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1.Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send “Alert” to ibm cloud aand display in device recent events.

Solution:

```
//Pins const int
```

```
TRIG_PIN = 7 ; const int
```

```
ECHO_PIN = 8;
```

```
//Anything over 400 cm (23200 us pulse) is "out of range" const
```

```
unsigned int MAX_DIST = 23200;
```

```
void setup() {
```

```
// The Trigger pin will tell the sensor to range find
```

```
Pin Mode(TRIG_PIN, OUTPUT); digital
```

```
Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the duration of
```

```

//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT );

// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}

void loop() { unsigned
long t1; unsigned
long t2; unsigned
long pulse_width;
float cm; float inches;

// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10); digitalWrite(TRIG_PIN,
LOW);

// Wait for pulse on echo pin while
(digitalRead( ECHO_PIN )!=0 );

// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70 min t1=
micros (); while (digitalRead(ECHO_PIN) == 1);
t2= micros ();
pulse_width = t2-t1;

// Calculate distance in centimeters and inches. The constants

```

```

//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58 ; inches = pulse_width/148.0;

// Print out results if
(pulse_width >MAX _
DIST ){Serial.println("Out of range");
} else
{ Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
        //}
}

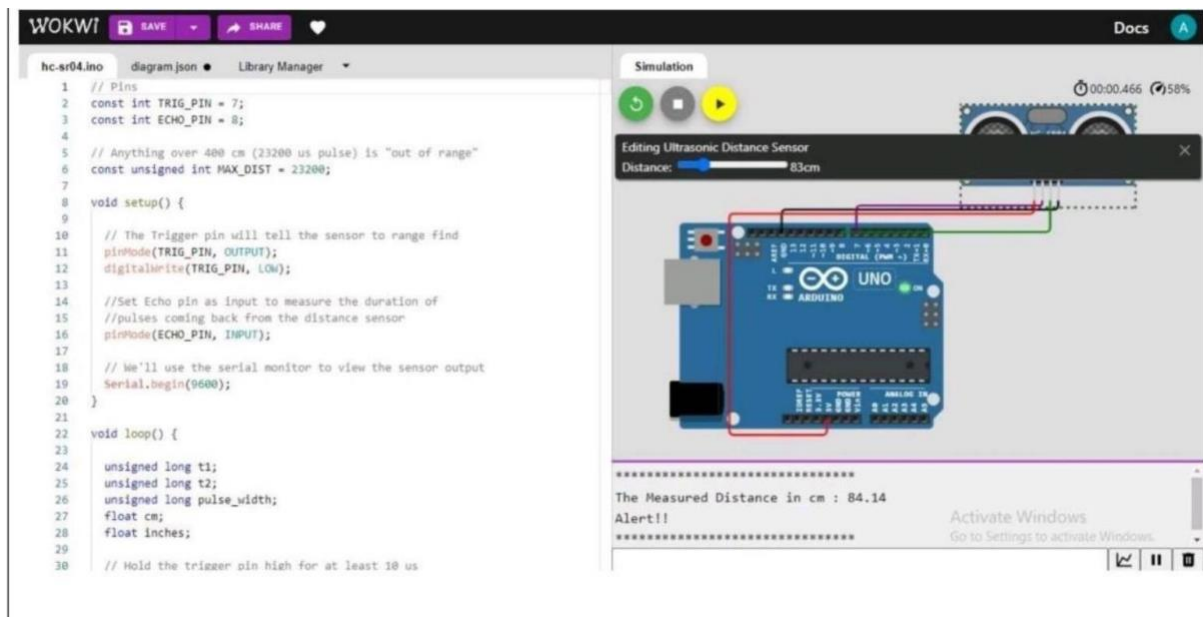
Serial.print("*****");
}

//wait at least 1000ms before next measurement
Delay(1000);
}

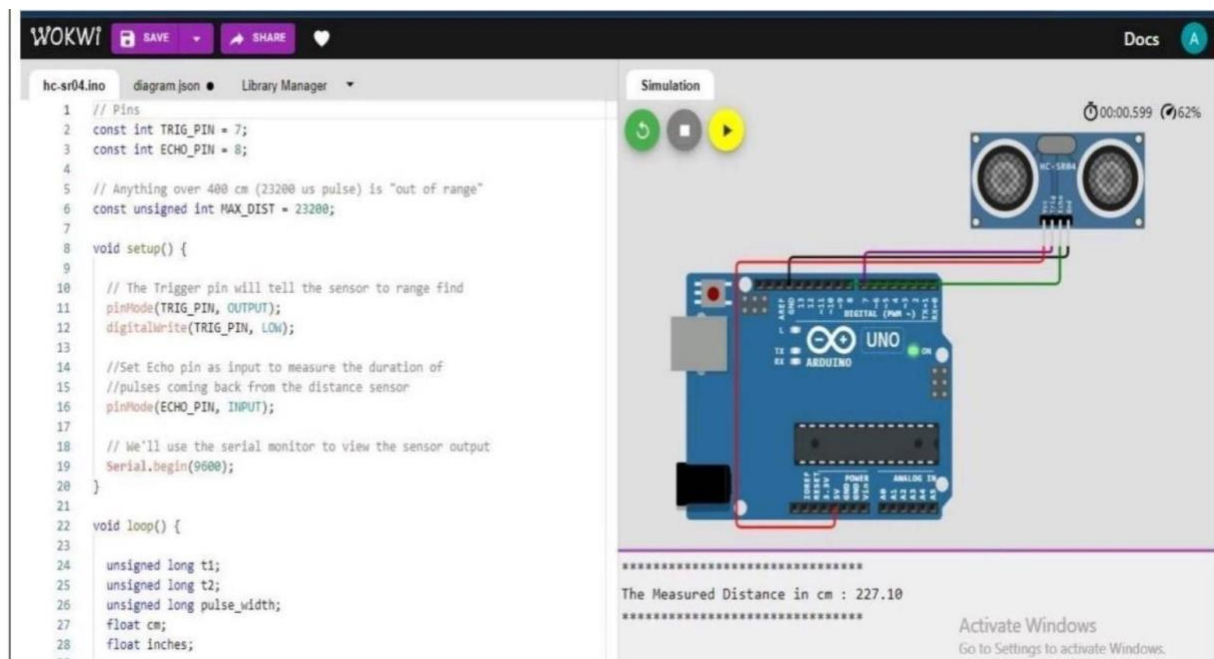
```

Output:

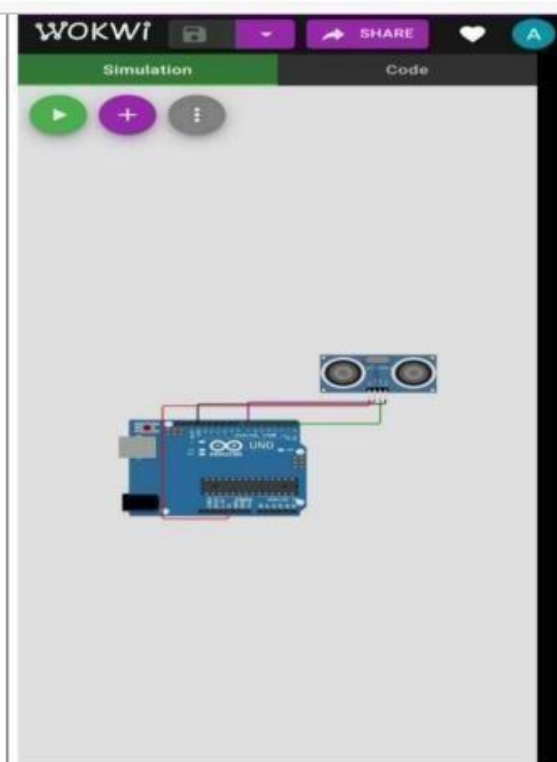
1.If the distance is less than 100 cms ,it alerts.



2.If the distance is more than 100 cms,it won't alert



3.Simulation and code execution



IBM cloud output:

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