

ASSIGNMENT-4

Date	30 October 2022
Team ID	PNT2022TMID39619
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Maximum Marks	2 Marks

Problem Statement:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

CODE :

```
1 #include <WiFi.h> //library for wifi
2 #include <PubSubClient.h> //library for mqtt
3
4
5 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
6
7 //----- credentials of IBM Accounts -----
8
9 #define ORG "4h0u1p" //IBM ORG/UNITID ID
10 #define DEVICE_TYPE "ULTRASONIC" //Device type mentioned in the Watson IoT Platform
11 #define DEVICE_ID "DISTANCEDETECT" //Device ID mentioned in the Watson IoT Platform
12 #define TOKEN "w00s7PRj25egWdta" //Token
13 String data3;
14 float dist;
15
16
17 //----- Customize the above values -----
18 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
19 char publishTopic[] = "iot-2/evt/data/rst/json"; // Topic name and type of event perform and format in which data to be send
20 char subscribetopic[] = "iot-2/cmd/test/rst/string"; // cmd REPRESENT command type AND COMMAND IS TEST OR COMPAT STRING
21 char authMethod[] = "one-token-auth"; // authentication method
22 char token[] = TOKEN;
23 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID //client id
24
25
26 //-----
27 WiFiClient wifiClient; // creating the instance for wifiClient
28 PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by passing parameter like server id,port and wifi credentials
29
30 int LED = 4;
31 int trig = 5;
32 int echo = 18;
33 void setup()
34 {
35   Serial.begin(115200);
```

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```

36 pinMode(trig,OUTPUT);
37 pinMode(echo,INPUT);
38 pinMode(LED, OUTPUT);
39 delay(10);
40 wificonnect();
41 mqttconnect();
42 }
43 void loop()// Recursive Function
44 {
45
46     digitalWrite(trig,LOW);
47     digitalWrite(trig,HIGH);
48     delayMicroseconds(10);
49     digitalWrite(trig,LOW);
50     float dur = pulseIn(echo,HIGH);
51     float dist = (dur * 0.0343)/2;
52     Serial.print ("Distance in cm");
53     Serial.println(dist);
54
55
56     PublishData(dist);
57     delay(1000);
58     if (!client.loop()) {
59         mqttconnect();
60     }
61 }
62
63
64
65 /*.....Retrieving to Cloud.....*/
66
67 void PublishData(float dist) {
68     mqttconnect();//function call for connecting to ibm
69     /*
70     |   creating the String in in form JSON to update the data to ibm cloud

```

```

70     |   creating the String in in form JSON to update the data to ibm cloud
71     */
72     String object;
73     if (dist < 100)
74     {
75         digitalWrite(LED,HIGH);
76         Serial.println("object is near");
77         object = "Near";
78     }
79     else
80     {
81         digitalWrite(LED,LOW);
82         Serial.println("no object found");
83         object = "No";
84     }
85
86     String payload = "{\"distance\":";
87     payload += dist;
88     payload += "," " \"object\":";
89     payload += object;
90     payload += "\"}";
91
92
93     Serial.print("Sending payload: ");
94     Serial.println(payload);
95
96
97
98

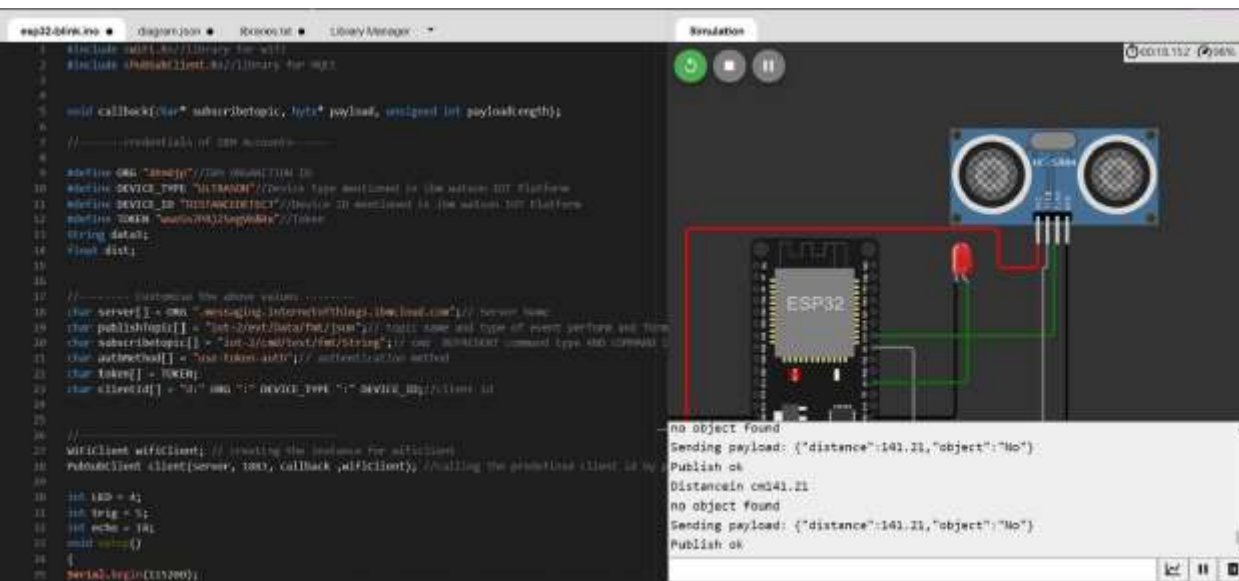
```

```
99
100 if (client.publish(publishTopic, (char*) payload.c_str())) {
101     Serial.println("Publish ok");// If it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
102 } else {
103     Serial.println("Publish failed");
104 }
105
106 void mqttconnect() {
107     if (!client.connected()) {
108         Serial.print("Reconnecting client to ");
109         Serial.println(server);
110         while (!client.connect(clientId, authmethod, token)) {
111             Serial.print(".");
112             delay(500);
113         }
114
115         initManagedDevice();
116         Serial.println();
117     }
118 }
119 void wificonnect() //function definition for wificonnect
120 {
121     Serial.println();
122     Serial.print("connecting to ");
123
124     WiFi.begin("Wokwi-ESP32", ""); //passing the wifi credentials to establish the connection
125     while (WiFi.status() != WL_CONNECTED) {
126         delay(500);
127         Serial.print(".");
128     }
129     Serial.println("");
130     Serial.println("wifi connected");
131     Serial.println("IP address: ");
132     Serial.println(WiFi.localIP());
```

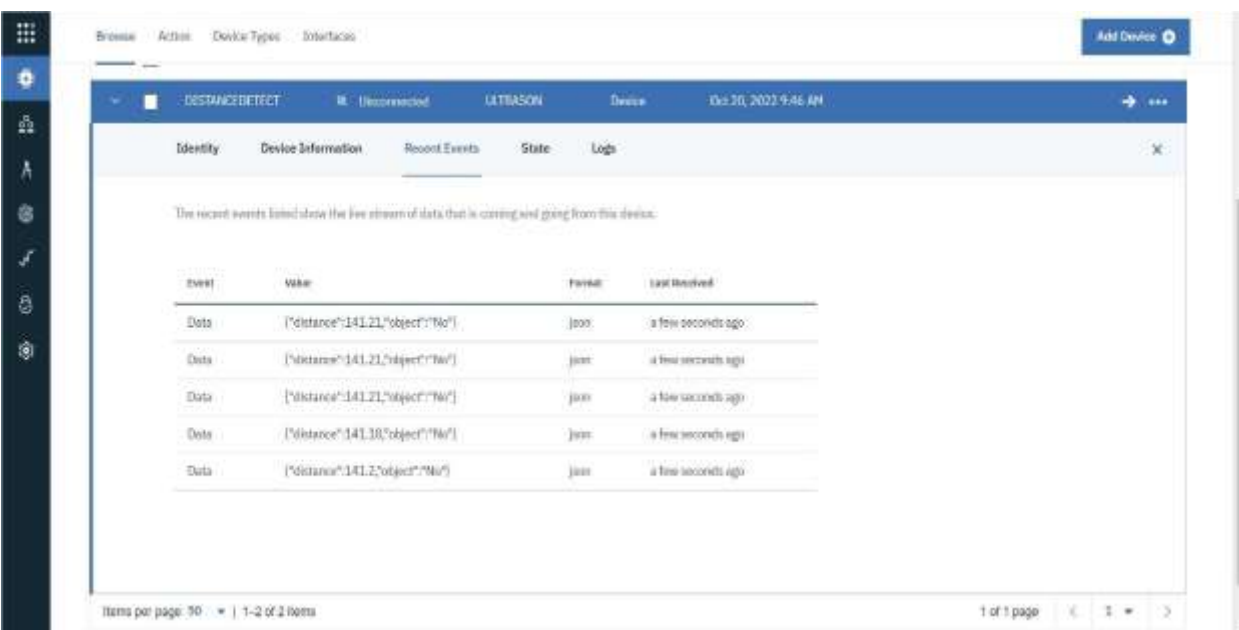
```
123
124   WiFi.begin("wokwi-GUEST", ""); //passing the wifi credentials to establish the connection
125   while (WiFi.status() != WL_CONNECTED) {
126       delay(500);
127       Serial.print(".");
128   }
129   Serial.println("");
130   Serial.println("WiFi connected");
131   Serial.println("IP address: ");
132   Serial.println(WiFi.localIP());
133 }
134
135 void initManagedDevice() {
136     if (client.subscribe(subscribetopic)) {
137         Serial.println(subscribetopic);
138         Serial.println("subscribe to cmd OK");
139     } else {
140         Serial.println("subscribe to cmd FAILED");
141     }
142 }
143
144 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145 {
146     Serial.print("callback invoked for topic: ");
147     Serial.println(subscribetopic);
148     for (int i = 0; i < payloadLength; i++) {
149         //Serial.print((char)payload[i]);
150         data3 += (char)payload[i];
151     }
152 }
153
154 // Serial.println("data: "+ data3);
155 // if(data3=="Near")
156 // {
157 // Serial.println(data3);
158 // }
```

```
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142 }
143
144 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145 {
146
147     Serial.print("callback invoked for topic: ");
148     Serial.println(subscribetopic);
149     for (int i = 0; i < payloadLength; i++) {
150         //Serial.print((char)payload[i]);
151         data3 += (char)payload[i];
152     }
153
154     // Serial.println("data: "+ data3);
155     // if(data3=="Near")
156     // {
157     // Serial.println(data3);
158     // digitalWrite(LED,HIGH);
159
160     // }
161
162     // else
163     // {
164     // Serial.println(data3);
165     // digitalWrite(LED,LOW);
166
167     // }
168     data3="";
169
170
171 }
```

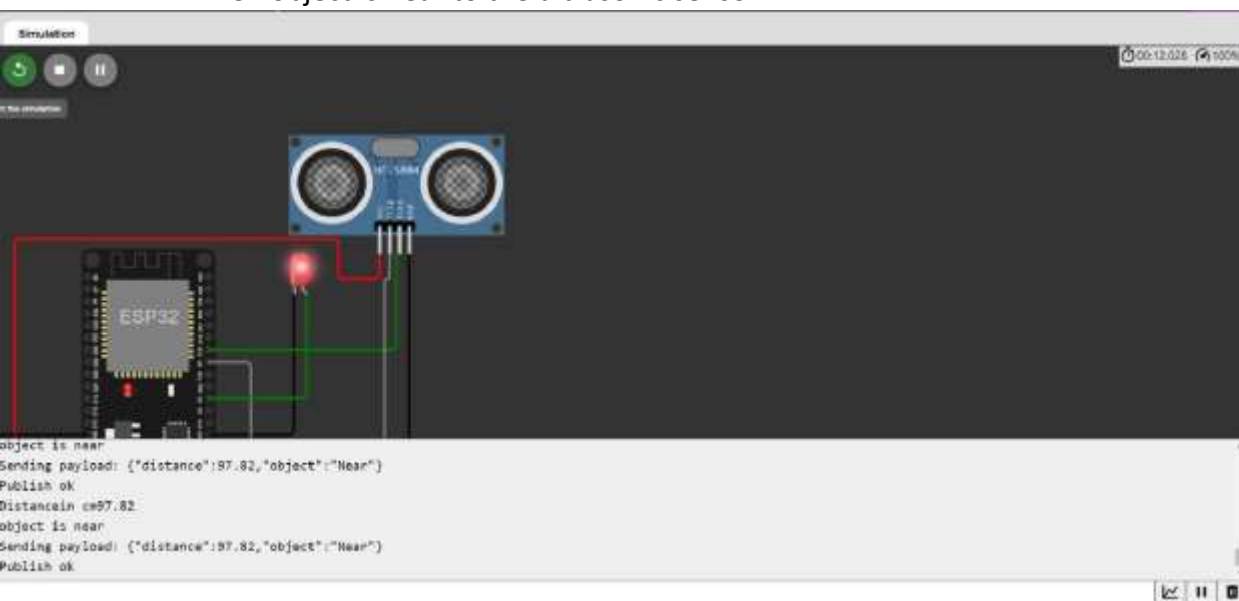
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near