# RAJALAKSHMI ENGINEERING COLLEGE

# [Department of computer science and engineering] ASSIGNMENT -04

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TOPIC: Write a code and connections in wokwi for ultrasonic sensor

#### CODE:

```
#include <WiFi.h>
#include <PubSubClient.h> void callback(char*
subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG "92zbfc"
#define DEVICE_TYPE "esp32"
#define DEVICE_ID "12345"
#define TOKEN "12345678" String data3; char server[] = ORG
 ".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/Data/fmt/json"; char subscribetopic[]
= "iot-2/cmd/test/fmt/String"; char authMethod[] = "use-token-
auth"; char token[] = TOKEN; char
clientId[] = "d:" ORG ":" DEVICE_TYPE ":"
DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883,
callback ,wifiClient); const int
trigPin = 5; const int echoPin = 18;
#define SOUND_SPEED 0.034 long
duration; float distance; void setup()
{ Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect(); mqttconnect();
void loop() {
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW); duration
= pulseIn(echoPin, HIGH); distance
= duration * SOUND_SPEED/2;
```

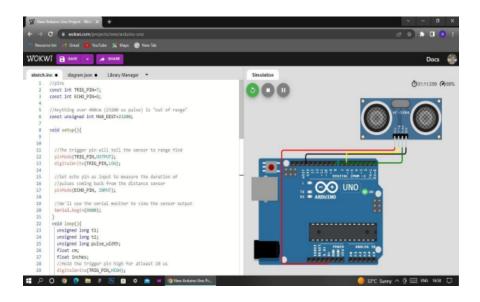
```
Serial.print("Distance (cm): ");
Serial.println(distance); if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000); if
(!client.loop()) {
mqttconnect();
}}
delay(1000)
;}
void PublishData(float dist) { mqttconnect();
String payload = "{\"Distance\":";
payload += dist; payload +=
",\"ALERT!!\":""\"Distance less than
100cms\""; payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*)
payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}}
void mqttconnect() { if
(!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId,
authMethod, token)) {
Serial.print("."); delay(500);
initManagedDevice();
Serial.println();
}}
void wificonnect()
Serial.println();
Serial.print("Connecting to "); WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) { delay(500); Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
```

```
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) { Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
} else {
  Serial.println("subscribe to cmd FAILED");
}}
void callback(char* subscribetopic, byte* payload,
  unsigned int payloadLength) {
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic); for (int i = 0; i
  < payloadLength; i++)
  {
  data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3); data3="";
}</pre>
```

## **WOKWI LINK:**

https://wokwi.com/projects/345395196387656275

## **OUTPUT**:



Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

