ASSIGNMENT-4

| Date | 2 NOVEMBER 2022 |
|---------------|------------------|
| Team ID | PNT2022TMID31693 |
| Name | GOWTHAMAN M |
| Maximum Marks | 2 Marks |

Question1:

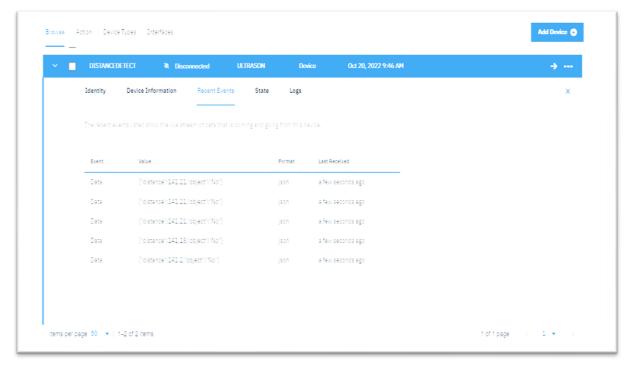
Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100cms send "alert "to IBM cloud and display in device recent events.

CODE:

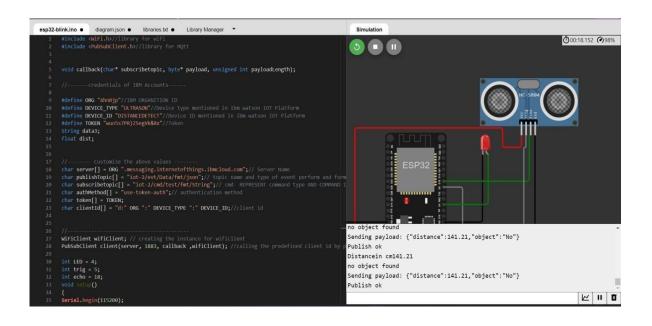
```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt •
                                                 Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

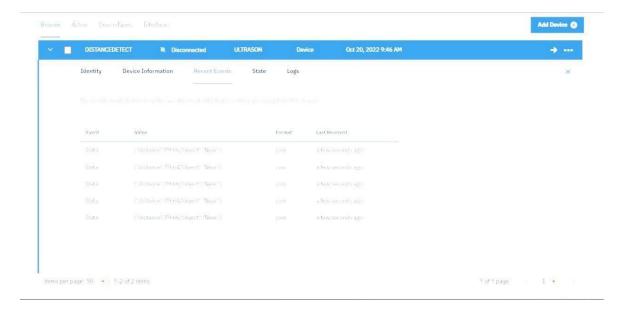
OUTPUT:



Data send to the IBM cloud device when the object is far



Data sent to the IBM Cloud Device when the object is near



When object is near to the ultrasonic sensor

