

**Assignment -1**  
Home Automation with Tinkercad

Assignment Date	5 September 2022
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Maximum Marks	2 Marks

**Question:**

Make a home automation with tinkercad, add 2-3 sensors. led. buzzers and make a common code and circuit. multiple detections and alarms should be given.

**Solution:**

**PROGRAM:**

```
#include <Servo.h>
int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const gas_sensor = A1;
int const LDR = A0;
int limit = 400;
long readUltrasonicDistance(int triggerPin, int echoPin)
{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Reads the echo pin, and returns the sound wave travel time in microseconds
    return pulseIn(echoPin, HIGH);
}
Servo servo_7;
void setup()
{
    Serial.begin(9600);           //initialize serial communication
    pinMode(A0, INPUT);           //LDR
    pinMode(A1, INPUT);           //gas sensor
    pinMode(13, OUTPUT);           //connected to relay
    servo_7.attach(7, 500, 2500); //servo motor

    pinMode(8, OUTPUT);           //signal to piezo buzzer
    pinMode(9, INPUT);            //signal to PIR
    pinMode(10, OUTPUT);          //signal to npn as switch
    pinMode(4, OUTPUT);           //Red LED
    pinMode(3, OUTPUT);           //Green LED
}
void loop()
{
    //-----light intensity control-----//
    //-----
    int val1 = analogRead(LDR);
```

```

if (val1 > 500)
{
    digitalWrite(13, LOW);
    Serial.print("Bulb ON = ");
    Serial.print(val1);
}
else
{
    digitalWrite(13, HIGH);
    Serial.print("Bulb OFF = ");
    Serial.print(val1);
}

//-----
//----- light & fan control -----//
//-----
sen2Value = digitalRead(9);
if (sen2Value == 0)
{
    digitalWrite(10, LOW); //npn as switch OFF
    digitalWrite(4, HIGH); // Red LED ON, indicating no motion
    digitalWrite(3, LOW); //Green LED OFF, since no Motion detected
    Serial.print(" || NO Motion Detected ");
}
if (sen2Value == 1)
{
    digitalWrite(10, HIGH); //npn as switch ON
    delay(5000);
    digitalWrite(4, LOW); // RED LED OFF
    digitalWrite(3, HIGH); //GREEN LED ON , indicating motion detected
    Serial.print(" || Motion Detected! ");
}

//-----
// ----- Gas Sensor -----//
//-----
int val = analogRead(gas_sensor); //read sensor value
Serial.print(" | Gas Sensor Value = ");
Serial.print(val); //Printing in serial monitor
//val = map(val, 300, 750, 0, 100);
if (val > limit)
{
    tone(8, 650);
}
delay(300);
noTone(8);

//-----
//----- servo motor -----//
//-----
sen1Value = 0.01723 * readUltrasonicDistance(6, 6);
if (sen1Value < 100)
{
    servo_7.write(90);
    Serial.print(" || Door Open! ; Distance = ");
    Serial.print(sen1Value);
    Serial.print("\n");
}
else
{

```

```

servo_7.write(0);
Serial.print("  || Door Closed! ; Distance = ");
Serial.print(sen1Value);
Serial.print("\n");
}
delay(10); // Delay a little bit to improve simulation performance
}

```

## OUTPUT:

