FNK202121DRAD1042058

```
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "ki82qi"
#define DEVICE_TYPE "athithiya"
#define DEVICE_ID "athithiya123"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/athithiya/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
```

#include <WiFi.h>

String command;

```
String data="";
long duration;
float dist;

void setup()
{
   Serial.begin(115200);
   pinMode(led, OUTPUT);
   pinMode(trigpin, OUTPUT);
   pinMode(echopin, INPUT);
   wifiConnect();
   mqttConnect();
}

void loop() {
   bool isNearby = dist < 100;
   digitalWrite(led, isNearby);
   publishData();
   delay(500);</pre>
```

```
if (!client.loop()) {
    mqttConnect();
}

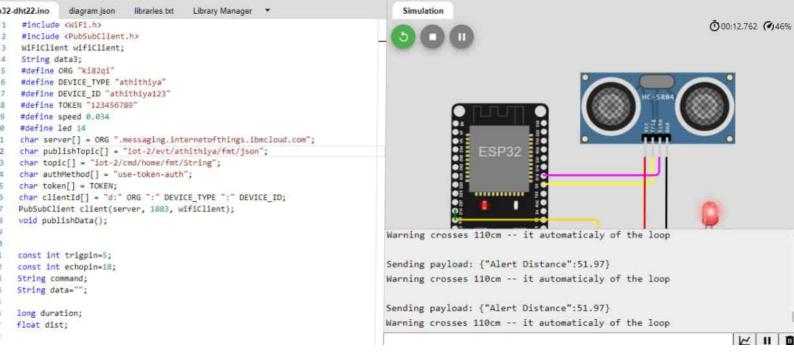
void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
}

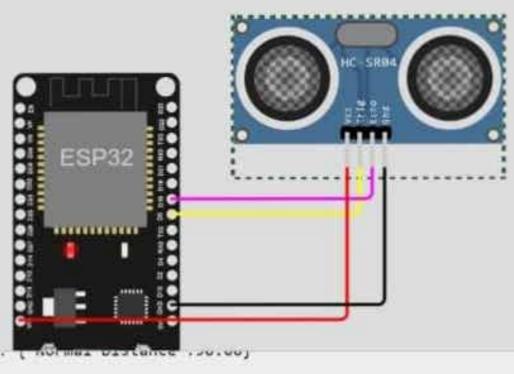
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
```

```
Serial.println();
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
   // Serial.println(client.subscribe(topic));
   Serial.println("IBM subscribe to cmd OK");
 } else {
   Serial.println("subscribe to cmd FAILED");
 }
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
   String payload = "{\"Alert Distance\":";
   payload += dist;
```

```
String payload = "{\"Alert Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
 digitalWrite(led,HIGH);
}
if(dist>101 && dist<111){
String payload = "{\"Normal Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
}
```





Publish OK

Sending payload: {"Normal Distance":89.95}

Publish OK

Sending payload: {"Normal Distance":89.95}

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