## **ASSIGNMENT 4**

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## **Question:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less

than 100 cm send an "alert" to the IBM cloud and display in the device recent events.

## **Solution:**

```
#include <WiFi.h>
#include < PubSubClient.h >
#define ORG "486ral"
#define DEVICE TYPE "IOT"
#define DEVICE ID "id07"
#define TOKEN "123456789"
#define trigpin 5
#define echopin 18
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/data/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, wifiClient);
long duration;
```

```
float dist;
void setup()
Serial.begin(9900);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
publishData();
delay(500);
if (!client.loop())
{
mqttConnect();
}
}
void wifiConnect()
{
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
```

```
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect()
{
if (!client.connected())
{
Serial.print("Reconnecting MQTT client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token))
{
Serial.print(".");
delay(500);
}
Serial.println();
}
}
void publishData()
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
```

```
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*0.034 /2;
if(dist<100)
{
String payload = "{\"Distance\":";
payload += dist;
payload += ",";
payload += "\"Status\":";
payload += "\"Alert\"}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c str()))
{
Serial.println("Publish OK");
}
}
if(dist>100)
{
String payload = "{\"Distance\":";
payload += dist;
```

```
payload += ",";
payload += "\"Status\":";
payload += "\"Normal\"}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
}
```



