Assignment-4

Assignment Date	17 November 2022
Student Name	SABIHARINI.C
Student Roll Number	95071914076
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for the ultrasonic sensor.

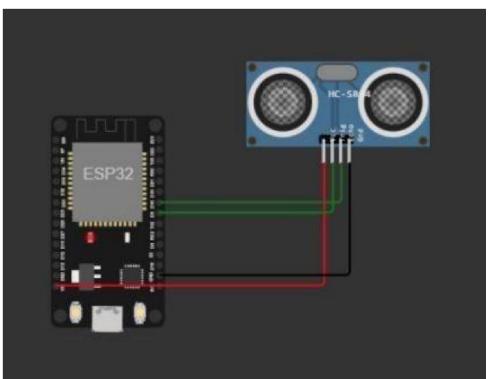
Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

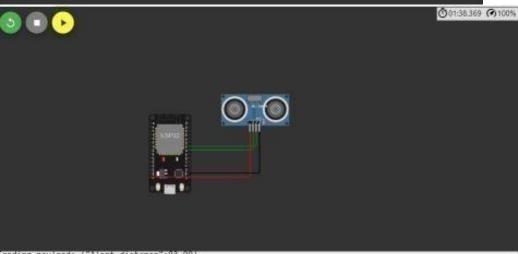
Upload document with wokwi share link and images of IBM cloud

Solution:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "nhpwjc"
#define DEVICE_TYPE "raspberypi"
#define DEVICE_ID "12345"
#define TOKEN "123456789"
#define speed 0.034
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/Data/fmt/json"; char topic[] = "iot-
2/cmd/home/fmt/String"; char authMethod[] = "use-tokenauth";
 char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient); void
publishData();
const int trigpin=5; const
int echopin=18; String
command;
String data="";
long duration;
int dist;
void setup()
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect(); mqttConnect();
} void
loop() {
publishData(); delay(500);
```

```
if (!client.loop()) {
   mqttConnect();
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status()
  != WL_CONNECTED) { delay(500);
   Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
             (!client.connect(clientId,
                                            authMethod,
                                                            token))
    Serial.print("."); delay(1000);
    initManagedDevice();
    Serial.println();
 }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  } else {
   Serial.println("subscribe to cmd FAILED");
 { digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10); digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
if(dist<100){</pre>
   DynamicJsonDocument doc(1024);
                         payload;
    doc["AlertDistance:"]=dist;
    serializeJson(doc, payload); delay(3000);
   Serial.print("\n");
    Serial.print("Sending payload: "); Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
    } else {
     Serial.println("Publish FAILED");
    }
 }
}
```





ending payload: ("Alert distance":93.99)

Publish OK

ending payload: {"Alert distance":93.96}

ublish OK

ending payload: {"Alert distance":93.96}

oublish OK

ending payload: {"Alert distance":93.96}

oblish OK

iending payload: ("Alert distance":93.96)

Publish OK

ending payload: {"Alert distance":93.96}

hublish OK

