

PYTHON SCRIPT

Team ID	PNT2022TMID37762
Project Title	Smart Waste Management System In Metropolitan Cities

PYTHON CODE:

```
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys

organization = "bbzx4u"
devicType = "esp32_rasp"
deviceId = "123456789"
authMethod= "token"
authToken= "pnZ4GfTK5m&)t@P(gV"
def myCommandCallback(cmd):
    global a
    print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
    print(control)
try:
    deviceOptions= {"org": organization, "type": devicType,"id": deviceId,"auth-method":authMethod,"authToken":authToken}
    deviceClient = ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()

#connect and send a datapoint "temp" with value integer value into the cloud as a
type of event for every 20 seconds
deviceClient.connect()

while True:

    distance= random.randint(10,70)
    loadcell= random.randint(5,15)
    data= {'dist':distance, 'load':loadcell}
```

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If loadcell < 13 and loadcell > 15:
    load = "90 %"

Elif loadcell < 8 and loadcell > 12:
    load = "60 %"

elif loadcell < 4 and loadcell > 7:
    load = "40 %"
else:
    load = "0 %"

if distance < 15:
    dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'

elif distance < 40 and distance >16:
    dist = 'Risk warning:' 'dumpster is above 60%'

elif distance < 60 and distance > 41:
    dist = 'Risk warning:' '40 %'

else:
    dist = 'Risk warning:' '17 %'

If load == "90 %" or distance == "90 %":
    warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)'

Elif load == "60 %" or distance == "60 %":
    warn = 'alert :' 'dumpster is above 60%'

else :
    warn = 'alert :' 'No need to collect right now '

def myOnPublishCallback(lat=12.678991,long=87.177731):
    print("Chennai, Porur")
    print("published distance = %s " %distance, "loadcell:%s " %loadcell, "lon = %s
" %long,"lat = %s" %lat)
    print(load)
    print(distance)
    print(warn)

time.sleep(20)

```

```
success=deviceClient.publishEvent ("IoTSensor","json",warn,qos=0,on_publish=
myOnPublishCallback)
```

```
if not success:
    print("not connected to ibmiot")
time.sleep(40)
```

```
deviceClient.commandCallback=myCommandCallback
```

```
#disconnect the device
deviceClient.disconnect
```