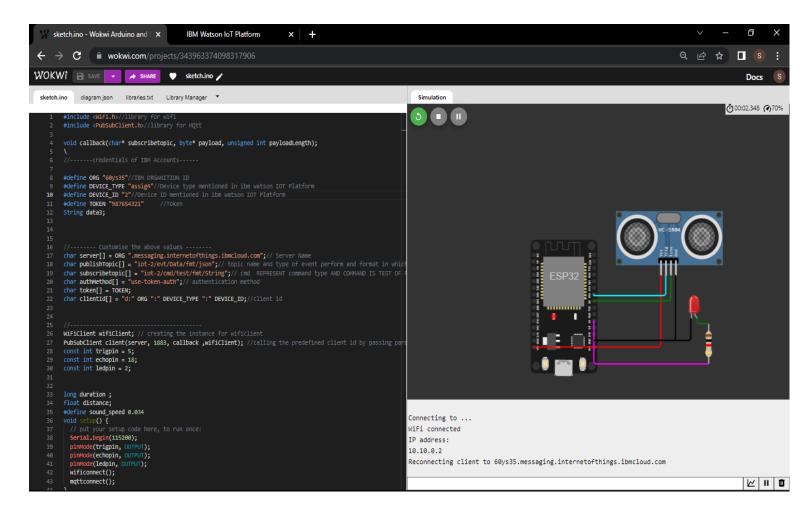
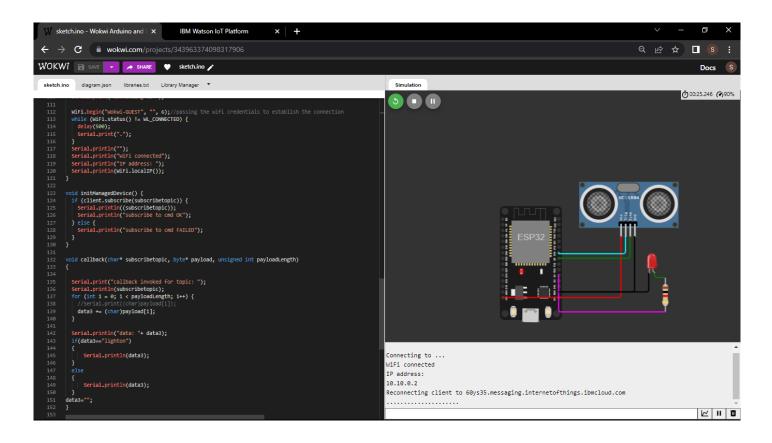
## ASSIGNMENT - 04

- i. Write code and connection in Wowki for ultrasonic sensor.
- ii. Whenever distance is less than 100 cm send "Alert" to IBM cloud and display in device recent events.

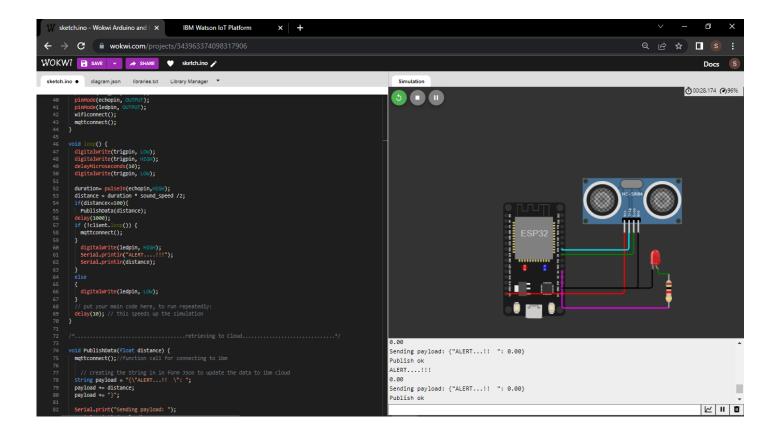
Step 1. Completed to build Circuit and run program.

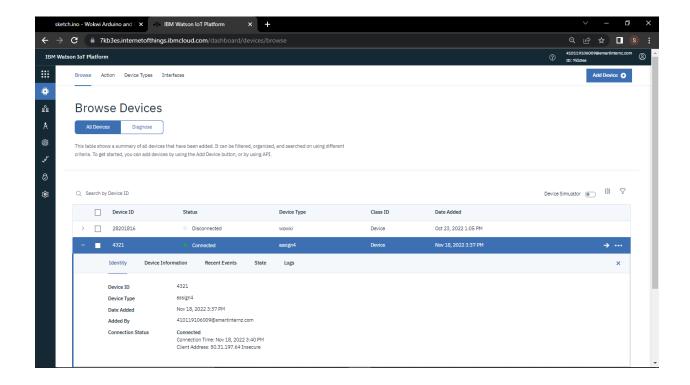




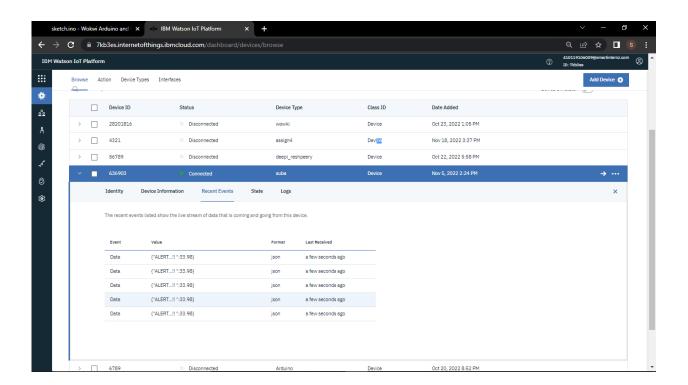
Step 2. Output in WOWKI

(When Distance is below 100 cm send alert to user)





Step 3.Output in IBM CLOUD (Watson Platform)



## PROGRAM:

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MOtt
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "60ys35"//IBM ORGANITION ID
#define DEVICE_TYPE "assign4"//Device type mentioned in ibm watson IOT Platform
#define DEVICE ID "4321"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "0987654321" //Token
String data3;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
//----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined
client id by passing parameter like server id, portand wificredential
const int trigpin = 5;
const int echopin = 18;
const int ledpin = 2;
long duration ;
float distance;
#define sound_speed 0.034
void setup() {
  // put your setup code here, to run once:
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, OUTPUT);
  pinMode(ledpin, OUTPUT);
 wificonnect();
  mqttconnect();
}
void loop() {
  digitalWrite(trigpin, LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin, LOW);
```

```
duration= pulseIn(echopin, HIGH);
  distance = duration * sound speed /2;
  if(distance<=100){</pre>
   PublishData(distance);
  delay(1000);
  if (!client.loop()) {
   mqttconnect();
  }
   digitalWrite(ledpin, HIGH);
   Serial.println("ALERT....!!!");
   Serial.println(distance);
  }
 else
   digitalWrite(ledpin, LOW);
  }
 // put your main code here, to run repeatedly:
 delay(10); // this speeds up the simulation
/*.....retrieving to
Cloud.....*/
void PublishData(float distance) {
  mqttconnect();//function call for connecting to ibm
   // creating the String in in form JSon to update the data to ibm cloud
  String payload = "{\"ALERT...!! \": ";
  payload += distance;
  payload += "}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish ok");// if it sucessfully upload data on the cloud
then it will print publish ok in Serial monitor or else it will print publish
failed
  } else {
   Serial.println("Publish failed");
void mqttconnect() {
  if (!client.connected()) {
   Serial.print("Reconnecting client to ");
   Serial.println(server);
   while (!!!client.connect(clientId, authMethod, token)) {
     Serial.print(".");
     delay(500);
   }
```

```
initManagedDevice();
     Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
  Serial.println();
  Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
 while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {</pre>
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
  if(data3=="lighton")
  {
      Serial.println(data3);
  }
 else
      Serial.println(data3);
data3="";
}
```