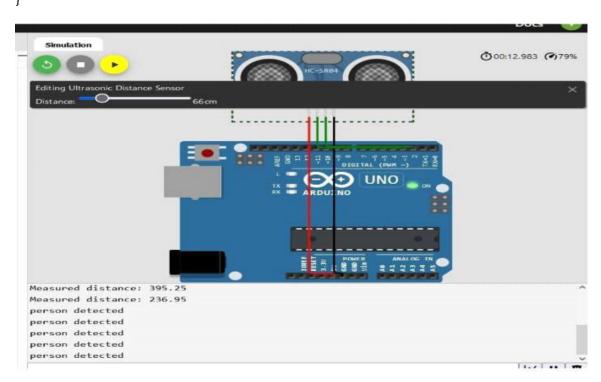
```
Assignment-4
Question-1:
```

Write code and connections in work wifor ultrasonic. Whenever distance is less than 100 cmss end "alert"

```
to ibmcloud and display indevice recent events.
Solution:
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "fkxdqs"
#define deviceType = "Arduino"
#define deviceId = "1200"
#define authMethod ="use-token-auth"#define
authToken = "00000000" void
setup() { Serial.begin(9600);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW); int
duration =pulseIn(ECHO_PIN,HIGH);
return duration * 0.034 / 2;
void loop() { float distance = readDistanceCM();
```

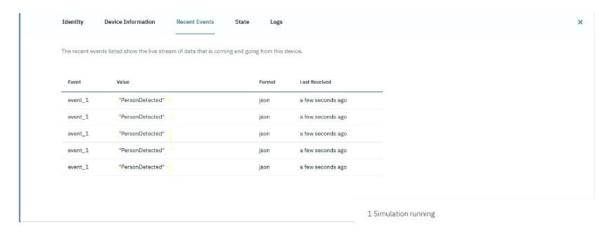
```
if(distance <=
100)
{
Serial.println("person detected ");
}
else{
Serial.print("Measureddistance: ");
Serial.println(readDistanceCM());
}
delay(1000);
</pre>
```



Wokwi Link: https://wokwi.com/projects/346567349532361298

IBM Cloud

Device Recent Events



WOWKI EXECUTIONPART WITH ANOTHER CODE:

```
1 #include "Ultrasonic.h"
 2 Ultrasonic ultrasonic(12, 13);
 3 int distance;
 5 void setup() {
 6 Serial.begin(9600);
 7 pinMode(6, OUTPUT);
10 void loop() {
distance = ultrasonic.read(CM);
Serial.print("Distance in CM: ");
Serial.println(distance);
if(distance<-100)
15
     {
Serial.println("alert!!!!");
16
17
      digitalWrite(4, HIGH);
18
19
20
21 delay(1000);
22 }
                                                                                                 Distance in CM: 50
                                                                                                 alert!!!!
```