# ASSIGNMENT - 4 ULTRASONIC SENSOR SIMULATION IN WOKWI

## CODE

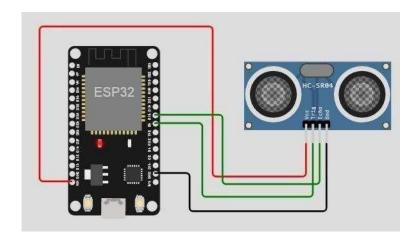
```
#include <WiFi.h> #include <PubSubClient.h>
void callback(char*
subscribetopic, byte* payload,
unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type
mentioned in ibm watson IOT Platform #define
DEVICE_ID "12345"//Device ID mentioned in ibm
watson IOT Platform #define TOKEN "12345678"
//Token
String data3;
char server[] = ORG
".messaging.internetofthings.ibmclou
d.com"; char publishTopic[] =
"iot-2/evt/Data/fmt/json";
char subscribetopic[] =
"iot-2/cmd/test/fmt/Str
ing"; char authMethod[]
= "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server,
1883, callback
,wifiClient); const int
trigPin = 5;
const int echoPin = 18; #define SOUND_SPEED 0.034 long duration;
float distance; void setup() {
Serial.begin(115200); pinMode(trigPin, OUTPUT); pinMode(echoPin, INPUT);
wificonnect(); mqttconnect();
void loop()
digitalWrite(trigPin, LOW); delayMicroseconds(2); digitalWrite(trigPin, HIGH);
delayMicroseconds(10); digitalWrite(trigPin, LOW); duration = pulseIn(echoPin,
HIGH); distance = duration * SOUND_SPEED/2; Serial.print("Distance (cm): ");
Serial.println(distance); if(distance<100)</pre>
Serial.println("ALERT!!"); delay(1000);
PublishData(distance); delay(1000);
if (!client.loop()) { mqttconnect();
}
delay(1000);
```

```
}
void PublishData(float dist) { mqttconnect();
String payload = "{\"Distance\":"; payload += dist;
payload +=
",\"ALERT!!\":""\"Distance
less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}
void mqttconnect() {
if (!client.connected()) { Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
}
 initManagedDevice();
 Serial.println();
 }
 }
 void wificonnect()
 Serial.println(); Serial.print("Connecting to "); WiFi.begin("Wokwi-GUEST", "",
 6); while (WiFi.status() != WL_CONNECTED) { delay(500);
 Serial.print(".");
 Serial.println(""); Serial.println("WiFi connected"); Serial.println("IP address:
 "); Serial.println(WiFi.localIP());
 void initManagedDevice() {
 (client.subscribe(subscrib
 etopic)) {
 Serial.println((subscribet
 opic));
 Serial.println("subscribe
 to cmd OK");
 } else {
 Serial.println("subscribe to cmd FAILED");
 }
 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
```

```
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
     Serial.println("data: "+ data3); data3="";
     }
Diagram.json:
"version": 1,
"author": "sweetysharon", "editor": "wokwi", "parts": [
{ "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67,
"attrs": {} },
{ "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17,
"attrs": {} }
"connections": [
[ "esp:TX0", "$serialMonitor:RX", "", [] ],
[ "esp:RX0", "$serialMonitor:TX", "", [] ], [
"esp:VIN", "ultrasonic1:VCC", "red",
[ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
],
[ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
[ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
```

### CIRCUIT DIAGRAM

]



## **OUTPUT**

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK
Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

### IBM CLOUD OUTPUT :

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