

Assignment -1

Assignment Date	19 September 2022
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Student Roll Number	820419104033
Maximum Marks	2 Marks

Question-1:

1.Smart Home using tinkercad.

Solution:

```
#include <Servo.h>

int output1Value = 0;

int sen1Value = 0;

int sen2Value = 0;

int const gas_sensor = A1;

int const LDR = A0;

int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)
{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Reads the echo pin, and returns the sound wave travel time in microseconds
    return pulseIn(echoPin, HIGH);
```

```

}

Servo servo_7;

void setup()
{
  Serial.begin(9600);          //initialize serial communication
  pinMode(A0, INPUT);          //LDR
  pinMode(A1, INPUT);          //gas sensor
  pinMode(13, OUTPUT);          //connected to relay
  servo_7.attach(7, 500, 2500); //servo motor

  pinMode(8, OUTPUT);          //signal to piezo buzzer
  pinMode(9, INPUT);           //signal to PIR
  pinMode(10, OUTPUT);          //signal to npn as switch
  pinMode(4, OUTPUT);           //Red LED
  pinMode(3, OUTPUT);           //Green LED
}

void loop()
{
  //-----light intensity control-----//
  //-----

  int val1 = analogRead(LDR);
  if (val1 > 500)
  {
    digitalWrite(13, LOW);
    Serial.print("Bulb ON = ");
    Serial.print(val1);
  }
  else
  {

```

```

digitalWrite(13, HIGH);

Serial.print("Bulb OFF = ");

Serial.print(val1);
}

//-----
//----- light & fan control -----//
//-----

sen2Value = digitalRead(9);
if (sen2Value == 0)
{
digitalWrite(10, LOW); //npn as switch OFF
digitalWrite(4, HIGH); // Red LED ON, indicating no motion
digitalWrite(3, LOW); //Green LED OFF, since no Motion detected
Serial.print("  || NO Motion Detected  ");
}

if (sen2Value == 1)
{
digitalWrite(10, HIGH); //npn as switch ON
delay(5000);
digitalWrite(4, LOW); // RED LED OFF
digitalWrite(3, HIGH); //GREEN LED ON , indicating motion detected
Serial.print("  || Motion Detected!  ");
}

//-----
// ----- Gas Sensor -----//
//-----

int val = analogRead(gas_sensor); //read sensor value
Serial.print(" || Gas Sensor Value = ");

Serial.print(val); //Printing in serial monitor

```

```

//val = map(val, 300, 750, 0, 100);

if (val > limit)
{
tone(8, 650);
}
delay(300);
noTone(8);

//-----
//----- servo motor -----//
//-----

sen1Value = 0.01723 * readUltrasonicDistance(6, 6);
if (sen1Value < 100)
{
servo_7.write(90);

Serial.print("  || Door Open! ; Distance = ");
Serial.print(sen1Value);
Serial.print("\n");

}
else
{
servo_7.write(0);

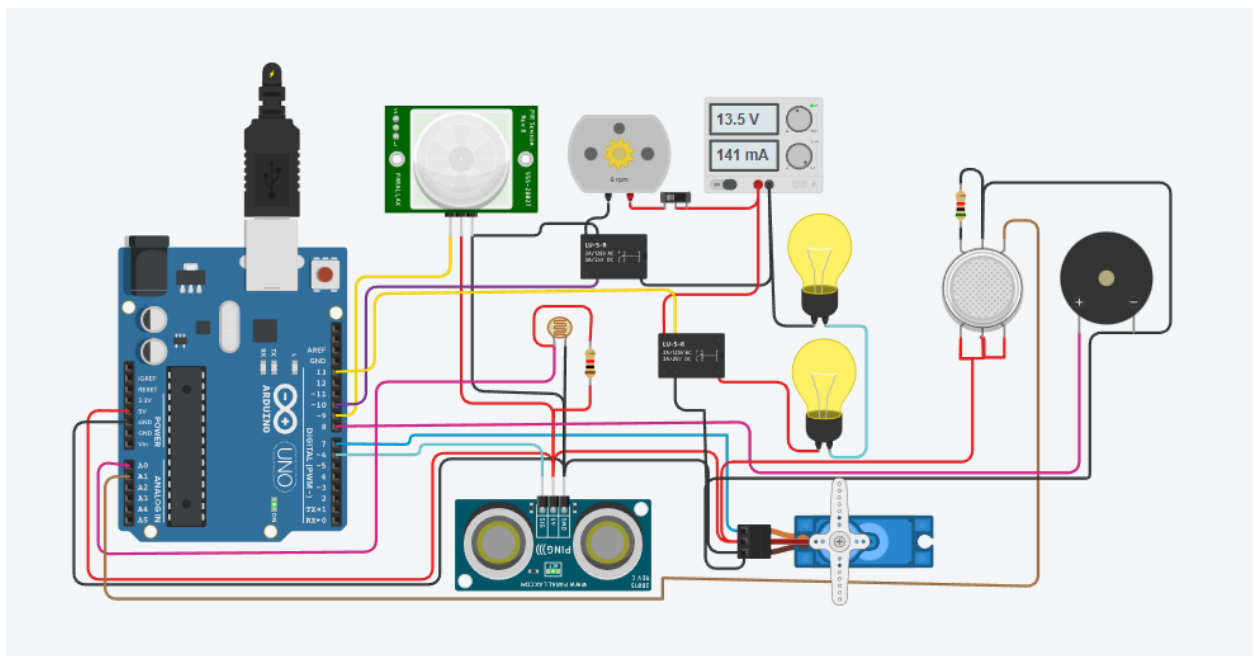
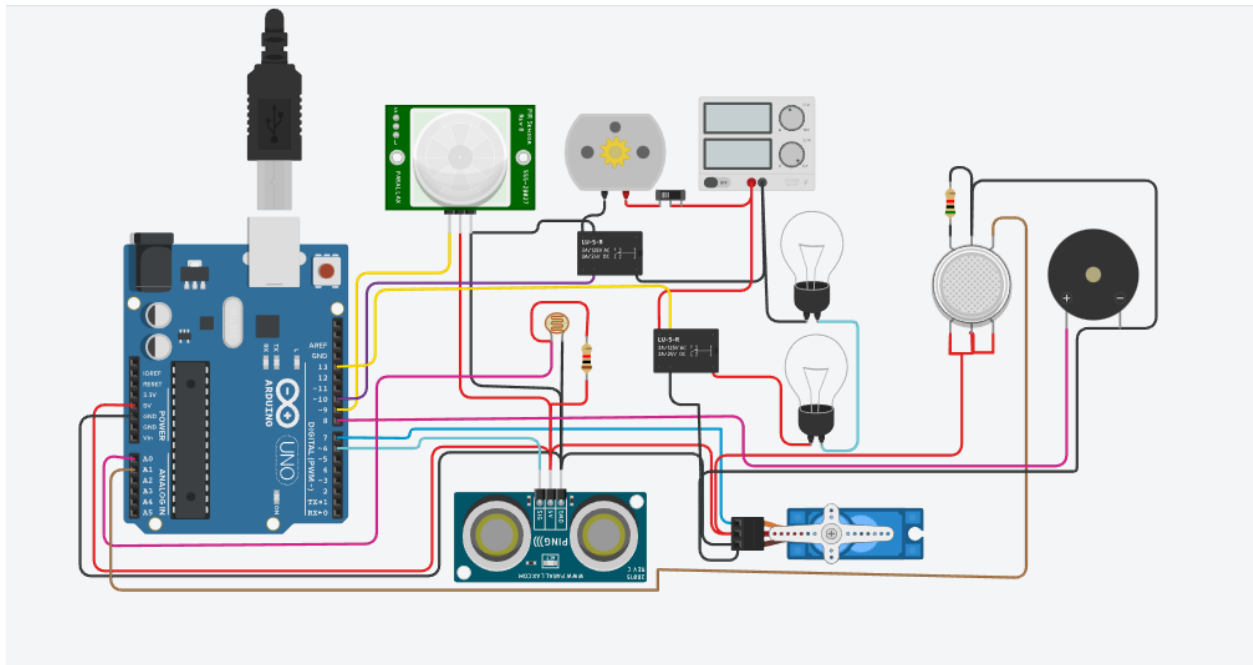
Serial.print("  || Door Closed! ; Distance = ");
Serial.print(sen1Value);
Serial.print("\n");
}

delay(10); // Delay a little bit to improve simulation performance
}

0

```

Output:

[illegible]