## Team ID:PNT2022TMID53952

Roll No:95071914012

Name: Aruna A

1.Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud aand display in device recent events.

```
Solution:
```

```
//Pins const int
TRIG_PIN = 7; const int
ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range" const
unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT); digital
Write(TRIG_PIN, LOW);

//Set Echo pin as input to measure the duration of
```

```
//pulses coming back from the distance sensor
pinMode(ECHO PIN, INPUT);
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
void loop() { unsigned
long t1; unsigned long
t2; unsigned long
pulse width; float
cm; float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10); digitalWrite(TRIG_PIN,
LOW);
// Wait for pulse on echo pin while
(digitalRead( ECHO PIN )==0 );
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min t1=
micros (); while (digitalRead(ECHO PIN) == 1);
 t2= micros ();
  pulse width = t2-t1;
// Calculate distance in centimeters and inches. The constants
```

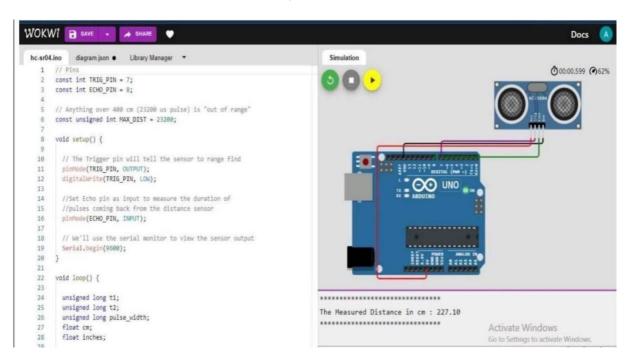
```
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s) cm=pulse Width
/ 58; inches = pulse_width/148.0; // Print out results if
(pulse_width >MAX _
DIST ){Serial.println("Out of range");
} else
Serial.print("The Measured Distance in cm: "); Serial.println(cm);
if( cm < 100 ){
   //while(true){
   Serial.println("Alert!!");
   //}
}
Serial.print("********************************);
}
//wait at least 1000ms before next measurement
Delay(1000);
}
```

# **Output:**

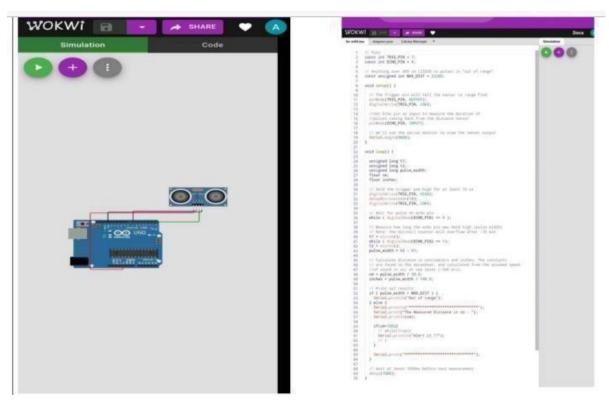
1.If the distance is less than 100 cms, it alerts.

```
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           const int TRIG_PIN = 7;
const int ECHO_PIN = 8;
           // Anything over 400 cm (23200 us pulse) is "out of range" const unsigned int MAX_DIST = 23200;
                                                                                                                                                                       // The Trigger pin will tell the sensor to range find
pinMode(TRIG_PIN, OUTPUT);
digitalWrite(TRIG_PIN, LOW);
                                                                                                                                     BERRY BESTAL (MAR -) CO
                                                                                                                                    UNO UNO
              //Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, IMPUT);
             // We'll use the serial monitor to view the sensor output Serial.begin (9600); \\
                                                                                                                                        Man and
            void loop() {
             unsigned long t1;
unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;
                                                                                                         The Measured Distance in cm : 84.14
                                                                                                         Alert!!
                                                                                                                                                                                                W 11 0
              // Hold the trigger pin high for at least 18 us
```

# 2.If the distance is more than 100 cms, it won't alert



### 3. Simulation and code execution







#### IBM cloud output:

