Project Development Phase Sprint 1

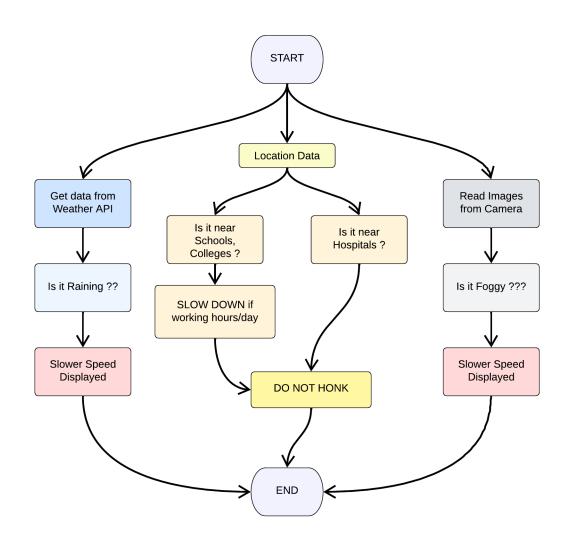
Date	24 October 2022
Team ID	PNT2022TMID41539
Project Name	Project-Signs with Smart Connectivity for Better Road Safety
	Better Road Salety
Maximum marks	8 Marks

Sprint 1:

Sprint Goals:

- 1. Create and initialize accounts in various public APIs like OpenWeather API.
- 2. Write a Python program that outputs results given the inputs like weather and location.

Code Flow:



Program Code:

Weather.py

This is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code
import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
        "temperature" : responseJSON['main']['temp'] - 273.15,
        "weather" : [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in percentage where 10km is
100% and 0km is 0%
    }
    if("rain" in responseJSON):
        returnObject["rain"] = [responseJSON["rain"][key] for key in responseJSON["rain"]]
    return(returnObject)
```

Brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2

```
if(localityInfo["hospitalsNearby"]):
    # hospital zone
    doNotHonk = True
  else:
    if(localityInfo["schools"]["schoolZone"]==False):
      # neither school nor hospital zone
      doNotHonk = False
    else:
      # school zone
      now = [dt.now().hour,dt.now().minute]
      activeTime = [list(map(int, .split(":"))) for in localityInfo["schools"]["activeTime"]]
      doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
  return({
    "speed": finalSpeed,
    "doNotHonk" : doNotHonk
  })
```

UTILITY LOGIC SECTION ENDS

Main.py

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
}
```

USER INPUT SECTION ENDS

MICRO-CONTROLLER CODE STARTS

print(brain.processConditions(myLocation,APIKEY,localityInfo))

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MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT SCHEDULE

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MICRO-CONTROLLER CODE ENDS

Output:

Code Output

{'speed': 40, 'doNotHonk': False}

Image:

