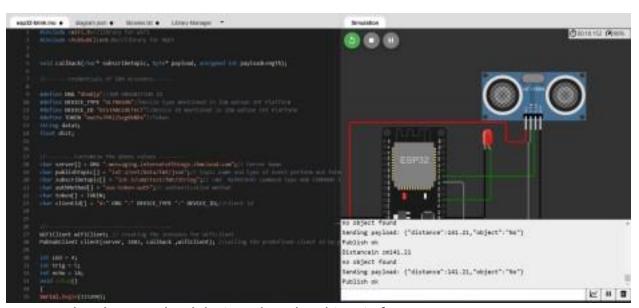
```
// Consting the String in in fore ison to update the data to the chool
// String object;
// If (dist <100)
// (digitalbrite(LED,HDM));
// Serial.println("nbject is coar");
// object = "Near";
// digitalbrite(LED,HDM);
// serial.println("no object found");
// object = "No";
// String payload = "\"distance\":";
// payload == dist;
// payload == dist;
// payload == "\""object\":\"";
// payload == object;
// payload == "\"");
// Serial.print("Sending payload: ");
// Serial.println(payload);
// Seria
```

```
applicable * degree con * theresist * throught explained *

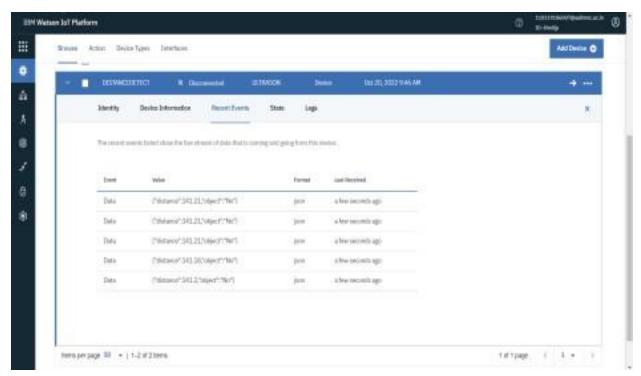
if (plant, philadephilatephilate, (nor*) paylors. ret())) {
    serial origin(-failed or); (if if throught allow has no the product of this or to began entire or size it will prot position on to began entire or size it will prot position for the paylor of this it will prot position on to began entire or size it will prot position for the paylor of the pay
```

```
esp32-blink.ino .
                  diagram json .
                                   libraries.bt ...
                                                Library Manager *
         WIF1.begin("Wokwi-GUES1", "", 6);//passing the wifl credentials to establish the connection
         while (WiFi.status() |- ML_COMNECTED) (
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: );
         Serial.println(WiFi.localIP());
       void initManagedDevice() [
         if (client.subscribe(subscribetopic)) (
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
         } else {
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
         for (int i - 0; i < payloadLength; i++) {
           data3 += (char)payload[i];
```

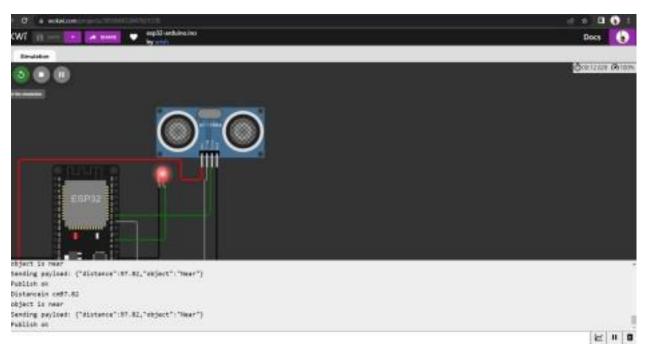
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

