Assignment - 4

Assignment Date	28 October 2022
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Question-1:

Write code and connections in wok Wi for ultrasonic sensor .Whenever distance is less than 100 cms send "Alert" to IBM cloud and display in device recent events.

Solution:

```
// Pins
 const int TRIG_PIN = 7;
 const int ECHO_PIN = 8;
 // Anything over 400 cm (23200 us pulse) is "out of range"
 const unsigned int MAX_DIST = 23200;
 void setup() (
  // The Trigger pin will tell the sensor to range find
  pinMode(TRIG_PIN, OUTPUT);
  digita1Write(TRIG_PIN, LOW);
  //Set Echo pin as input to measure the duration of
  //pulses coming back from the distance sensor
  pinMode(ECHO_PIN, INPUT);
  // We'll use the serial monitor to view the sensor output
  Serial.begin(9600);
void loop() (
  unsigned long t1;
  unsigned long t2;
  unsigned long pulsepwidth;
  float cm;
  float inches;
  // Hold the trigger pin high for at least 10 us
```

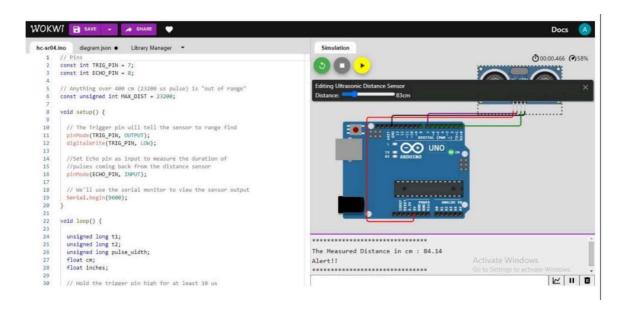
```
digita1Write(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digita1Read(ECHO_PIN) == 0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after -70 min
t1 = micros();
while (digita1Read(ECHO_PIN) == 1);
t2 = micros();
pulsepwidth = t2 - t1;
// Calculate distance in centimeters and inches. The constants
// are found in the datasheet, and calculated from the assumed speed
//of sound in air at sea level (-340 m/s).
cm = pulse\_width / 58.0;
inches = pulse_width / 148.0;
// Print out results
if (pulse_width > MAX_DIST) {
 Serial.println("Out of range");
} else {
 Serial.print("The Measured Distance in cm : ");
 Serial.print1n(cm);
 if(cm<100)(
  // while(true)(
  Serial.println("Alert!!");
  //}
 Serial.print("********************************);
// Wait at least 1000ms before next measurement
delay(1000);
```

}

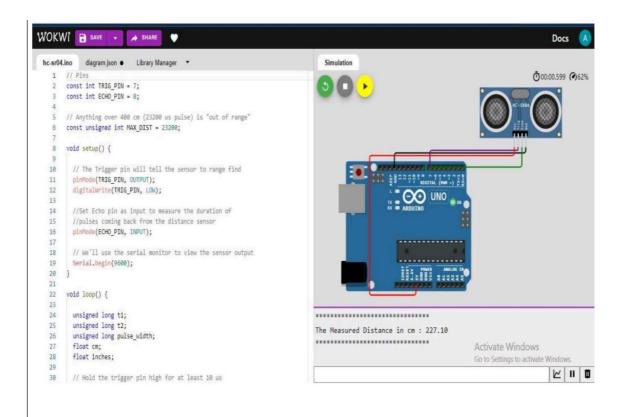
}

Output

1) If the distance is less than 100 cms, it alerts.



2) If the distance is more than 100 cms, it won't alert.



3) Simulation and code execution

