

Assignment 4

Assignment Date	29 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud

Solution :

```
#include <WiFi.h>
#include
<PubSubClient.h>
#include
<ArduinoJson.h>

WiFiClient wifiClient;

#define ORG "nhpwjc"
#define DEVICE_TYPE
"raspberrypi"#define
DEVICE_ID "12345"
#define TOKEN "123456789"
#define
speed 0.034
char
server[] =
ORG
".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/Data/fmt/json"; char
topic[] = "iot-2/cmd/home/fmt/String"; char
authMethod[] = "use-token-auth"; char token[] =
TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
```

```

PubSubClient client(server, 1883,
wifiClient); void publishData();

const int
trigpin=5; const int
echopin=18;
String
command;
String
data="";

long
duration;
int
n;
int
dist;

void setup()
{
    Serial.begin(115200
    );
    pinMode(trigpin,
    OUTPUT);
    pinMode(echopin,
    INPUT);
    wifiConnect();
    mqttConnect();
}
void
loop()
{
    publish
    Data();
    delay(500);

    if
    (!client.loo
    p()) {
        mqttConnect(
        );
    }
}

void wifiConnect() {
    Serial.print("Connecting to ");
    Serial.print("Wifi"); WiFi.begin("Wokwi-GUEST",
    "", 6); while (WiFi.status()
    != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {

```

```

    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server); while (!client.connect(clientId,
            authMethod, token)) { Serial.print("."); delay(1000);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        Serial.println(client.subscribe(topic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void
publis
hData(
)
{
    digitalWrite(trigpin, LOW)
    ;
    digitalWrite(trigpin, HIGH
    ); delayMicroseconds(10);
    digitalWrite(trigpin, LOW)
    ;
    duration=pulseIn(echopin, H
    IGH);
    dist=duration*speed/2;
    if(dist<100){
        DynamicJsonDocument
        doc(1024); String
        p
        ayload;
        doc["AlertDistance:"]=d
        ist; serializeJson(doc,
        pay
        load); delay(3000);
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish OK");
        } else {
            Serial.println("Publish FAILED");
        }
    }
}
}

```

