SPRINT 2

Date	7 November 2022
Team ID	PNT2022TMID26000
Project Name	Smart Waste Management System for
	Metropolitan cities
	wietropolitaii cities

CODE FOR DETECTING BIN LEVEL AND DISPLAYING IT IN IBM CLOUD:

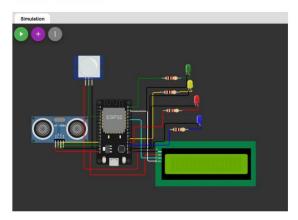
esp32-dht22.ino:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
                                                      // library for wifi
// library for MQTT
 //---- credentials of IBM Accounts
 watson iot platform
#define DEVICE_ID "252525" // Device ID mentioned in ibm watson iot
 #define TOKEN "QZqODYo6U*Q6b+IpuC"
                                               // Token
 //----customise above values -----
 //-----
 WiFiClient wifiClient; // creating instance for wificlient PubSubClient client(server, 1883, wifiClient);
 #define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
  Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
   //pir pin
pinMode(34, INPUT);
  //ledpins
pinMode(23, OUTPUT);
pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
   lcd.init();
   lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
   lcd.print("");
wifiConnect();
   mqttConnect();
float readcmCM()
  digitalWrite(TRIG_PIN, LOW);
 delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
void loop()
```

```
lcd.clear();
   publishData();
   delay(500);
if (!client.loop())
     {
  mqttConnect();
                                                                          // function call to
connect to IBM
/* -----retrieving to cloud------*/
void wifiConnect()
  Serial.print("Connecting to ");
Serial.print("Wifi");
Wifi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
  void mqttConnect()
     if (!client.connected())
                {
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
    /
                      {
   Serial.print(".");
   delay(500);
                    initManagedDevice();
        void initManagedDevice()
{
             if (client.subscribe(topic))
                {
    Serial.println("IBM subscribe to cmd OK");
               {
    Serial.println("subscribe to cmd FAILED");
}
        void publishData()
           float cm = readcmCM();
          if(digitalRead(34))
                                                                                //pir motion detection
          {
   Serial.println("Motion Detected");
   Serial.println("Lid Opened");
   digitalWrite(15, HIGH);
         if(digitalRead(34)== true)
         {
if(cm <= 60)
                                                                                             //Bin level
        detection
             digitalWrite(2, HIGH);
Serial.println("High Alert!!!,Trash bin is about to be full");
Serial.println("tid Closed");
lcd.print("Full! Don't use");
             delay(2000);
             lcd.clear();
digitalWrite(4, LOW);
digitalWrite(23, LOW);
           } else if(cm > 60 && cm < 120)
             digitalWrite(4, HIGH);
Serial.orintln("Warning!!,Trash is about to cross 50% of bin level");
digitalWrite(2, LOW);
digitalWrite(23, LOW);
            else if(cm > 120)
```

```
digitalWrite(23, HIGH);
Serial.println("Bin is available");
digitalWrite(2,LOW);
digitalWrite(4, LOW);
      }
delay(10000);
Serial.println("Lid Closed");
   Serial.println("Lid Closed");
}
else
{
Serial.println("No motion detected");
digitalWrite(2, LOW);
digitalWrite(15, LOW);
digitalWrite(4, LOW);
digitalWrite(23, LOW);
} else
          digitalWrite(15, LOW);
     }
     if(cm <= 60)
  f(digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
 }
else if(cm <= 120)
{</pre>
        digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cn ;
payload += " };
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.print(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))) {
          Serial.println("Publish OK");
         {
Serial.println("Publish FAILED");
         }
}
else
{
Serial.println();
}
              float inches = (cm / 2.54);
                                                                                                                                              //print on lcd
             lcd.setCursor(0,0);
lcd.print("Inches");
lcd.setCursor(4,0);
             lcd.setCursor(4,0);
lcd.setCursor(12,0);
lcd.print("cm");
lcd.setCursor(1,1);
lcd.print(inches, 1);
lcd.setCursor(11,1);
lcd.setCursor(11,1);
```

CIRCUIT DIAGRAM:



IBM WATSON IOT PLATFORM OUTPUT:

