

**Assignment - 4**

Assignment Date	22 October 2022
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Student Roll Number	95071914041
Maximum Marks	2 Marks

**Question-1:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

**Solution:**

```
// Pins
const int TRIG_PIN = 7; const int
ECHO_PIN = 8;

// Anything over 400 cm (23200 us pulse) is "out of range" const
unsigned int MAX_DIST = 23200; void setup() {

  // The Trigger pin will tell the sensor to range find pinMode(TRIG_PIN,
    OUTPUT);
  digitalWrite(TRIG_PIN, LOW);

  //Set Echo pin as input to measure the duration of
  //pulses coming back from the distance sensor pinMode(ECHO_PIN,
    INPUT);

  // We'll use the serial monitor to view the sensor output Serial.begin(9600); }
void loop()

{

  unsigned    long    t1;
  unsigned    long    t2;
  unsigned          long
  pulse_width;    float  cm;
  float inches;

  // Hold the trigger pin high for at least 10 us
```

```

        digitalWrite(TRIG_PIN, HIGH); delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin while ( digitalRead(ECHO_PIN) ==
0 );

// Measure how long the echo pin was held high (pulse
width) // Note: the micros() counter will overflow after ~70
min t1 = micros();
while ( digitalRead(ECHO_PIN) == 1); t2
= micros(); pulse_width = t2 - t1;

// Calculate distance in centimeters and inches. The constants // are
found in the datasheet, and calculated from the assumed speed //of
sound in air at sea level (~340 m/s). cm = pulse_width / 58.0;
inches = pulse_width / 148.0;

// Print out results
if ( pulse_width > MAX_DIST ) { Serial.println("Out
of range"); }
else {
    Serial.println("*****");
    Serial.print("The Measured Distance in cm : ");
    Serial.println(cm);

    if(cm<100){
        // while(true){
        Serial.println("Alert!!");
        // } }

    Serial.print("*****"); }

// Wait at least 1000ms before next measurement delay(1000);
}

```

## Output:

1) If the distance is less than 100 cms , it alerts.

WOKWI

SAVE SHARE

Docs

hc-sr04.ino diagram.json Library Manager

```
1 // Pins
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (23200 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 23200;
7
8 void setup() {
9
10 // The Trigger pin will tell the sensor to range find
11 pinMode(TRIG_PIN, OUTPUT);
12 digitalWrite(TRIG_PIN, LOW);
13
14 //Set Echo pin as input to measure the duration of
15 //pulses coming back from the distance sensor
16 pinMode(ECHO_PIN, INPUT);
17
18 // We'll use the serial monitor to view the sensor output
19 Serial.begin(9600);
20 }
21
22 void loop() {
23
24 unsigned long t1;
25 unsigned long t2;
26 unsigned long pulse_width;
27 float cm;
28 float inches;
29
30 // Hold the trigger pin high for at least 10 us
```

Simulation

00:00.466 58%

Editing Ultrasonic Distance Sensor

Distance: 83cm

UNO

ARDUINO

The Measured Distance in cm : 84.14

Alert!!

Activate Windows

Go to Settings to activate Windows.

2) If the distance is more than 100 cms, it won't alert.

WOKWI

SAVE SHARE

Docs

hc-sr04.ino diagram.json Library Manager

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Simulation

00:00.599 62%

UNO

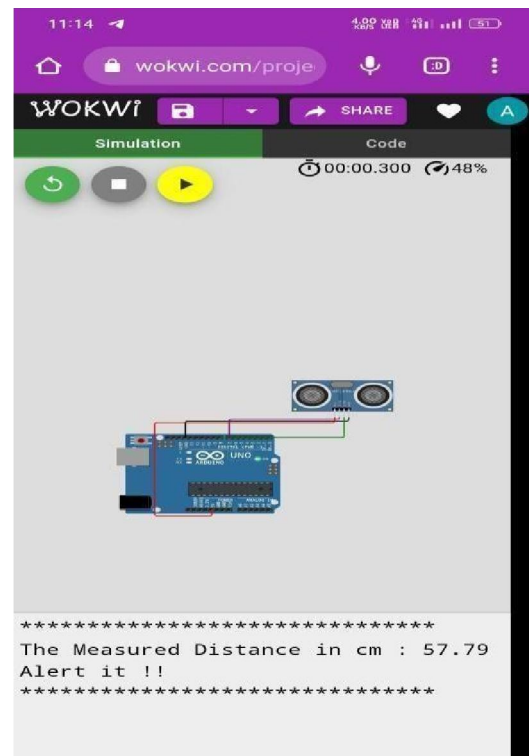
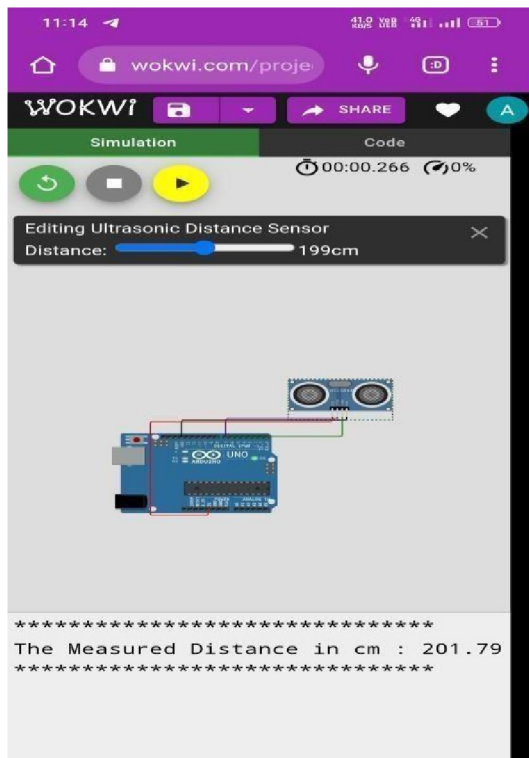
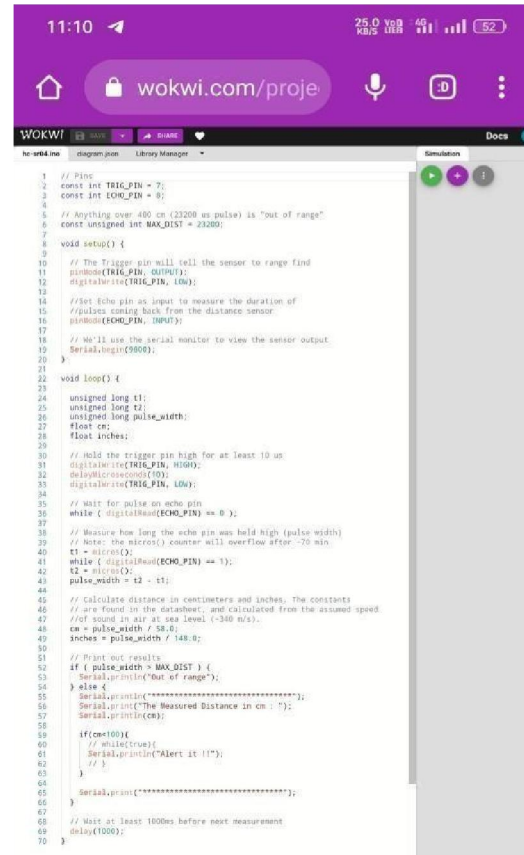
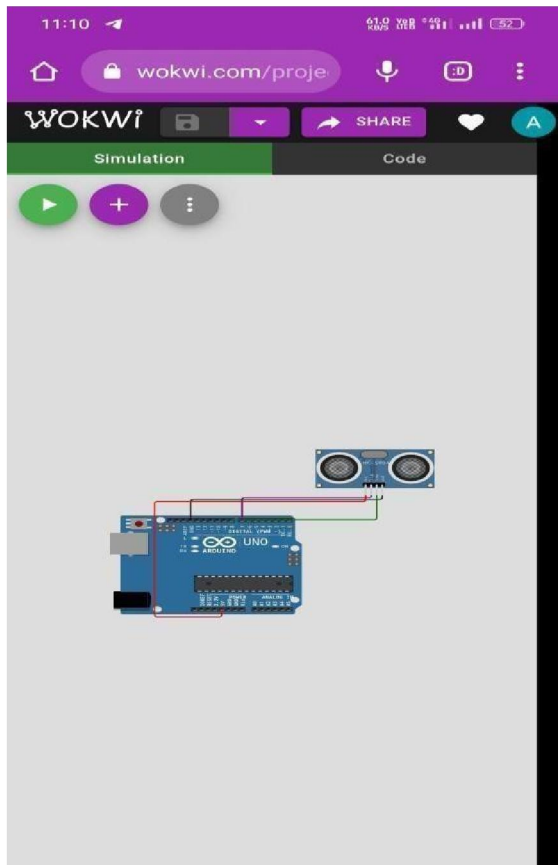
ARDUINO

The Measured Distance in cm : 227.10

Activate Windows

Go to Settings to activate Windows.

### 3) Simulation and code execution



## **Project link**

<https://wokwi.com/projects/346646086791725650>

