SPRINT I

Team ID	PNT2022TMID01889
Project Name	Smart Waste Management System for
	metropolitan cities

WORK DONE IN SPRINT 1:

> Python code is developed and then tested whether the code is generating random sensor data or not

SCREENSHOT:



CODE:

import time

import random

import sys

import requests

import json

import ibmiotf.application

```
import ibmiotf.device
# watson device details
organization = "3w5ire"
devicType = "Dustbin"
deviceId = "DustbinID"
authMethod= "token"
authToken= "987654321"
#generate random values for random variables (Distance and load)
def myCommandCallback(cmd):
  global a
  print("command recieved:%s" %cmd.data['command'])
  control=cmd.data['command']
  print(control)
try:
    deviceOptions={"org": organization, "type": devicType, "id": deviceId, "auth-
method":authMethod,"auth-token":authToken}
    deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()
#connect and send a datapoint "Distance" with value integer value into the cloud as a type of
event for every 10 seconds
deviceCli.connect()
while True:
  lat=10.9368
  lon=78.1366
  Distance= random.randint(1,75)
```

```
Loadcell= random.randint(0,20)
  data= {'dist':Distance,'load':Loadcell,'latitude':lat,'longitude':lon}
  if Loadcell<5 and Loadcell>0:
       load="20%"
  elif Loadcell<10 and Loadcell>5:
       load="40%"
  elif Loadcell<15 and Loadcell>10:
       load="60%"
  elif Loadcell<18 and Loadcell>15:
       load="80%"
  elif Loadcell<20 and Loadcell>18:
       load="90%"
  else:
       load="100%"
  if Distance<7 and Distance>1:
       level="90%"
  elif Distance<15 and Distance>7:
       level="80%"
  elif Distance<30 and Distance>15:
       level="60%"
  elif Distance<45 and Distance>30:
       level="40%"
  elif Distance<60 and Distance>45:
       level="20%"
  elif Distance<75 and Distance>60:
       level="10%"
  else:
       level="0%"
  if(distance="90%" or load="90%"):
    warn={'Alert':'Dustbin is almost filled'}
  def myOnPublishCallback(latitude=10.9368,longitude=78.1366):
    print("Puliyur,Karur,Tamilnadu")
    print("published Level of bin = %s " %level,"Load = %s " %load, "Latitude = %s "
%latitude, "Longitude = %s " %longitude)
```

```
print(load)
                             print(level)
                                            print(warn)
           time.sleep(10)
              success=deviceCli.publishEvent\ ("IoTSensor","json",warn,qos=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_publish=0,on\_pu
myOnPublishCallback)
              success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on_publish=
myOnPublishCallback)
              if not success:
                             print("not connected to ibmiot")
              time.sleep(20)
              device Cli.command Callback = my Command Callback\\
#disconnect the device
deviceCli.disconnect()
```