ASSIGNMENT – 4

Ultrasonic sensor simulation in Wokwi

Date	31October 2022
Team ID	PNT2022TMID07167
Project Name	Real-Time River Water Quality Monitoring and Control System.
Maximum Marks	2 Marks

QUESTIONS:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events

CODE:

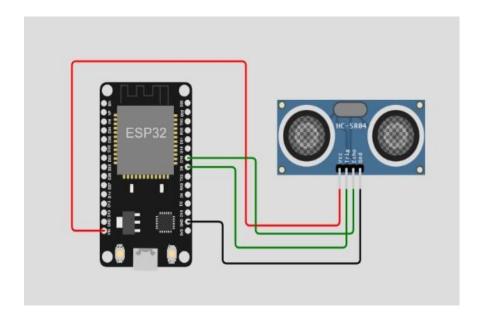
```
#include <WiFi.h> #include
<PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json"; char
subscribetopic[] = "iot-2/cmd/test/fmt/String"; char authMethod[]
= "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient); const
int trigPin = 5;
const int echoPin = 18;
#define SOUND SPEED 0.034
long duration; float distance;
void setup() {
```

```
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect(); mqttconnect();
} void loop() { digitalWrite(trigPin,
LOW); delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW); duration =
pulseIn(echoPin, HIGH); distance =
duration * SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance); if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000); if
(!client.loop()) {
mqttconnect();
} }
delay(1000);
void PublishData(float dist) { mqttconnect();
String payload = "{\"Distance\":"; payload
+= dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
if (!client.connected()) {
Serial.print("Reconnect
ing client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
}
initManagedDevice();
```

```
Serial.println();
} }
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while
(WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
} }
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic); for (int i =
0; i < payloadLength; i++) {
//Serial.print((char)payload[i]); data3 +=
(char)payload[i];
Serial.println("data: "+ data3); data3="";
```

.json CODE:

CIRCUIT DIAGRAM:



Wokwi simulation link:

https://wokwi.com/projects/346404308518961748

WOKWI OUTPUT:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

IBM CLOUD OUTPUT:

