



```
int led = 13;
```

```
int sensor = 2;
```

```
int state = LOW;
```

```
int val = 0;
```

```
const int buzzer = 3;
```

```
const int buzz = 6;
```

```
float temp;
```

```
int tempPin = 0;
```

```
void setup() {
```

```
  pinMode(led, OUTPUT);
```

```
  pinMode(sensor, INPUT);
```

```
  pinMode (buzzer, OUTPUT);
```

```
  pinMode (buzz, OUTPUT);
```

```
  Serial.begin(9600); }
```

```

void loop(){
  temp = analogRead(tempPin);
  temp = temp * 0.48828125;
  Serial.print("TEMPERATURE = ");
  Serial.print(temp);
  Serial.print("*C");
  Serial.println();
  delay(1000);
  if(temp>=60)
  {
    digitalWrite(buzzer,HIGH);
    delay(3000);
    digitalWrite(buzzer,LOW);
    delay(1000);
  }

  val = digitalRead(sensor);
  if (val == HIGH) {
    digitalWrite(led, HIGH);
    digitalWrite(buzz,HIGH);
    delay(1000);
    digitalWrite(buzz,LOW);

    if (state == LOW) {
      Serial.println("Motion detected!");
      state = HIGH;
    }
  }
}

```

```
else {  
    digitalWrite(led, LOW);  
    delay(500);  
  
    if (state == HIGH){  
        Serial.println("Motion stopped!");  
        state = LOW;  
    }  
}  
}
```