

- 1
- 2
- 3
- 4
- 5
- 6
- 7
- 8
- 9
- 10
- 11
- 12
- 13
- 14
- 15
- 16
- 17
- 18
- 19
- 20
- 21
- 22
- ...
- Door Op
- Distance
- Door Op
- Distance
- Door Op
- Distance
- Door C
- Distance



Code

Start Simulation

Send To

Text

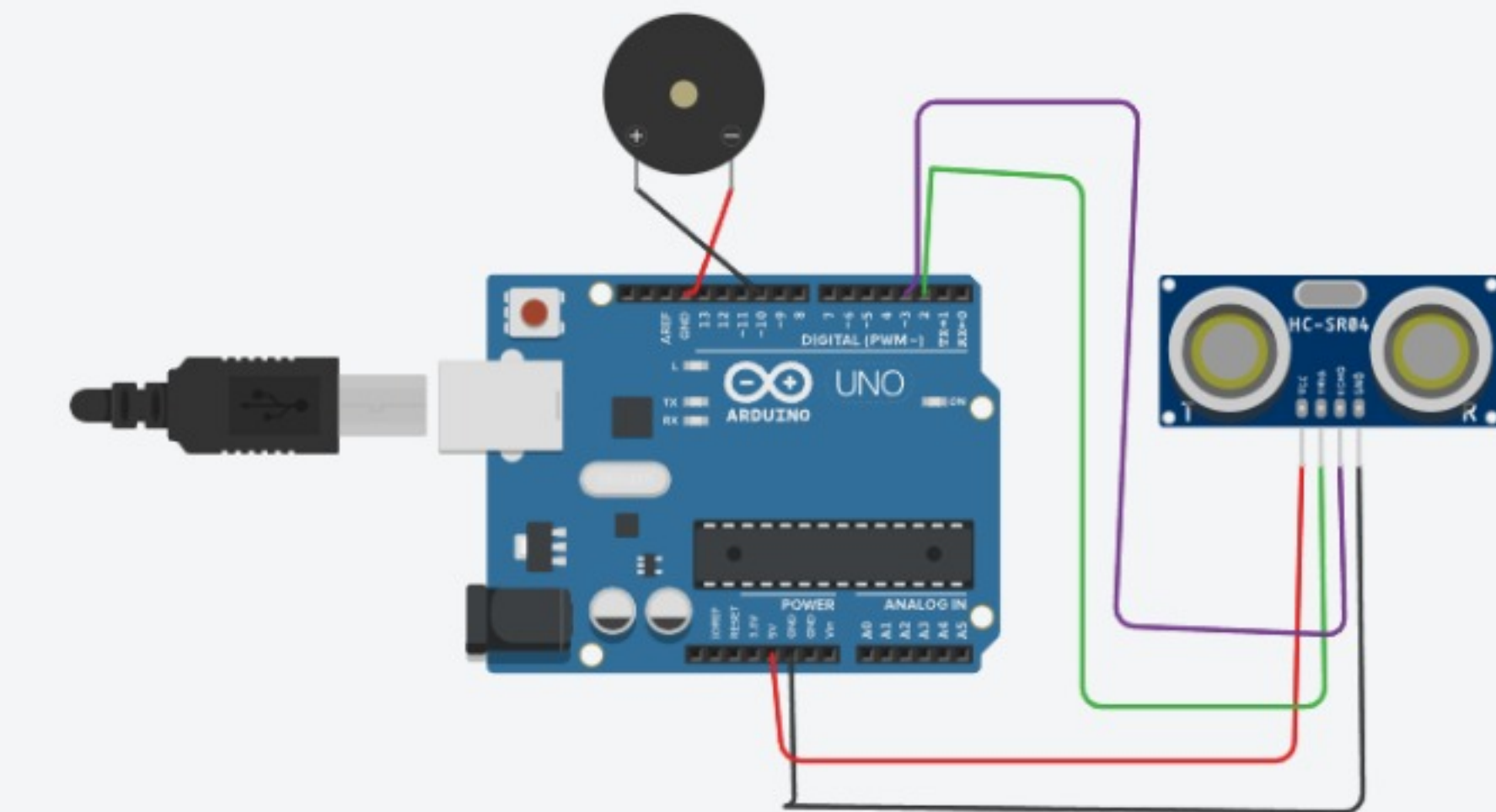


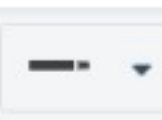
A

1 (Arduino Uno R3)

```
1 int trigger_pin = 2;
2 int echo_pin = 3;
3 int buzzer_pin = 10;
4 int time;
5 int distance;
6 void setup() {
7   Serial.begin(9600);
8   pinMode(trigger_pin, OUTPUT);
9   pinMode(echo_pin, INPUT);
10  pinMode(buzzer_pin, OUTPUT);
11 }
12 void loop()
13 {
14   digitalWrite(trigger_pin, HIGH);
15   delayMicroseconds(10);
16   digitalWrite(trigger_pin, LOW);
17   time = pulseIn(echo_pin, HIGH);
18   distance = (time * 0.034) / 2;
19   if(distance <= 10){
20     Serial.println("Door Open");
21     Serial.print("Distance= ");
22     Serial.println(distance);
23     digitalWrite(buzzer_pin, HIGH);
24     delay(500);
25   }
26   else{
27     Serial.println("Door Closed");
28     Serial.print("Distance= ");
29     Serial.println(distance);
30     digitalWrite(buzzer_pin, LOW);
31     delay(500);
32   }
33 }
```

Serial Monitor





Simulator time: 00:00:04

Code

Stop Simulation

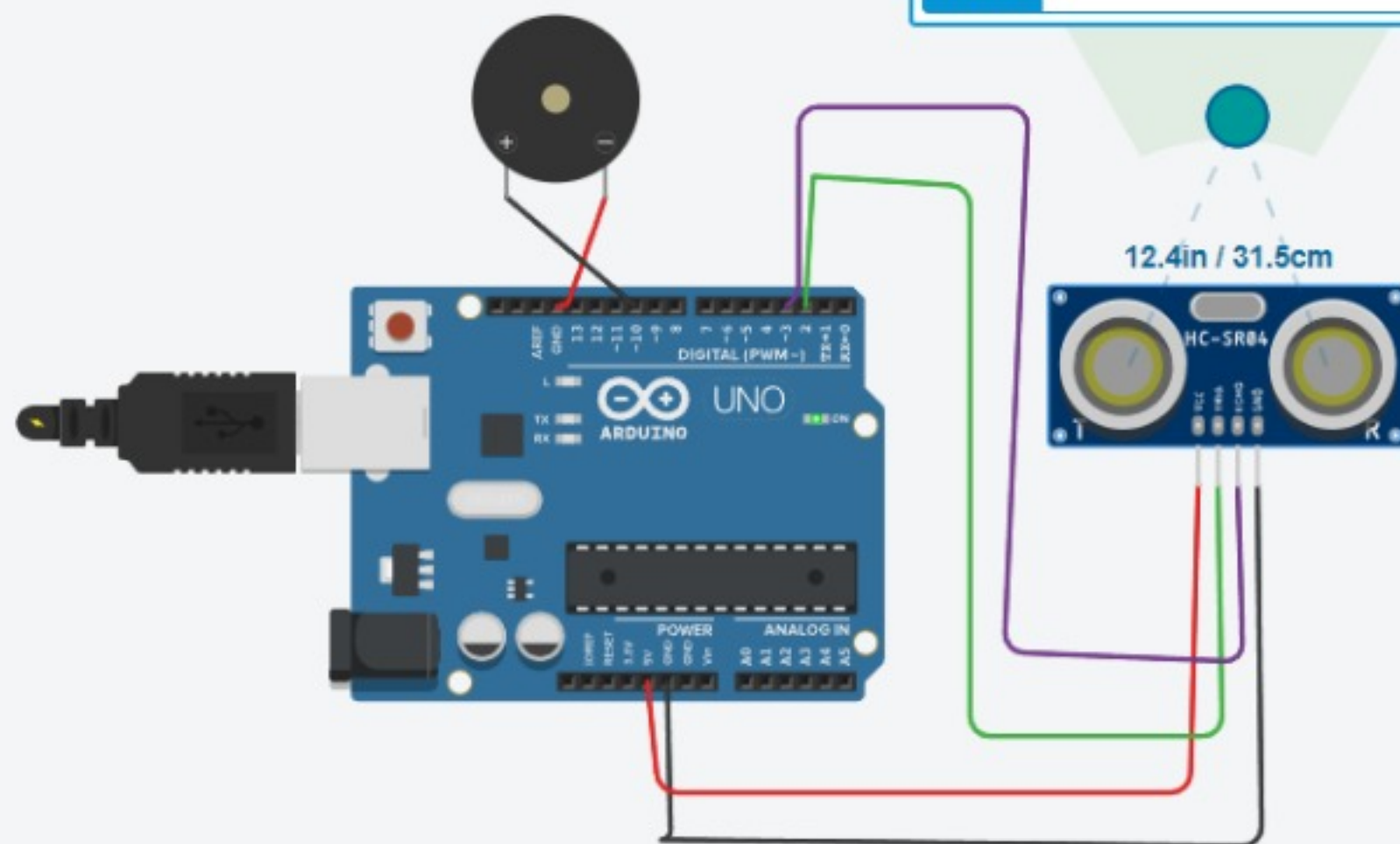
Send To



1 (Arduino Uno R3)

Ultrasonic Distance Sensor

Name 1



```
1 int trigger_pin = 2;
2 int echo_pin = 3;
3 int buzzer_pin = 10;
4 int time;
5 int distance;
6 void setup() {
7   Serial.begin(9600);
8   pinMode(trigger_pin, OUTPUT);
9   pinMode(echo_pin, INPUT);
10  pinMode(buzzer_pin, OUTPUT);
11 }
12 void loop()
13 {
14   digitalWrite(trigger_pin, HIGH);
15   delayMicroseconds(10);
16   digitalWrite(trigger_pin, LOW);
17   time = pulseIn(echo_pin, HIGH);
18   distance = (time * 0.034) / 2;
19   if(distance <= 10){
20     Serial.println("Door Open");
21     Serial.print("Distance= ");
22     Serial.println(distance);
23   }
24 }
```

Serial Monitor

```
Door Open
Distance= 6
Door Open
Distance= 6
Door Open
Distance= 6
Door Closed
Distance= 332
```

Send

Clear

