Circuit design Neat Densor-Hang | New Tab

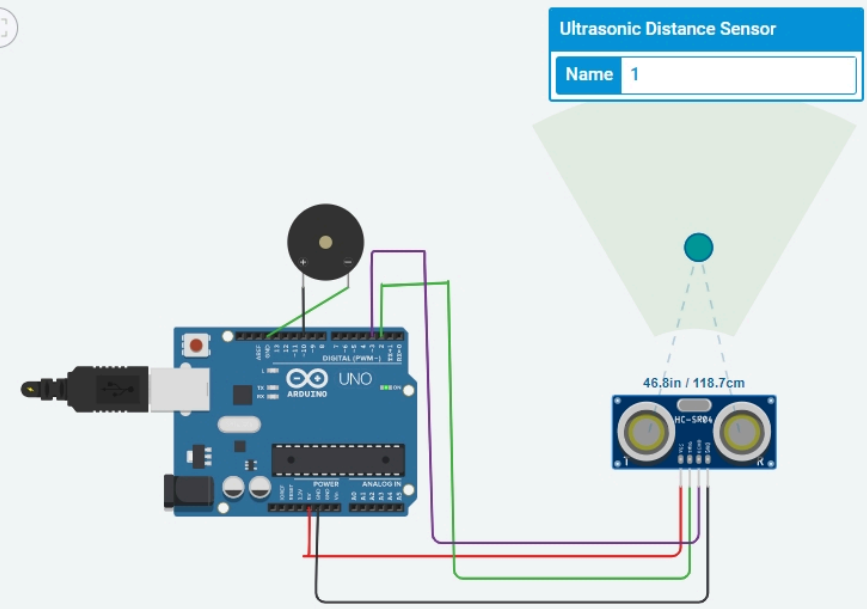
tinkercad.com/things/7kEbDHTdgLC-neat-densor-hango/editel?tenant=circuits

Neat Densor-Hango

All changes saved

Simulator time: 00:01:39

Code | Stop Simulation | Send To



1 (Arduino Uno R3)

```
int trigger_pin=2;
int echo_pin=3;
int buzzer_pin=10;
int time;
int distance;
void setup(){
  Serial.begin(9600);
  pinMode(trigger_pin,OUTPUT);
  pinMode(echo_pin,INPUT);
  pinMode(buzzer_pin,OUTPUT);
}
void loop()
{
  digitalWrite(trigger_pin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigger_pin,LOW);
  time=pulseIn(echo_pin,HIGH);
  distance=(time*0.034)/2;
  if(distance<=10){
```

How the debugger works

1. Add breakpoints by clicking on the line numbers.
2. Hover over the variables while paused to see their value.
3. Use the buttons above to resume simulation or step one line at a time.

Serial Monitor

```
Door Closed
Distance=117
Door Closed
Distance=117
Door Closed
Distance=117
Door Closed
Distance=117
```

Send | Clear

12:26
14-09-2022

Circuit design Neat Densor-H | New Tab

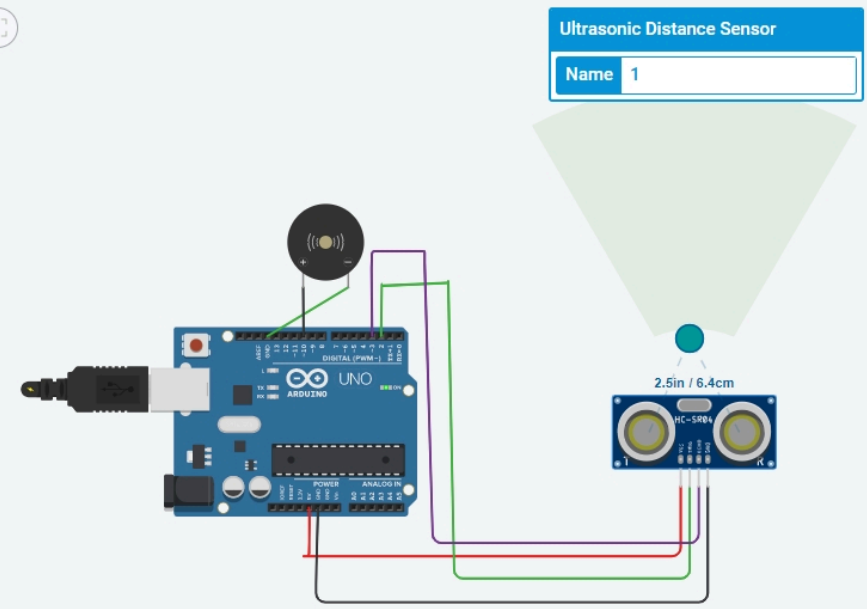
tinkercad.com/things/7kEbDHTdgLC-neat-densor-hango/editel?tenant=circuits

Neat Densor-Hango

All changes saved

Simulator time: 00:02:09

Code | Stop Simulation | Send To



1 (Arduino Uno R3)

```
1  int trigger_pin=2;
2  int echo_pin=3;
3  int buzzer_pin=10;
4  int time;
5  int distance;
6  void setup(){
7    Serial.begin(9600);
8    pinMode(trigger_pin,OUTPUT);
9    pinMode(echo_pin,INPUT);
10   pinMode(buzzer_pin,OUTPUT);
11 }
12 void loop()
13 {
14   digitalWrite(trigger_pin,HIGH);
15   delayMicroseconds(10);
16   digitalWrite(trigger_pin,LOW);
17   time=pulseIn(echo_pin,HIGH);
18   distance=(time*0.034)/2;
19   if(distance<=10){
```

How the debugger works

1. Add breakpoints by clicking on the line numbers.
2. Hover over the variables while paused to see their value.
3. Use the buttons above to resume simulation or step one line at a time.

Serial Monitor

```
Door Open
Distance=6
Door Open
Distance=6
Door Open
Distance=6
Door Open
Distance=6
```

Send | Clear

12:27
14-09-2022

Circuit design Neat Densor-Hang | New Tab

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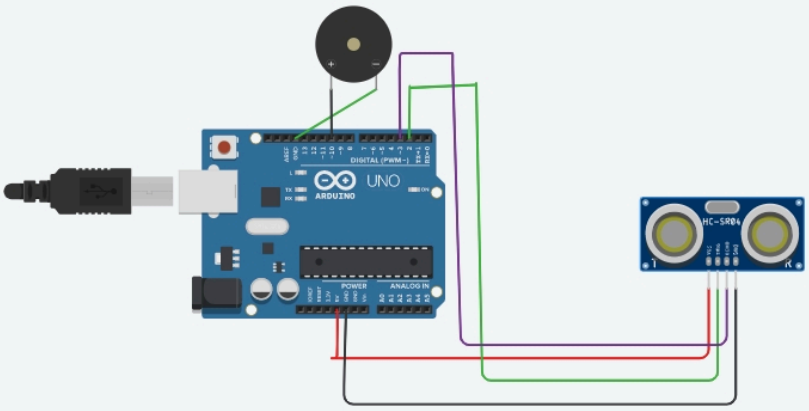
Neat Densor-Hango

All changes saved

Code | Start Simulation | Send To

Ultrasonic Distance Sensor

Name 1



Text | 1 (Arduino Uno R3)

```
int buzzer_pin=10;
int time;
int distance;
void setup(){
  Serial.begin(9600);
  pinMode(trigger_pin,OUTPUT);
  pinMode(echo_pin,INPUT);
  pinMode(buzzer_pin,OUTPUT);
}
void loop()
{
  digitalWrite(trigger_pin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigger_pin,LOW);
  time=pulseIn(echo_pin,HIGH);
  distance=(time*0.034)/2;
  if(distance<=10){
    Serial.println("Door Open");
    Serial.print("Distance=");
    Serial.println(distance);
    digitalWrite(buzzer_pin,HIGH);
    delay(500);
  }
  else{
    Serial.println("Door Closed");
    Serial.print("Distance=");
    Serial.println(distance);
    digitalWrite(buzzer_pin,LOW);
    delay(500);
  }
```

Serial Monitor

12:27
14-09-2022