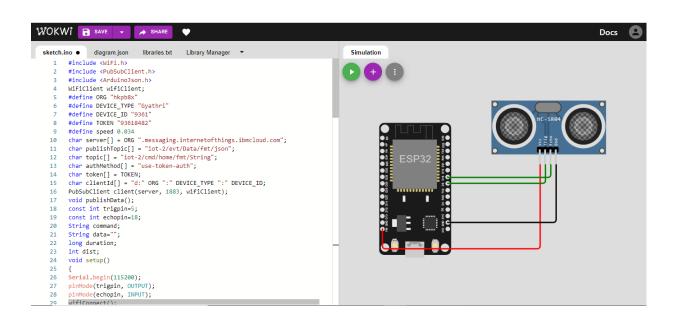
Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "hkpb8x"
#define DEVICE TYPE "Gayathri"
#define DEVICE ID "9361"
#define TOKEN "93618482"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
int dist;
void setup()
{
Serial.begin(115200);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
void loop() {
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
```

```
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(1000);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic)) {
Serial.println(client.subscribe(topic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){</pre>
DynamicJsonDocument doc(1024);
String payload;
doc["Distance Alert:"]=dist;
serializeJson(doc, payload);
delay(3000);
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
} else {
Serial.println("Publish FAILED");
}
}
}
```



Event	Value	Format	Last Received
Data	("Distance Alert:":26)	json	a few seconds ago
Data	{"Distance Alert:":26}	json	a few seconds ago
Data	{"Distance Alert:":26}	json	a few seconds ago
Data	{"Distance Alert:":26}	json	a few seconds ago
Data	{"Distance Alert:":26}	json	a few seconds ago