Assignment -4

Python Programming

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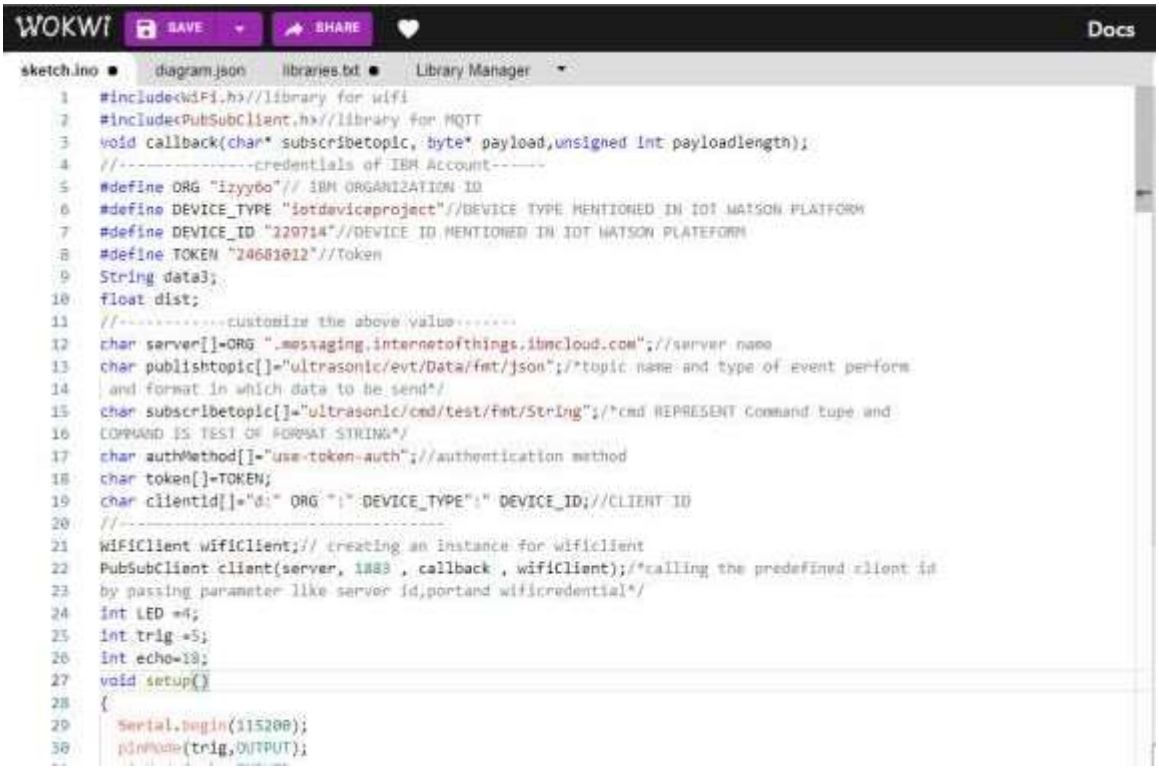
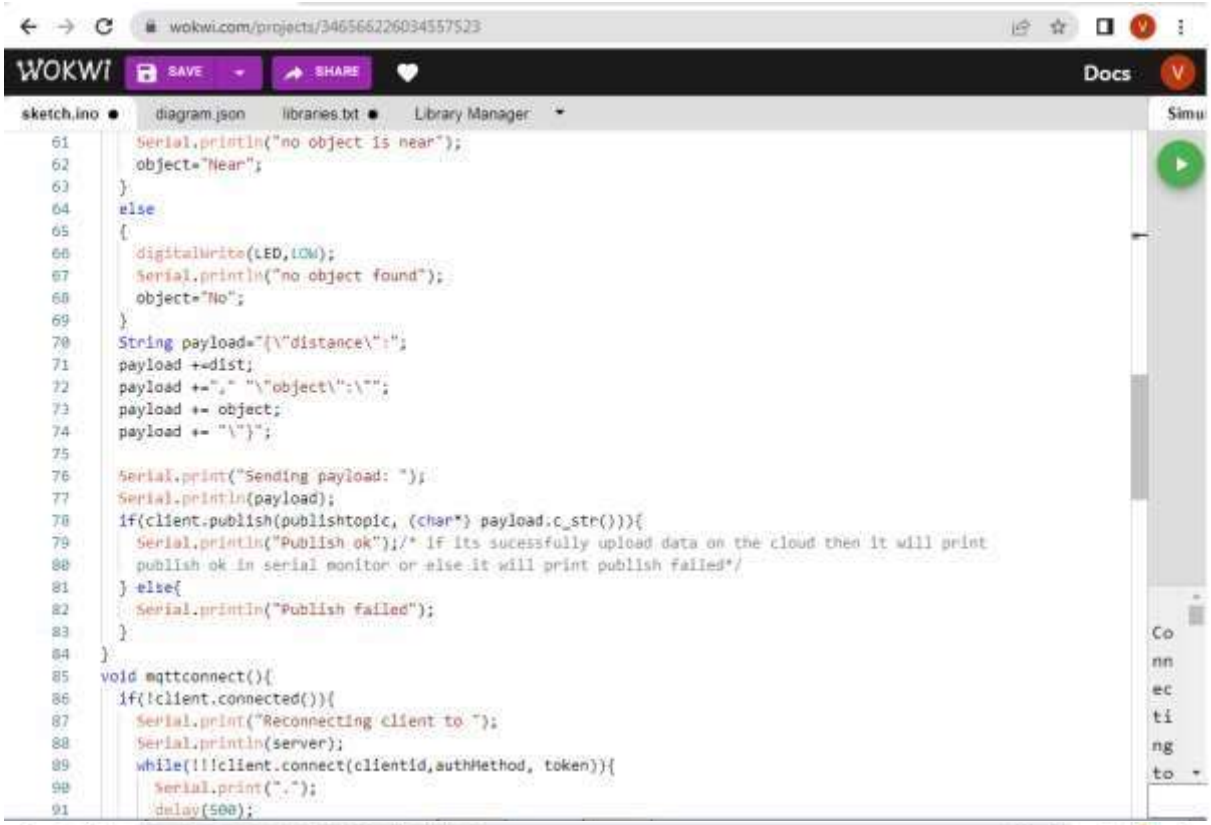
Question-1:

Write code and connections in wokWi for ultrasonic sensor.
Whenever distance is less than 100 cm's send "alert" to IBM cloud and display in device recent events.
Upload document with wokwi share link and images of IBM cloud.

Solution:




wokwi.com/projects/346566226034557523
WOKWI
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Docs
sketch.ino
diagram.json
libraries.txt
Library Manager
Simu
Serial.println("no object is near");
object="Near";
}
else
{
digitalWrite(LED,LOW);
Serial.println("no object found");
object="No";
}
String payload="{\"distance\":";
payload +=dist;
payload +="," "\"object\":\"";
payload += object;
payload += "\"}";
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishtopic, (char*) payload.c_str())){
Serial.println("Publish ok");// If its sucessfully upload data on the cloud then it will print
publish ok in serial monitor or else it will print publish failed*/
} else{
Serial.println("Publish failed");
}
}
void mqttconnect(){
if(!client.connected()){
Serial.print("Reconnecting client to ");
Serial.println(server);
while(!!!client.connect(clientId,authMethod, token)){
Serial.print(".");
delay(500);
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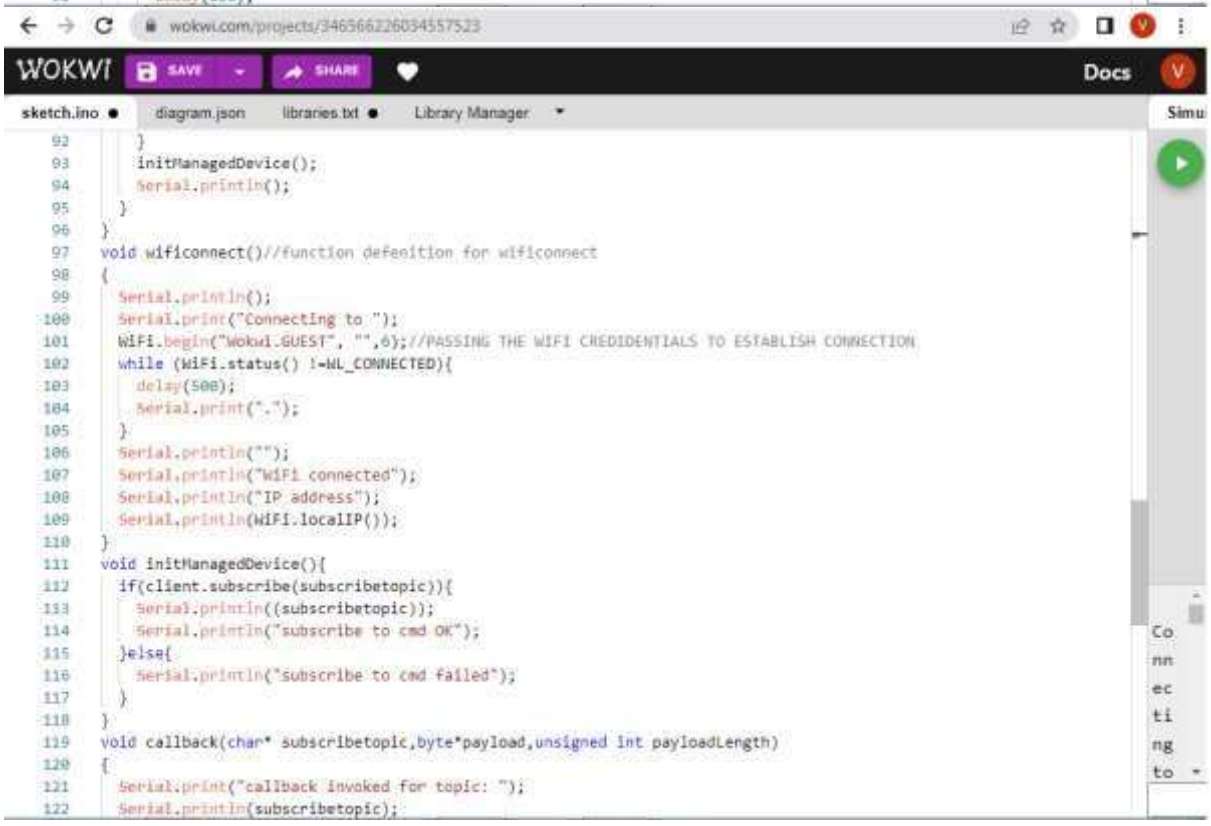
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}
initManagedDevice();
Serial.println();
}
}
void wificonnect()//function defenition for wificonnect
{
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "",6);//PASSING THE WIFI CREDIDENTIALS TO ESTABLISH CONNECTION
while (WiFi.status() !=WL_CONNECTED){
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address");
Serial.println(WiFi.localIP());
}
void initManagedDevice(){
if(client.subscribe(subscribetopic)){
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
}else{
Serial.println("subscribe to cmd failed");
}
}
void callback(char* subscribetopic,byte*payload,unsigned int payloadLength)
{
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
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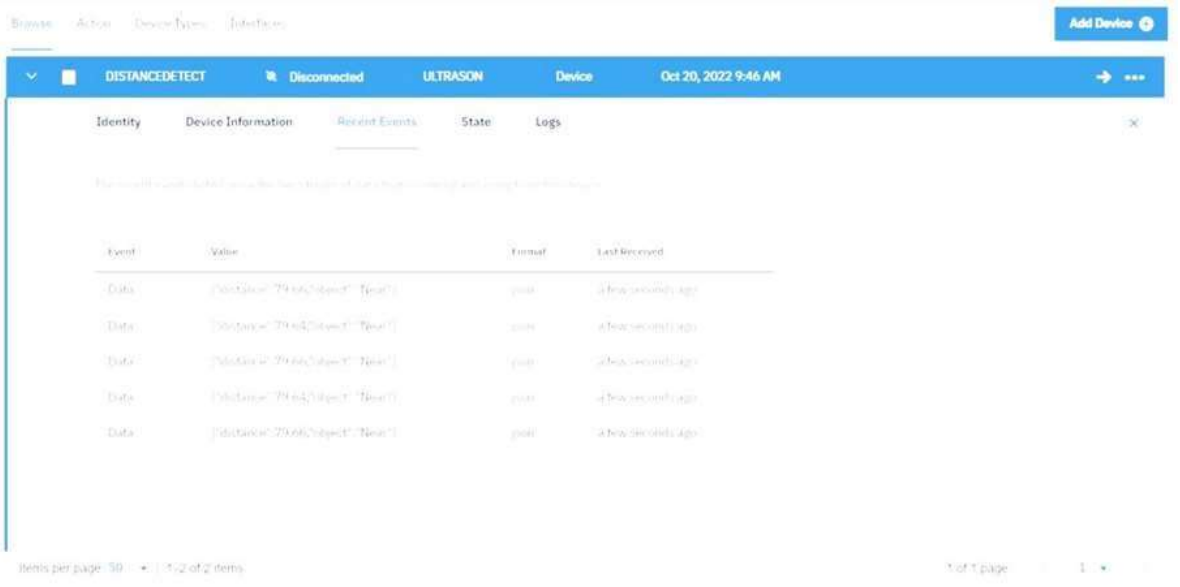
WOKWI SAVE SHARE Doc

sketch.ino ● diagram.json libraries.txt ● Library Manager

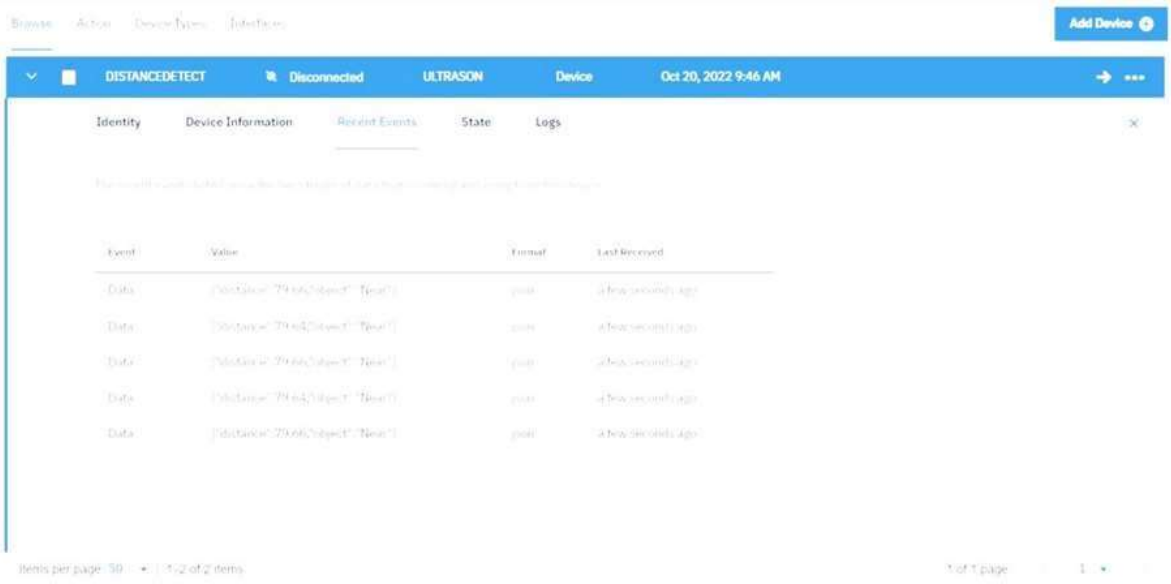
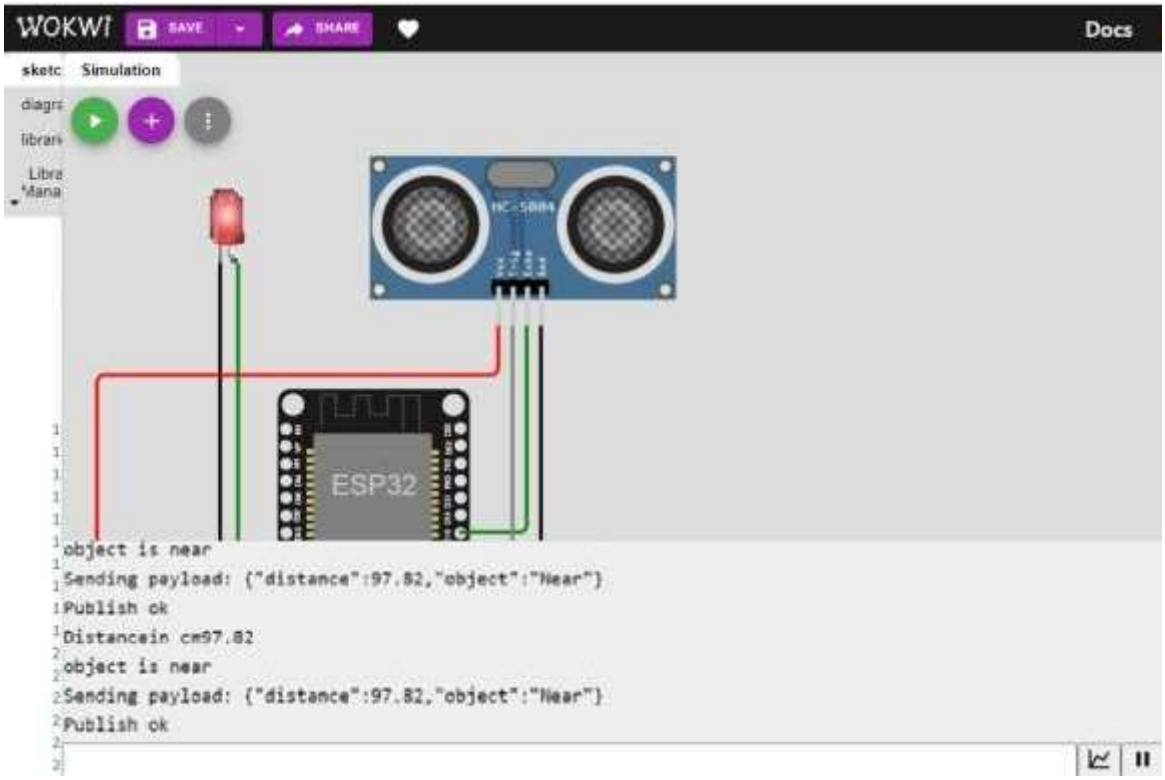
```
123   for(int i=0; i< payloadLength; i++){
124     //Serial.print((char)payload[i]);
125     data3 +=(char)payload[i];
126   }
127   //Serial.println("data: "+ data3);
128   //if(data3=="Near")
129   //{
130   //Serial.println(data3);
131   //digitalWrite(LED,HIGH);
132   //}
133   //else
134   //{
135   //Serial.println(data3);
136   //digitalWrite(LED,LOW);
137   //}
138   data3="";
139 }
```

OUTPUT:

DATA IS SENT TO IBM CLOUD WHEN NO OBJECT IS DETECTED



When no object is detected



When object is detected in ultrasonic detector