Assignment -4

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#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
#define ECHO PIN 5
#define TRIG_PIN 4
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "qxzu5g"//IBM ORGANITION ID
#define DEVICE_TYPE "Esp32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "131519"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "1315192956"
                             //Token
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT
command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, NULL ,wifiClient); //calling the predefined
client id by passing parameter like server id, portand wificredential
void setup() // configureing the ESP32
 Serial.begin(115200);
 pinMode(LED_BUILTIN, OUTPUT);
 pinMode(TRIG_PIN, OUTPUT);
 pinMode(ECHO_PIN, INPUT);
 wificonnect();
 mqttconnect();
float readDistanceCM() {
 digitalWrite(TRIG PIN, LOW);
 delayMicroseconds(2);
 digitalWrite(TRIG_PIN, HIGH);
```

```
delayMicroseconds(10);
 digitalWrite(TRIG PIN, LOW);
 int duration = pulseIn(ECHO PIN, HIGH);
 return duration * 0.034 / 2;
}
void loop() {
 digitalWrite(TRIG_PIN, LOW);
 delayMicroseconds(2);
 digitalWrite(TRIG_PIN, HIGH);
 delayMicroseconds(10);
 digitalWrite(TRIG PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  float distance = duration * 0.034 / 2;
  Serial.print("Distance: ");
  Serial.println(distance);
 if(distance <100)</pre>
   Serial.println("Alert");
 else if(distance >100)
   Serial.println("Distance is maintained");
 PublishData(distance);
 delay(1000);
 if (!client.loop()) {
   mqttconnect();
 }
}
/*....retrieving to
Cloud....*/
void PublishData(float distance) {
 mqttconnect();//function call for connecting to ibm
 /*
    creating the String in in form JSon to update the data to ibm cloud
  String payload = "{\"Distance\":";
  payload += distance;
 payload += "," "\"Status\":";
  payload += "\"Alert\"";
  payload += "}";
 Serial.print("Sending payload: ");
  Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
then it will print publish ok in Serial monitor or else it will print publish
failed
  } else {
   Serial.println("Publish failed");
}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
   while (!!!client.connect(clientId, authMethod, token)) {
     Serial.print(".");
     delay(500);
    }
     initManagedDevice();
     Serial.println();
 }
}
void wificonnect() //function defination for wificonnect
  Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
 while (WiFi.status() != WL_CONNECTED) {
    delay(500);
   Serial.print(".");
 }
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
   Serial.println("subscribe to cmd OK");
  } else {
   Serial.println("subscribe to cmd FAILED");
}
```

