

ASSIGNMENT-4

Assignment Date	06 NOVEMBER2022
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Project Name	Gas Leakage Monitoring and Alerting System

**Write code and connections in wokwi for ultrasonic sensor.
Whenever distance is less than 100 cms send "alert" to ibm cloud
and display in device recent events.**

CODE:

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT

void callback(char* subscribtopic, byte* payload, unsigned int payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "74w7lb" //IBM ORGANITION ID
#define DEVICE_TYPE "ESP32" //Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "021" //Device ID mentioned in ibm watson IOT Platform
#define TOKEN "Keerthana@532" //Token
String data3;
float dist;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of event perform and format
in which data to be send
char subscribtopic[] = "iot-2/cmd/test/fmt/String"; // cmd REPRESENT command type AND
COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id

//-----
WiFiClient wifiClient; // creating the instance for wificlient
```

PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

```
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED, OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}
void loop()// Recursive Function
{

  digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}
/* .....retrieving to Cloud..... */

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
   creating the String in in form JSon to update the data to ibm cloud
  */
  String object;
  if (dist <100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
```

```

}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\": ";
payload += dist;
payload += ", \"object\": ";
payload += object;
payload += "}";

Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish
    ok in Serial monitor or else it will print publish failed
} else {
    Serial.println("Publish failed");
}

}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function definition for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
    while (WiFi.status() != WL_CONNECTED) {

```

```

    delay(500);
    Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }

    // Serial.println("data: "+ data3);
    // if(data3=="Near")
    // {
    // Serial.println(data3);
    // digitalWrite(LED,HIGH);

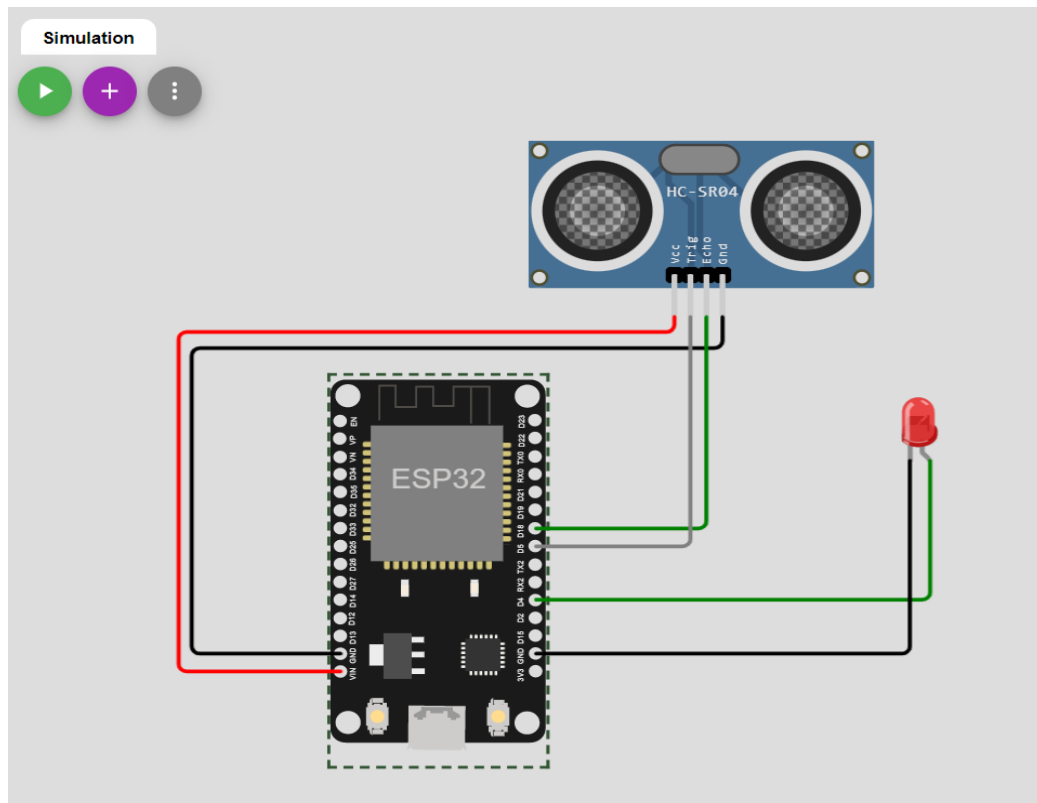
    // }

    // else
    // {
    // Serial.println(data3);
    // digitalWrite(LED,LOW);

    // }
    data3="";
}

```

CIRCUIT DIAGRAM:

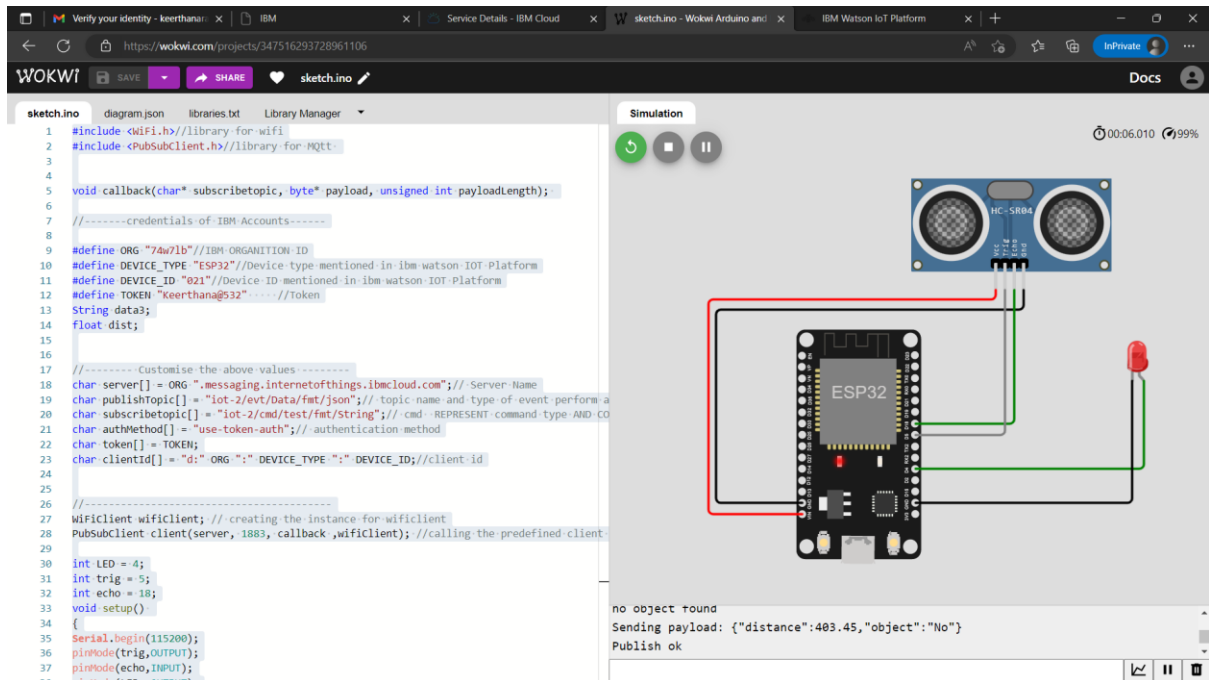


WOWKI OUTPUT:

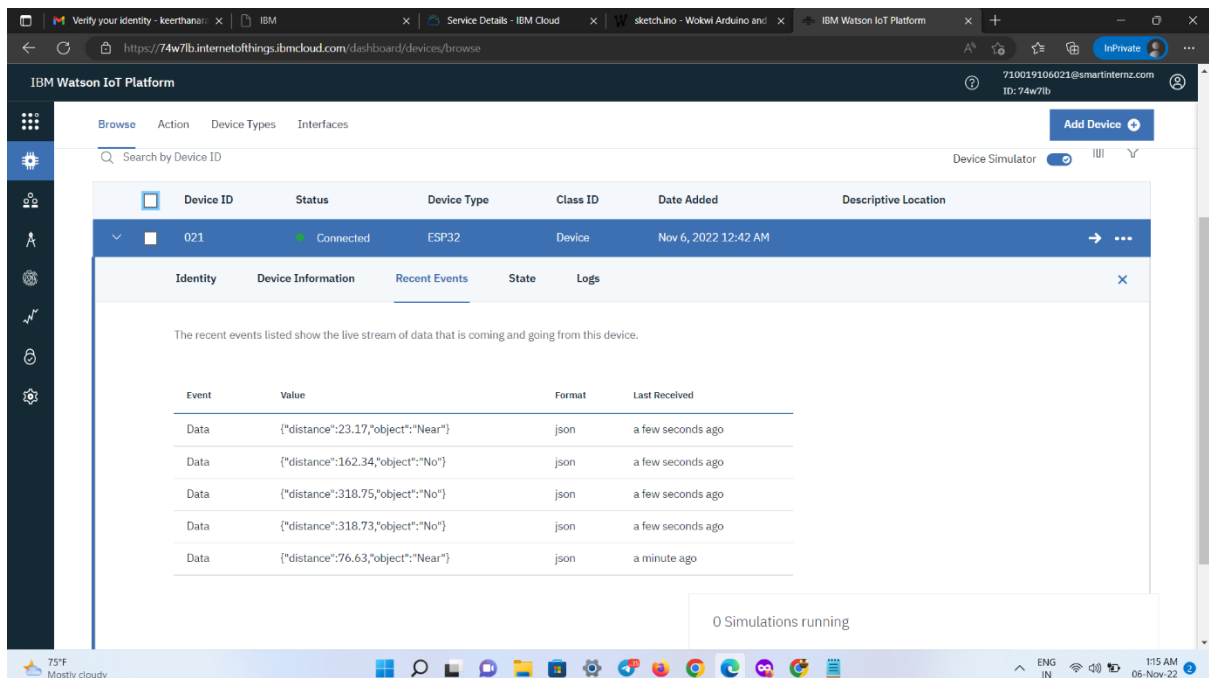
```
Distancein cm403.45
no object found
Sending payload: {"distance":403.45,"object":"No"}
Publish ok
Distancein cm403.47
no object found
Sending payload: {"distance":403.47,"object":"No"}
Publish ok
Distancein cm403.49
no object found
Sending payload: {"distance":403.49,"object":"No"}
Publish ok
Distancein cm403.47
no object found
Sending payload: {"distance":403.47,"object":"No"}
Publish ok
```

The output shows the sensor's readings and the ESP32's response. The sensor reports distances of 403.45 cm, 403.47 cm, 403.49 cm, and 403.47 cm, all with "no object found". The ESP32 sends a JSON payload for each reading and publishes it successfully.

WOWKI CIRCUIT:



IBM CLOUD OUTPUT:



WOWKI LINK:

<https://wokwi.com/projects/347516293728961106>