|  |
| --- |
| #include <Servo.h> |
|  |  |
|  | int output1Value = 0; |
|  | int sen1Value = 0; |
|  | int sen2Value = 0; |
|  | int const gas\_sensor = A1; |
|  | int const LDR = A0; |
|  | int limit = 400; |
|  |  |
|  | long readUltrasonicDistance(int triggerPin, int echoPin) |
|  | { |
|  | pinMode(triggerPin, OUTPUT); |
|  | digitalWrite(triggerPin, LOW); |
|  | delayMicroseconds(2); |
|  | digitalWrite(triggerPin, HIGH); |
|  | delayMicroseconds(10); |
|  | digitalWrite(triggerPin, LOW); |
|  | pinMode(echoPin, INPUT); |
|  | return pulseIn(echoPin, HIGH); |
|  | } |
|  |  |
|  | Servo servo\_7; |
|  |  |
|  | void setup() |
|  | { |
|  | Serial.begin(9600); |
|  | pinMode(A0, INPUT); |
|  | pinMode(A1,INPUT); |
|  | pinMode(13, OUTPUT); |
|  | servo\_7.attach(7, 500, 2500); |
|  |  |
|  | pinMode(8,OUTPUT); |
|  | pinMode(9, INPUT); |
|  | pinMode(10, OUTPUT); |
|  | pinMode(4, OUTPUT); |
|  | pinMode(3, OUTPUT); |
|  | } |
|  |  |
|  | void loop() |
|  | { |
|  |  |
|  |  |
|  | int val1 = analogRead(LDR); |
|  | if (val1 > 500) |
|  | { |
|  | digitalWrite(13, LOW); |
|  | Serial.print("Bulb ON = "); |
|  | Serial.print(val1); |
|  | } |
|  | else |
|  | { |
|  | digitalWrite(13, HIGH); |
|  | Serial.print("Bulb OFF = "); |
|  | Serial.print(val1); |
|  | } |
|  | sen2Value = digitalRead(9); |
|  | if (sen2Value == 0) |
|  | { |
|  | digitalWrite(10, LOW); |
|  | digitalWrite(4, HIGH); |
|  | digitalWrite(3, LOW); |
|  | Serial.print(" || NO Motion Detected " ); |
|  | } |
|  |  |
|  | if (sen2Value == 1) |
|  | { |
|  | digitalWrite(10, HIGH); |
|  | delay(3000); |
|  | digitalWrite(4, LOW); |
|  | digitalWrite(3, HIGH); |
|  | Serial.print(" || Motion Detected! " ); |
|  | } |
|  | delay(300); |
|  | int val = analogRead(gas\_sensor); |
|  | Serial.print("|| Gas Sensor Value = "); |
|  | Serial.print(val); |
|  | val = map(val, 300, 750, 0, 100); |
|  | if (val > limit) |
|  | { |
|  | tone(8, 650); |
|  | } |
|  | delay(300); |
|  | noTone(8); |
|  |  |
|  |  |
|  | sen1Value = 0.01723 \* readUltrasonicDistance(6, 6); |
|  |  |
|  | if (sen1Value < 100) |
|  | { |
|  | servo\_7.write(90); |
|  | Serial.print(" || Door Open! ; Distance = "); |
|  | Serial.print(sen1Value); |
|  | Serial.print("\n"); |
|  |  |
|  | } |
|  | else |
|  | { |
|  | servo\_7.write(0); |
|  | Serial.print(" || Door Closed! ; Distance = "); |
|  | Serial.print(sen1Value); |
|  | Serial.print("\n"); |
|  | } |
|  | delay(10); |
|  | } |