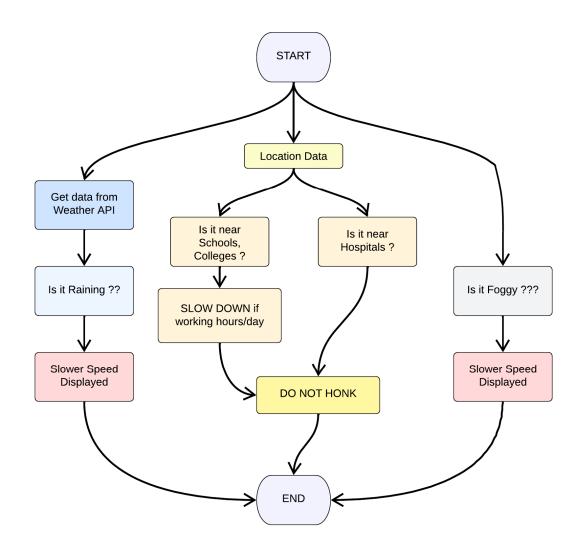
Sprint 01

Signs with Smart Connectivity for Better Road Safety Team ID - PNT2022TMID27042

Sprint Goals:

- 1. Create and initialize accounts in various public APIs like Open Weather API.
- 2. Write a Python program that outputs results given the inputs like weather and location.

Code Flow:



Program Code:

```
> weather.py
```

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code
import requests as reqs
def get(myLocation,APIKEY):
  apiURL = f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
  responseJSON = (reqs.get(apiURL)).json()
  returnObject = {
    "temperature": responseJSON['main']['temp'] - 273.15,
    "weather" : [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
    "visibility": responseJSON['visibility']/100, # visibility in percentage where 10km is 100% and
0km is 0%
  }
  if("rain" in responseJSON):
    returnObject["rain"] = [responseJSON["rain"][key] for key in responseJSON["rain"]]
  return(returnObject)
> brain.py
```

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

#Python code

IMPORT SECTION STARTS

import weather

from datetime import datetime as dt

```
# IMPORT SECTION ENDS
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
  weatherData = weather.get(myLocation,APIKEY)
  finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
  finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
  if(localityInfo["hospitalsNearby"]):
    # hospital zone
    doNotHonk = True
  else:
    if(localityInfo["schools"]["schoolZone"]==False):
      # neither school nor hospital zone
      doNotHonk = False
    else:
      # school zone
      now = [dt.now().hour,dt.now().minute]
      activeTime = [list(map(int,_.split(":"))) for _ in localityInfo["schools"]["activeTime"]]
      doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
  return({
    "speed": finalSpeed,
    "doNotHonk" : doNotHonk
  })
# UTILITY LOGIC SECTION ENDS
> main.py
```

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
  "schools" : {
    "schoolZone": True,
    "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
    },
  "hospitalsNearby": False,
  "usualSpeedLimit": 40 # in km/hr
}
# USER INPUT SECTION ENDS
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
```

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MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT SCHEDULE

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MICRO-CONTROLLER CODE ENDS

Output:

Code Output

{'speed': 40, 'doNotHonk': False}

