Assignment 4 Wokwi Assignment

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| Date | 05-11-2022 |
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| Student Roll number | 2019PITEC140 |
| Maximum Marks | 2 Marks |

**Assignment Question:**

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Wokwi link : https://wokwi.com/projects/347473999736865364

#include <WiFi.h>//library for wifi

#include <PubSubClient.h>//library for MQtt

#define ECHO\_GPIO 12

#define TRIGGER\_GPIO 13

#define MAX\_DISTANCE\_CM 100 // Maximum of 5 meters #include "Ultrasonic.h"

Ultrasonic ultrasonic(13, 12); int distance;

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "kizp10"//IBM ORGANITION ID

#define DEVICE\_TYPE "IOTdevice"//Device type mentioned in ibm watson IOT Platform #define DEVICE\_ID "1234567890"//Device ID mentioned in ibm watson IOT Platform #define TOKEN "1234567890" //Token

String data3; float h, t;

//-------- Customise the above values --------

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send

char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING

char authMethod[] = "use-token-auth";// authentication method char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;//client id

//-- - - - - - --

WiFiClient wifiClient; // creating the instance for wificlient

PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

void setup()// configureing the ESP32

{

**Serial**.begin(115200); delay(10); **Serial**.println(); wificonnect(); mqttconnect();

}

void loop()// Recursive Function

{

distance = ultrasonic.read(CM); if (distance < 100) { **Serial**.print("Distance in CM: "); **Serial**.println(distance); PublishData(distance); delay(1000);

if (!client.loop()) { mqttconnect();

}

}

delay(1000);

}

/\*.....................................retrieving to Cloud \*/

void PublishData(float temp) { mqttconnect();//function call for connecting to ibm

/\*

creating the String in in form JSon to update the data to ibm cloud

\*/

String payload = "{\"Alert Distance:\":"; payload += temp;

payload += "}";

**Serial**.print("Sending payload: ");

**Serial**.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) {

**Serial**.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed

} else {

**Serial**.println("Publish failed");

}

}

void mqttconnect() {

if (!client.connected()) { **Serial**.print("Reconnecting client to "); **Serial**.println(server);

while (!!!client.connect(clientId, authMethod, token)) {

**Serial**.print("."); delay(500);

}

initManagedDevice();

**Serial**.println();

}

void wificonnect() //function defination for wificonnect

{

**Serial**.println(); **Serial**.print("Connecting to ");

WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection

while (WiFi.status() != WL\_CONNECTED) { delay(500);

**Serial**.print(".");

}

**Serial**.println(""); **Serial**.println("WiFi connected"); **Serial**.println("IP address: "); **Serial**.println(WiFi.localIP());

}

void initManagedDevice() {

if (client.subscribe(subscribetopic)) { **Serial**.println((subscribetopic)); **Serial**.println("subscribe to cmd OK");

} else {

**Serial**.println("subscribe to cmd FAILED");

}

}

void callback(char\* subscribetopic, byte\* payload, unsigned int payloadLength)

{

**Serial**.print("callback invoked for topic: ");

**Serial**.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {

//Serial.print((char)payload[i]); data3 += (char)payload[i];

}

**Serial**.println("data: " + data3); if (data3 == "lighton")

{

**Serial**.println(data3);

else

{

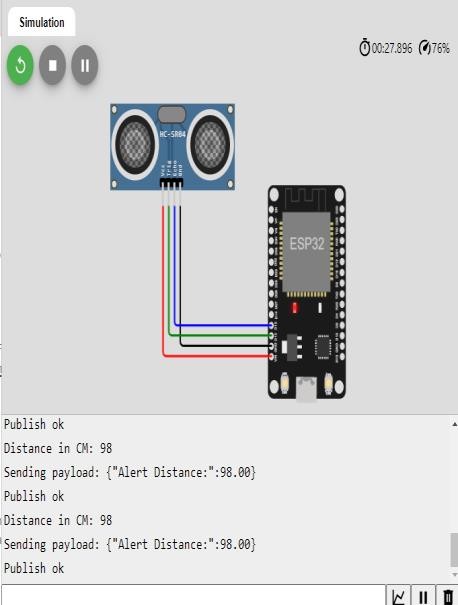
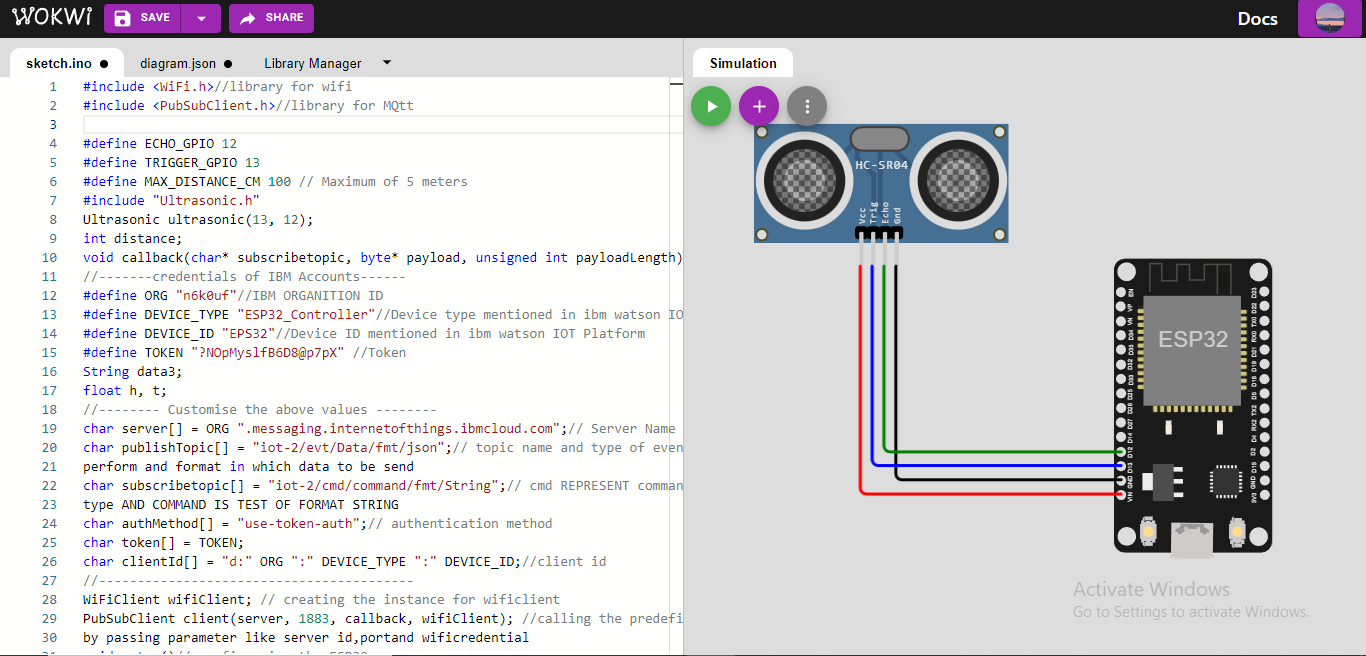
**Serial**.println(data3);

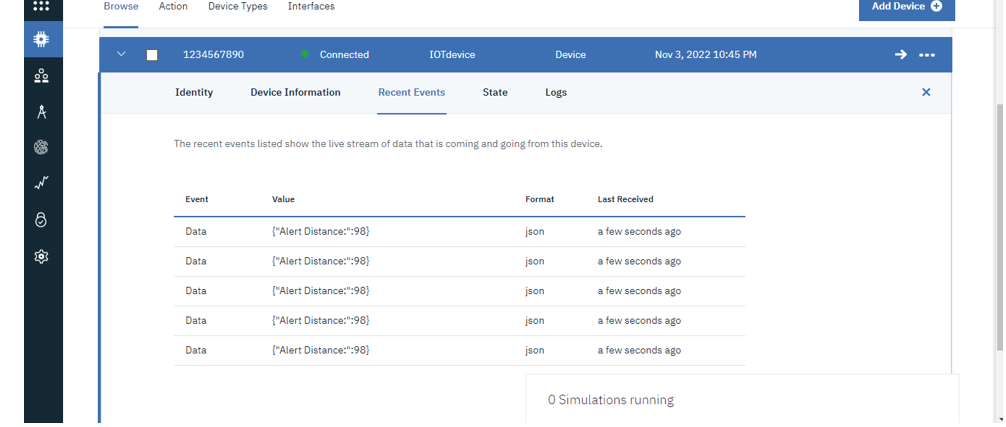
}

data3 = "";

}

When the distance is less than 100cm the alert is not sent to the IBM cloud





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