# Assignment -4

# **ULTRASONIC SENSOR**

Assignment Date	29 October 2022
Student Name	ARTHI.V
Student Roll Number	412519106013
Maximum Marks	2 Marks

# **QUESTION:**

Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud

### **SOLUTION:**

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "x0cl0i"
#define deviceType = "ultrasonicsensor"
#define deviceId = "ultrasonic_sensor"
#define authMethod = "use-token-auth"
#define authToken = "yfZ@HoxcWNUv3ZePkK"
void setup()
{
Serial.begin(9600);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM()
{
digitalWrite(TRIG_PIN, LOW);
```

```
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
float distance = readDistanceCM();
if (distance <= 100)
{
Serial.println("ALERT!!! Object Detected");
}
else
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
}
delay(1000);
}
```

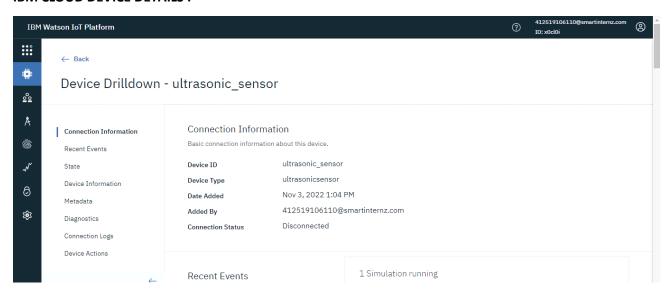
**SIMULATION OUTPUT:** 

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "xeclei"
#define deviceType = "ultrasonicsensor"
#define deviceId = "ultrasonicsensor"
#define deviceId = "ultrasonicsensor"
#define authNebthod = "use-token-auth"
#define authToken = "yfZ@HoxchNUv3ZePkK"
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float readDistanceCM()
  {
digitalWrite(TRIG_PIN, LOW);
digitalWrite(TRIG_PIN, LOW);
delapWicrosconds(2);
digitalWrite(TRIG_PIN, HIGH);
delapWicrosconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
                                                                                                                                                                                                                                                                                                 POMER ANALOG IN
{
    float distance = readDistanceCM();
    if (distance <= 100)
 {
Serial println("ALERT!!! Object Detected");
                                                                                                                                                                                                   Measured distance: 177.57
Measured distance: 177.67
 }
else
                                                                                                                                                                                                   ALERT!!! Object Detected
ALERT!!! Object Detected
{
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
                                                                                                                                                                                                   Measured distance: 241.72
Measured distance: 241.62
  }
delay(1000);
```

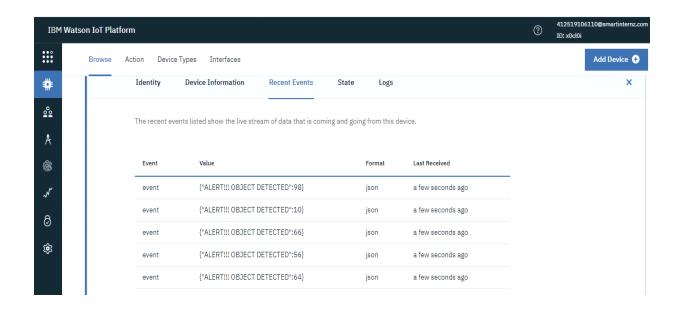
#### **WOKWI SHARE LINK:**

https://wokwi.com/projects/347291092185514580

### **IBM CLOUD DEVICE DETAILS:**



# **IBM CLOUD DEVICE RECENT EVENTS:**



# **LINE CHART OF IBM CLOUD DEVICE:**

