Delivery of Sprint-1

DATE	12 November 2022
TEAM ID	PNT2022TMID42279
PROJECT NAME	SMART WASTE MANAGEMENT FOR METROPOLITAN CITIES

Code for Data Transfer from Sensors

```
#include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal I2C.h>
LiquidCrystal_I2C lcd (0x27, 20, 4);
//----- credentials of IBM Accounts -----
#define ORG "9rlqaa" // IBM organisation id
#define DEVICE TYPE "smartwaste" // Device type mentioned in ibm watson iot platform
#define DEVICE ID "ibmproject" // Device ID mentioned in ibm watson iot platform
#define TOKEN "qvjYpl*mkM_F1&3NTi" // Token
//----- customise above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event perform and format in which data
to be send
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test format of strings
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID; //Client id
WiFiClient wifiClient; // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO PIN 12
#define TRIG_PIN 13
float dist;
void setup()
{
Serial.begin(115200);
pinMode(LED BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
//pir pin
pinMode(34, INPUT);
//ledpins
pinMode(23, OUTPUT);
pinMode(2, OUTPUT);
```

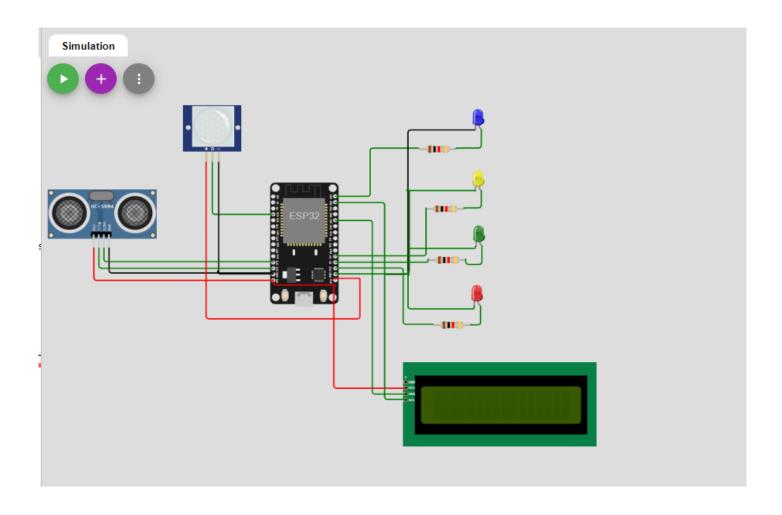
```
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
float readcmCM()
digitalWrite(TRIG PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
lcd.clear();
publishData();
delay(500);
if (!client.loop())
{
mqttConnect(); // function call to connect to IBM
}
}
/* ------*/
void wifiConnect()
{
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect()
if (!client.connected())
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
```

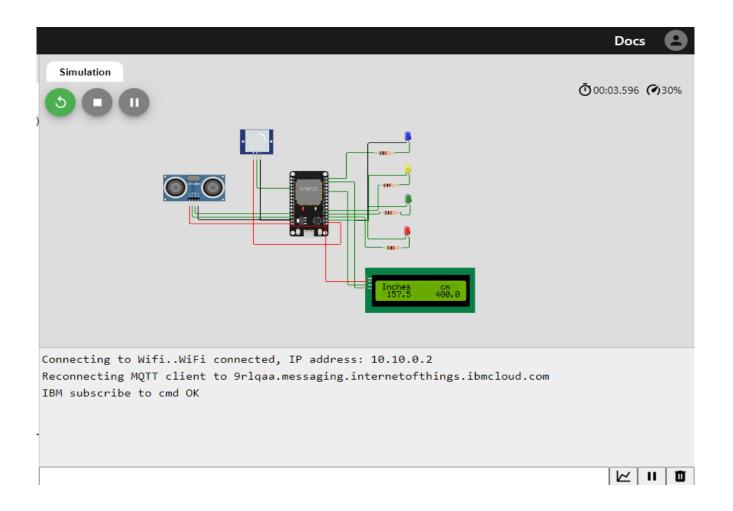
```
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice()
if (client.subscribe(topic))
Serial.println("IBM subscribe to cmd OK");
}
else
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
float cm = readcmCM();
if(digitalRead(34)) //pir motion detection
Serial.println("Motion Detected");
Serial.println("Lid Opened");
digitalWrite(15, HIGH);
if(digitalRead(34)== true)
{
if(cm <= 60) //Bin level detection
digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("Lid Closed");
lcd.print("Full! Don't use");
delay(2000);
lcd.clear();
digitalWrite(4, LOW);
digitalWrite(23, LOW);
}
else if(cm > 60 && cm < 120)
{
digitalWrite(4, HIGH);
Serial.println("Warning!!,Trash is about to cross 50% of bin level");
digitalWrite(2, LOW);
digitalWrite(23, LOW);
else if(cm > 120)
digitalWrite(23, HIGH);
```

```
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
}
delay(10000);
Serial.println("Lid Closed");
}
else
{
Serial.println("No motion detected");
digitalWrite(2, LOW);
digitalWrite(15, LOW);
digitalWrite(4, LOW);
digitalWrite(23, LOW);
}
}
else
{
digitalWrite(15, LOW);
}
if(cm \le 60)
digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
{
Serial.println("Publish OK");
}
}
else if (cm <= 120)
digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
```

```
}
else
{
Serial.println();
float inches = (cm / 2.54); //print on lcd
lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.print(cm, 1);
lcd.setCursor(14,1);
delay(1000);
lcd.clear();
```

CONNECTION DIAGRAM





LINK: https://wokwi.com/projects/348116819256541779