

# Built a web application using Node-Red

The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains various icons for navigation. The main content area displays a table of devices. The first device, 'Agriculture', is selected, and its details are shown in a modal window. The details include:

- Device ID:** Agriculture
- Device Type:** smart\_farm
- Date Added:** Nov 5, 2022 11:50 AM
- Added By:** 511919106010@smartinternz.com
- Connection Status:** Disconnected
- Last Connected:** Nov 6, 2022 1:17 PM
- Client Address:** 216.246.119.62 Insecure
- Duration:** a minute
- Data Transferred:** 1.7 KB

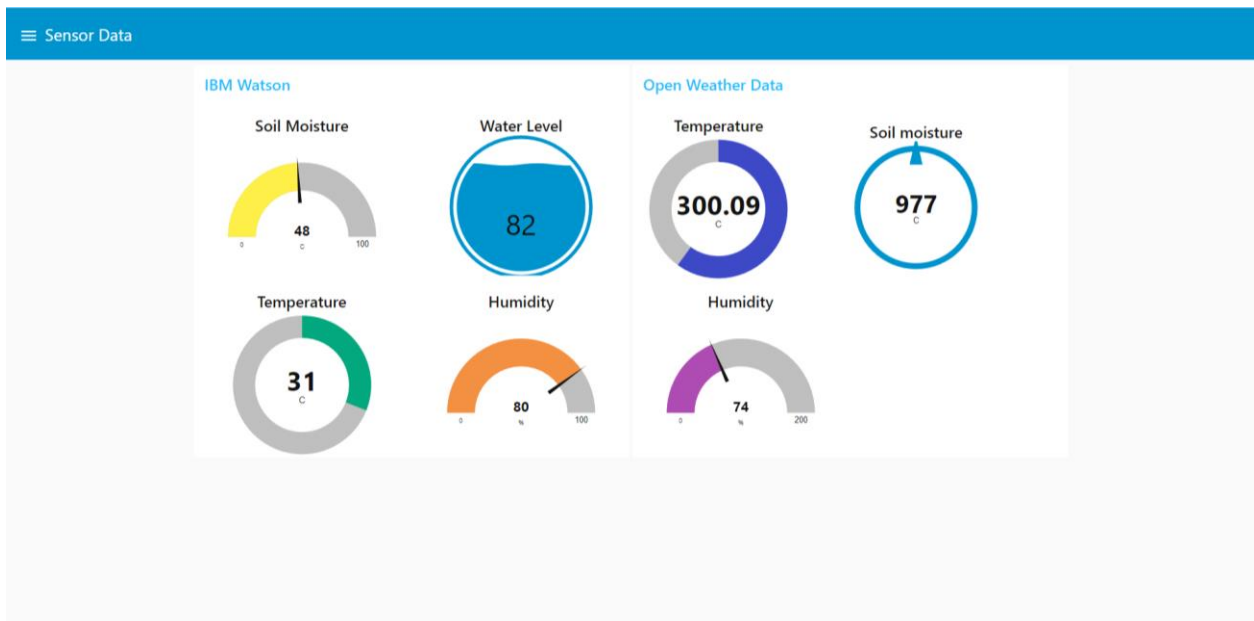
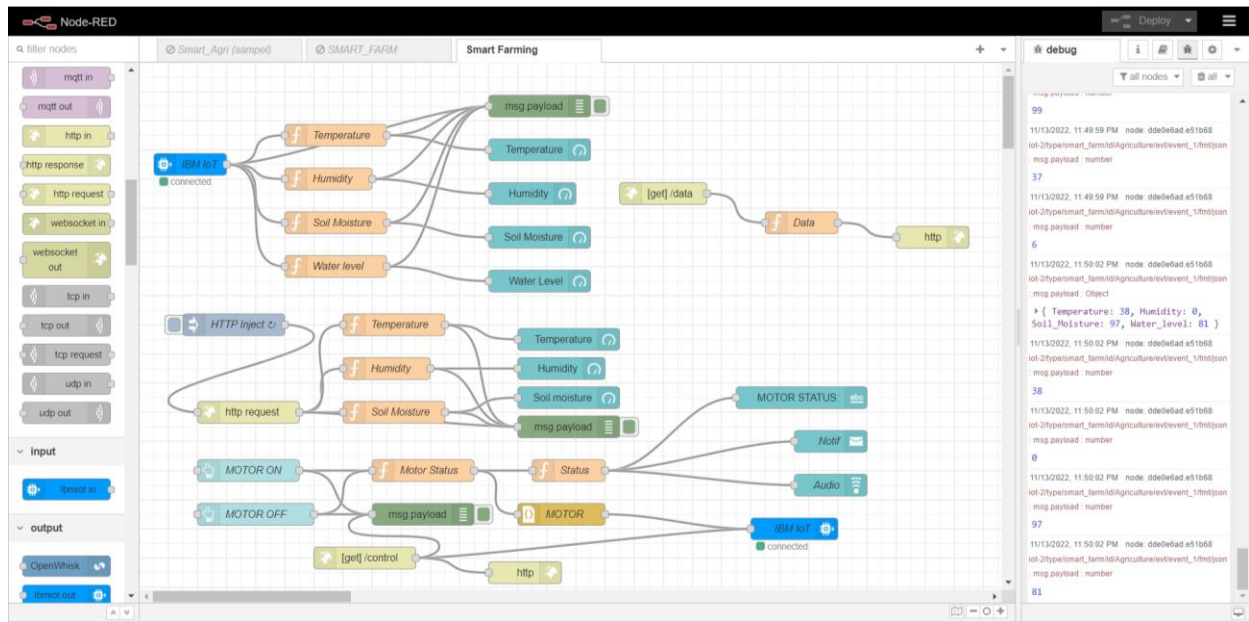
Below the modal, a table lists other devices:

| Device ID     | Status       | Device Type | Class ID | Date Added          | Descriptive Location |
|---------------|--------------|-------------|----------|---------------------|----------------------|
| Weatherid     | Disconnected | Weather     | Device   | Oct 6, 2022 9:25 AM |                      |
| agricultureid | Disconnected | smart_agri  | Device   |                     | 1 Simulation running |

The screenshot shows the IBM Watson IoT Platform interface, focusing on the 'Recent Events' tab for the 'smart\_farm' device. The events are listed in a table:

| Event   | Value  | Format | Last Received     |
|---------|--|--------|-------------------|
| event_1 | {"Temperature":44,"Humidity":11,"Soil_Moisture":...} | json   | a few seconds ago |
| event_1 | {"Temperature":47,"Humidity":77,"Soil_Moisture":...} | json   | a few seconds ago |
| event_1 | {"Temperature":42,"Humidity":74,"Soil_Moisture":...} | json   | a few seconds ago |
| event_1 | {"Temperature":90,"Humidity":7,"Soil_Moisture":...}  | json   | a few seconds ago |
| event_1 | {"Temperature":87,"Humidity":86,"Soil_Moisture":...} | json   | a few seconds ago |

Below the table, it indicates '1 Simulation running'.



Motor Control

MOTOR ON

MOTOR OFF

MOTOR STATUS:

OFF